

Algorithms for Decision Support

NP-Completeness (1/3)

Turing Machine, **P**, and **NP**

Overview

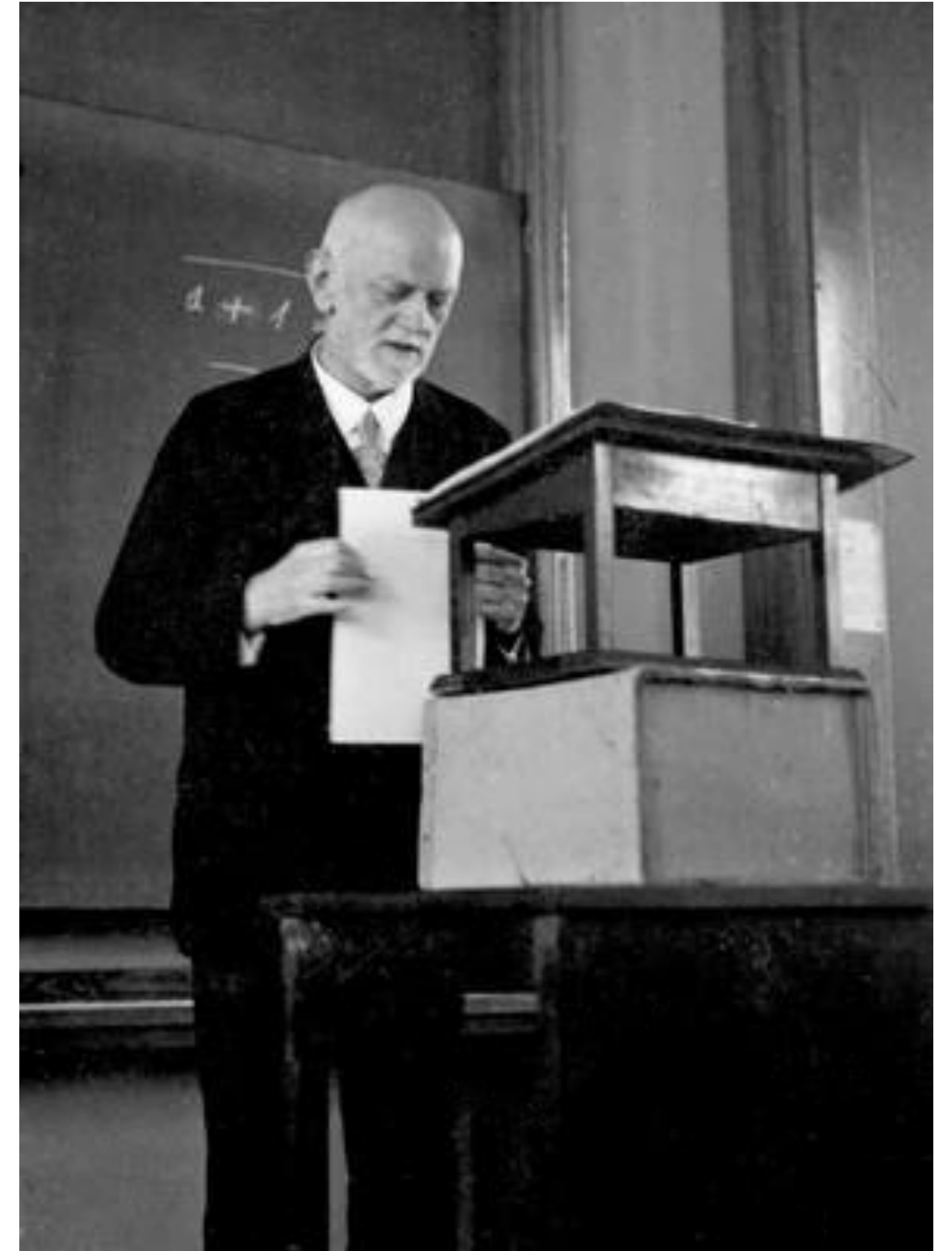
- Algorithms: Turing machine, Deterministic and non-deterministic
- Formal language framework: string and language
- Time complexity
 - Input size
 - Classes **P** and **NP**
 - Polynomial time verification

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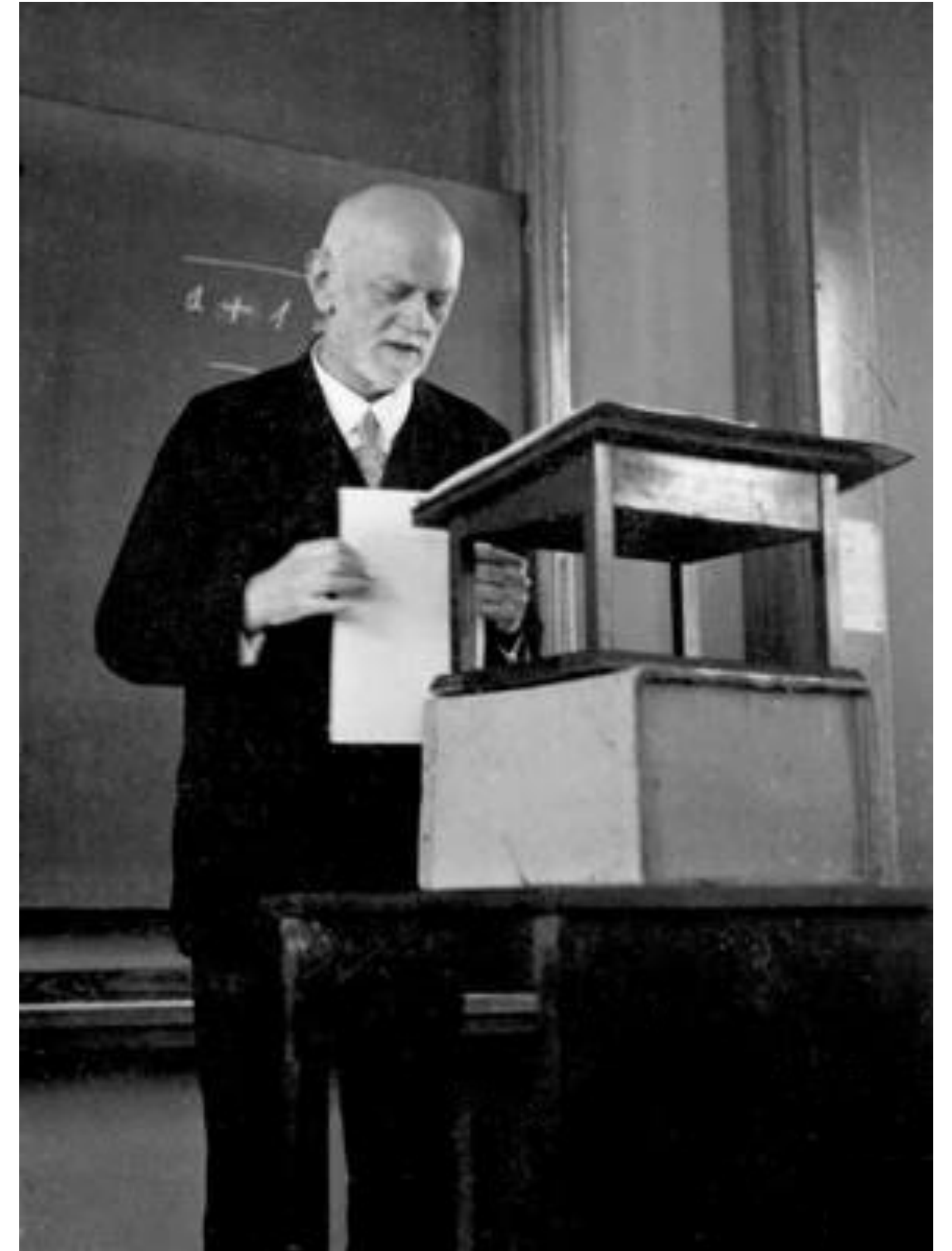
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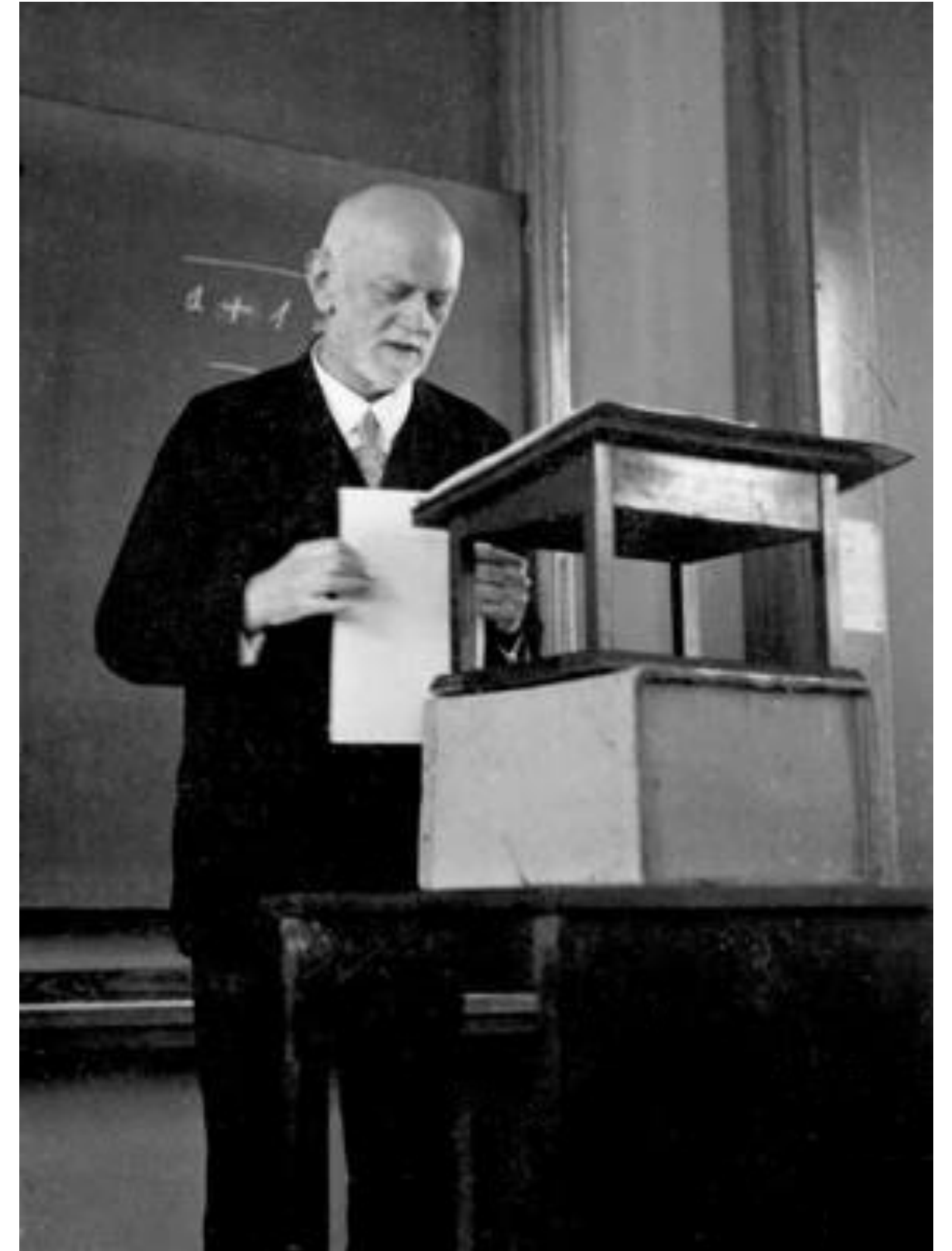
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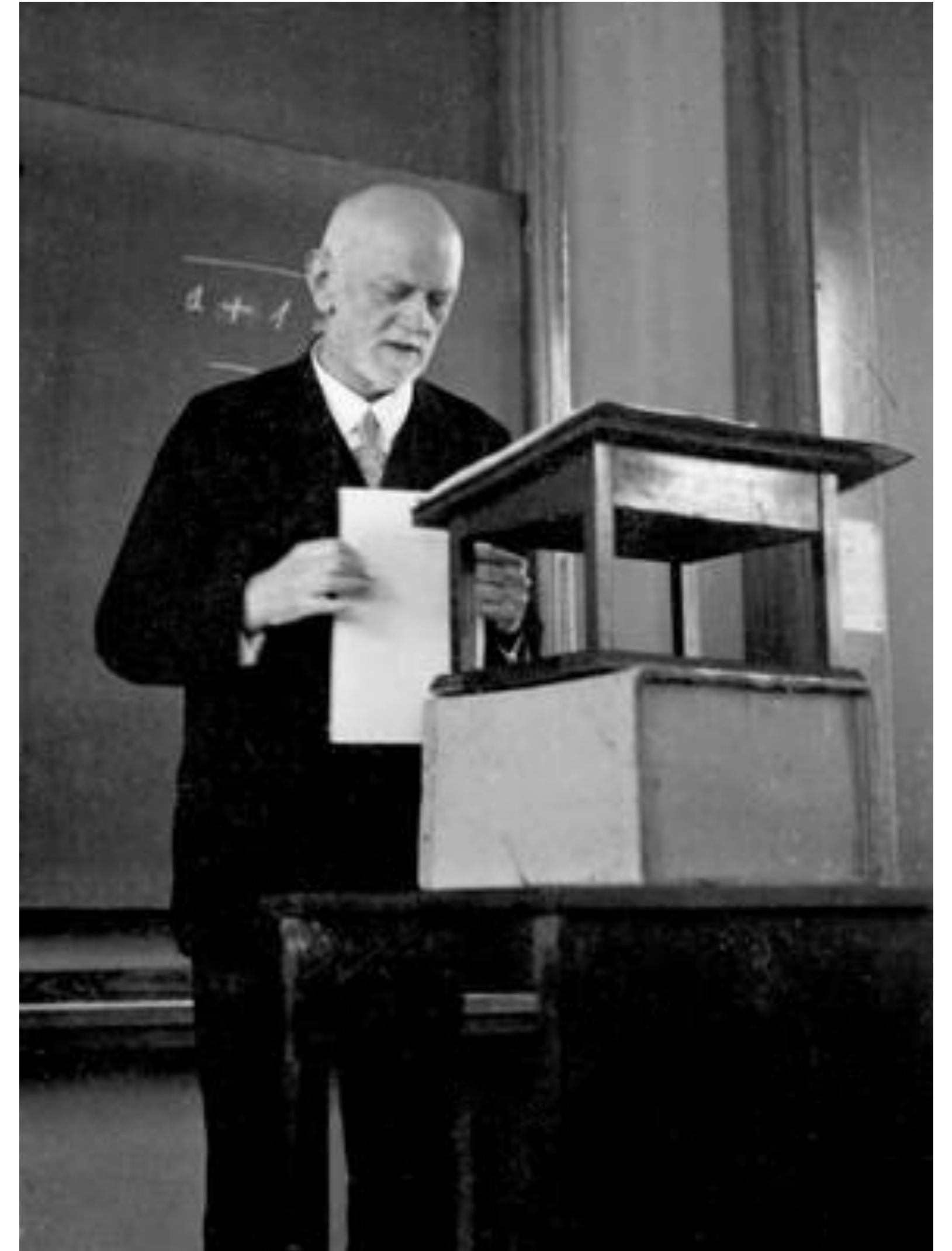
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Given a **multi-variable polynomial** F with integral coefficients. To devise a process according to which it can be determined in a finite number of operations whether F has integral roots.
 - $x^2 + 2xy + y^2 - 1 = 0$



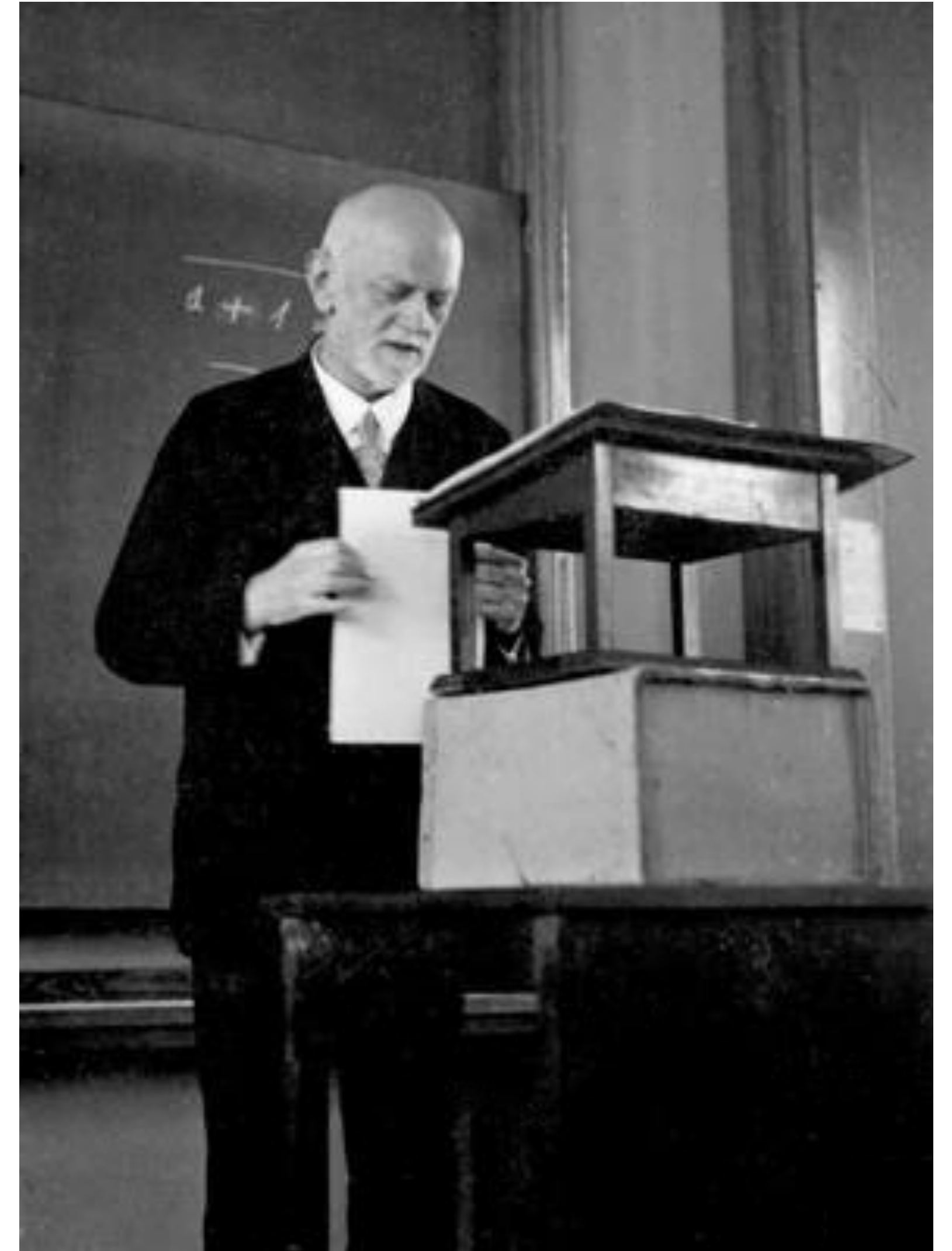
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 - $x^2 + y^2 - 3 = 0$



What is an algorithm/computer?

Turing Machine

- Proposed by Alan Turing in 1936



Alan Turing 1912~1954

Turing Machine

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- A model of a general purpose computer:
a Turing machine can do every thing that a real computer
can do



Alan Turing 1912~1954

Turing Machine

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 - An infinitely long tape/memory



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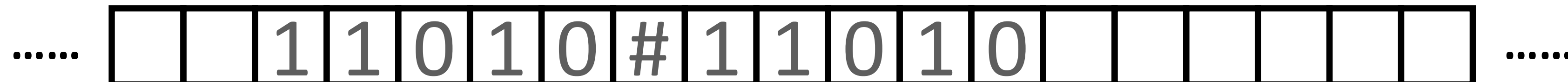


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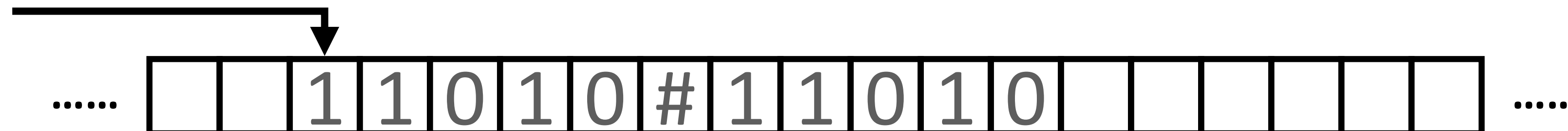


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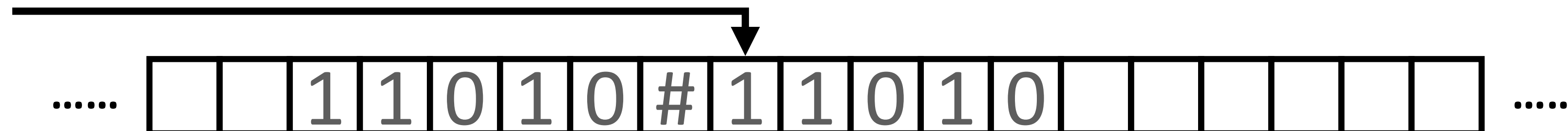


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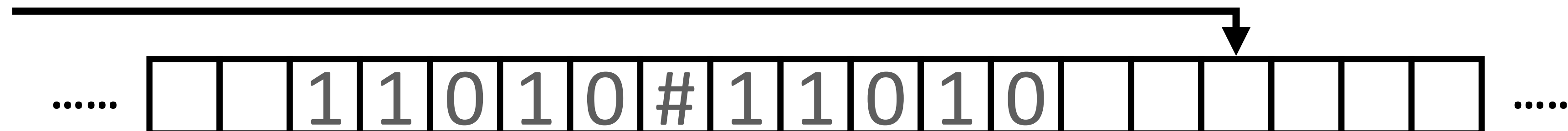


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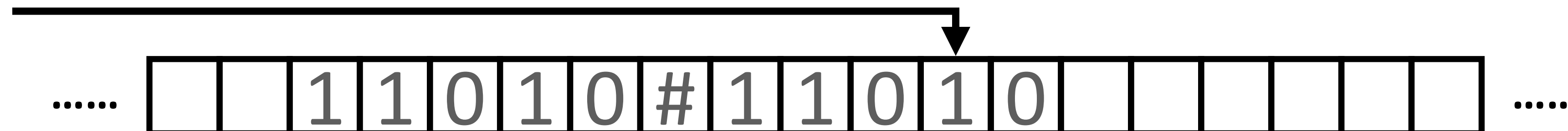


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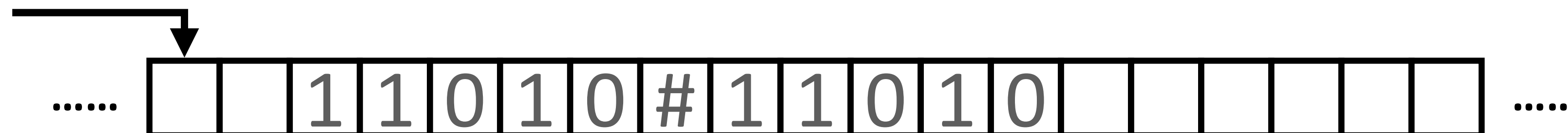


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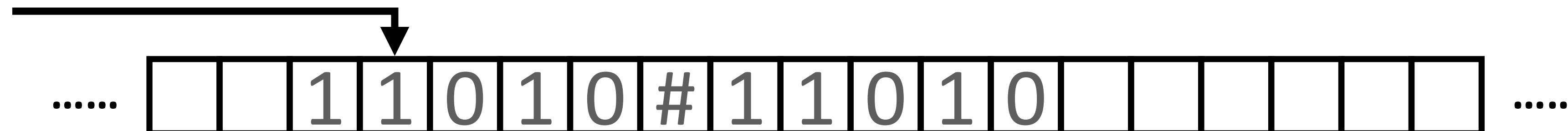


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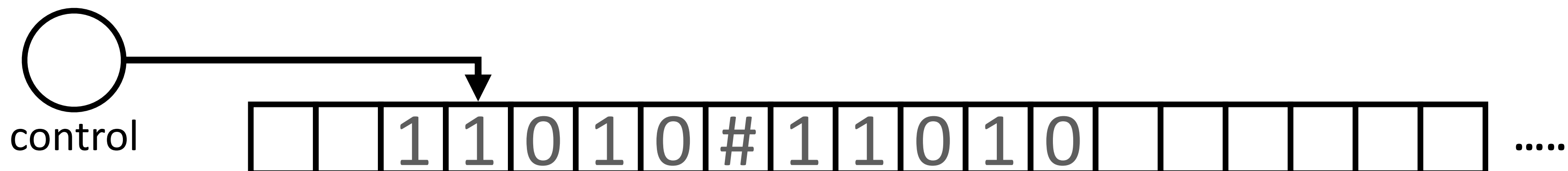


Turing Machine

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- An infinitely long tape/memory
 - Initially contains the (finite) input sequence and is blank everywhere else
- A tape head that can read and write symbols and move around on the tape
- control

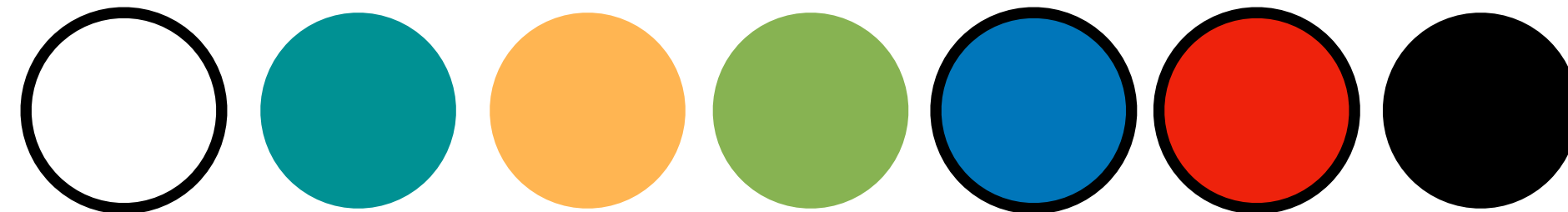


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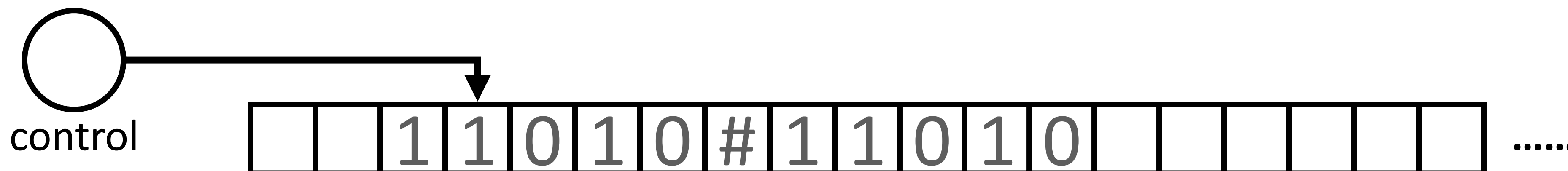


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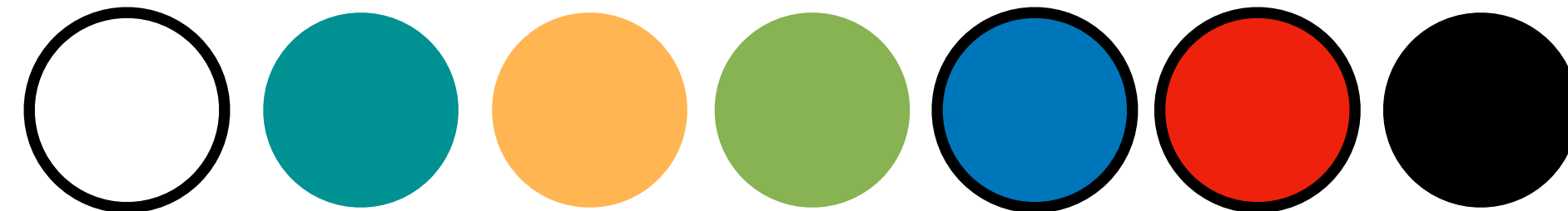


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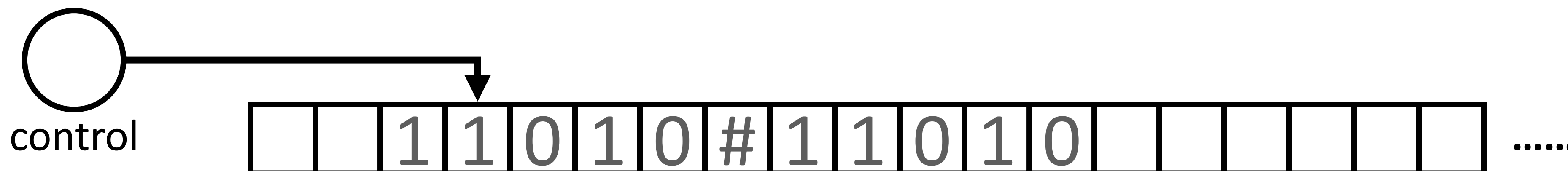


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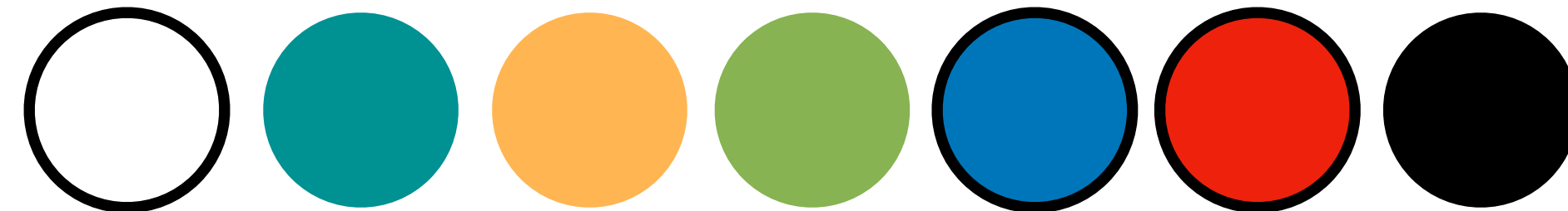


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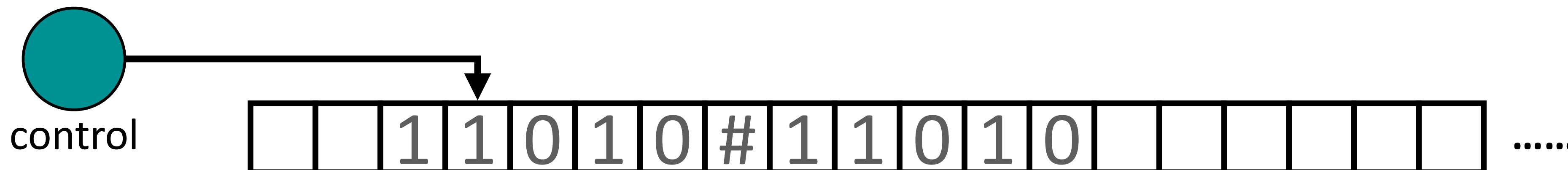


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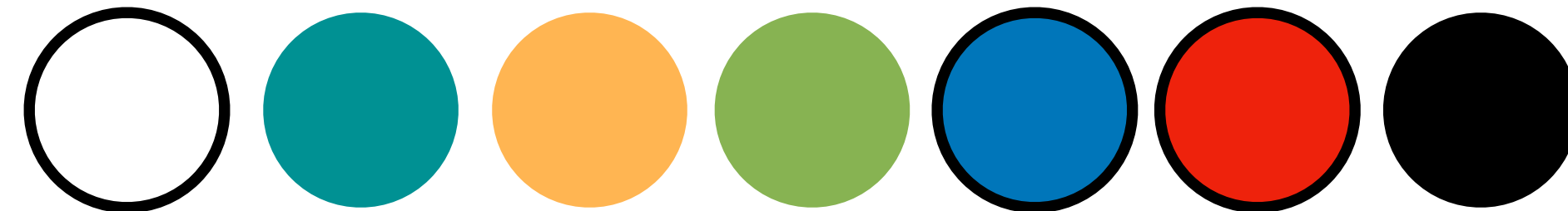


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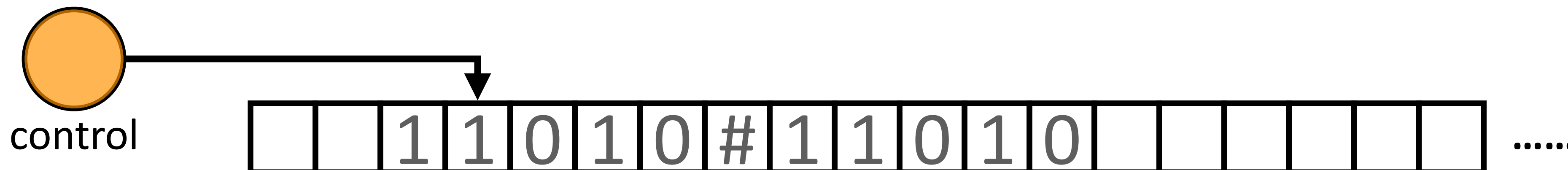


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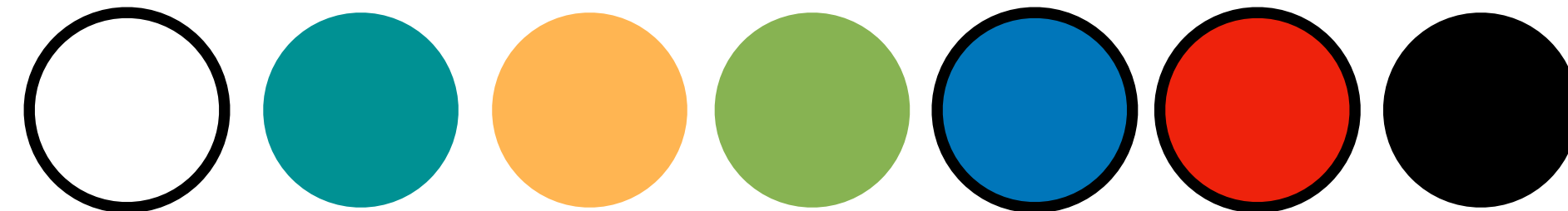


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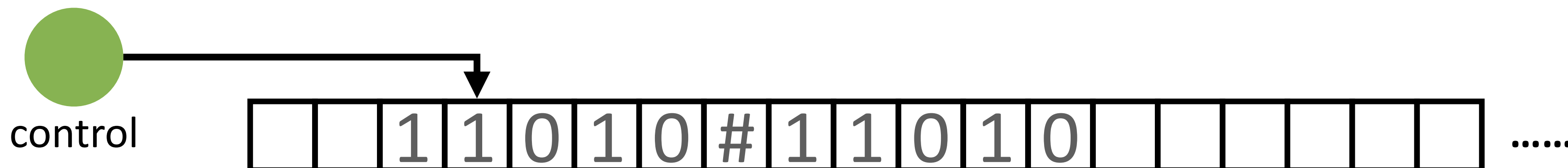


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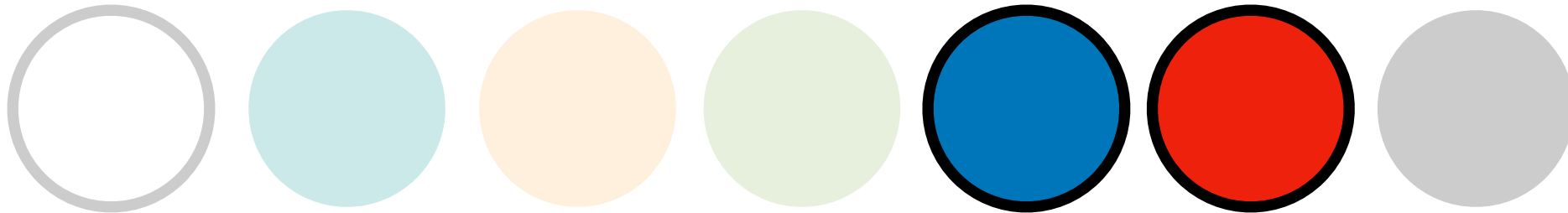
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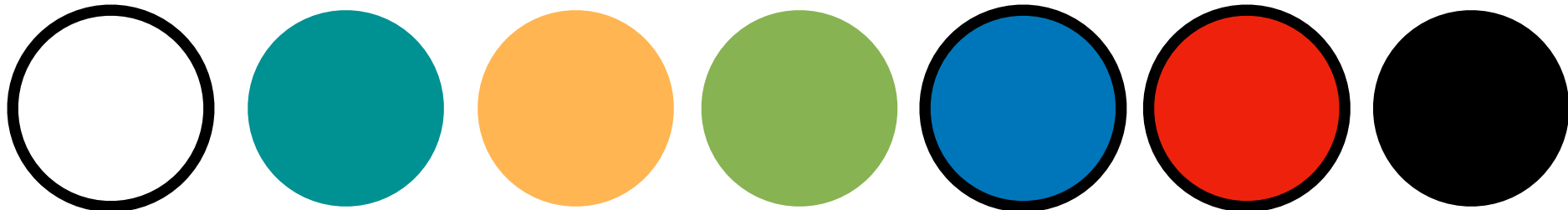
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 - Two special **halting** states: accept and reject



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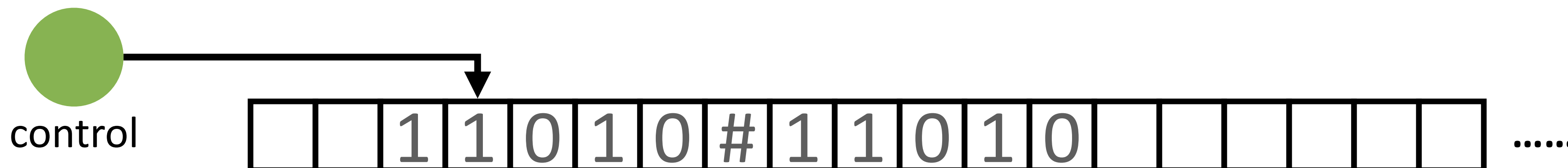


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Alan Turing 1912~1954



Turing Machine

- A Turing machine's *configuration*:



Turing Machine

- A Turing machine's *configuration*:
 - Its current state
 - what the read-write head reads



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 - what the read-write head reads
- By its current configuration, a Turing machine
 - decides the tape symbol to write on the tape,
 - switches to the next state, and
 - moves the tape head to its left or right



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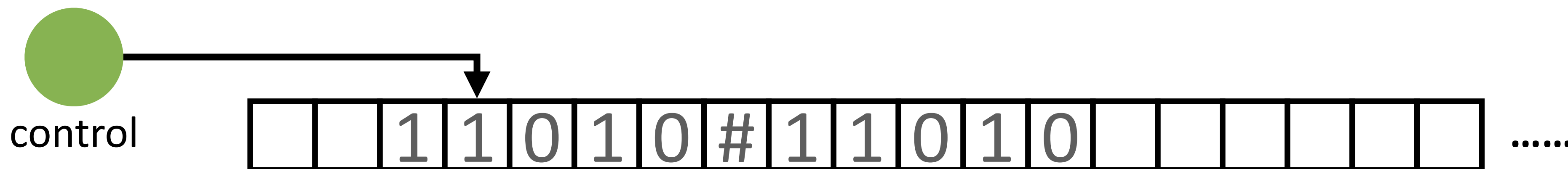
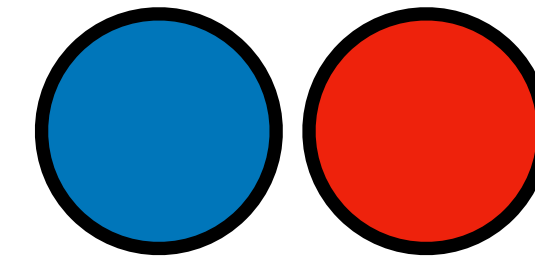
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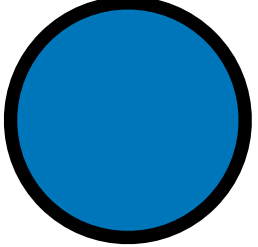
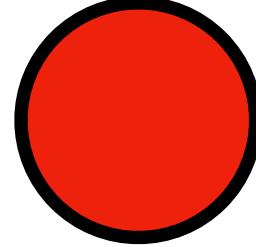


Turing Machine

- Output: *accept* or *reject* (both **halting** configurations)

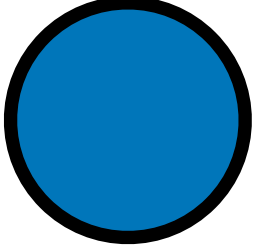
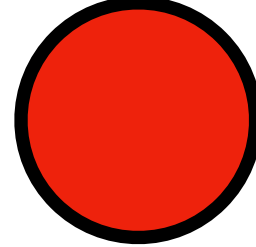


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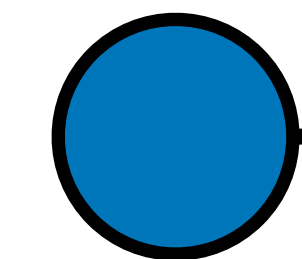
- Output: *accept* or *reject* (both **halting** configurations)  
- Obtained by entering designated *accepting* and *rejecting* states



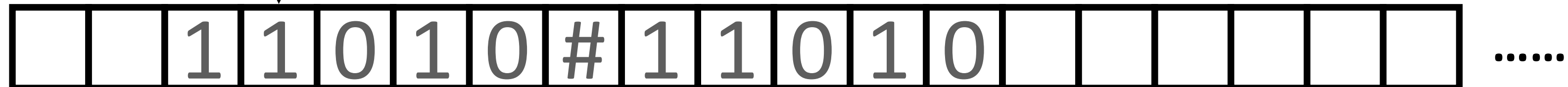
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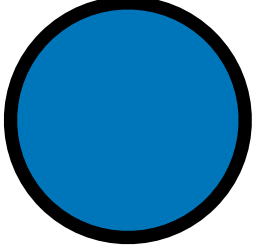
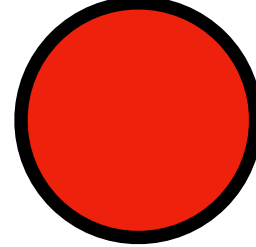
accept

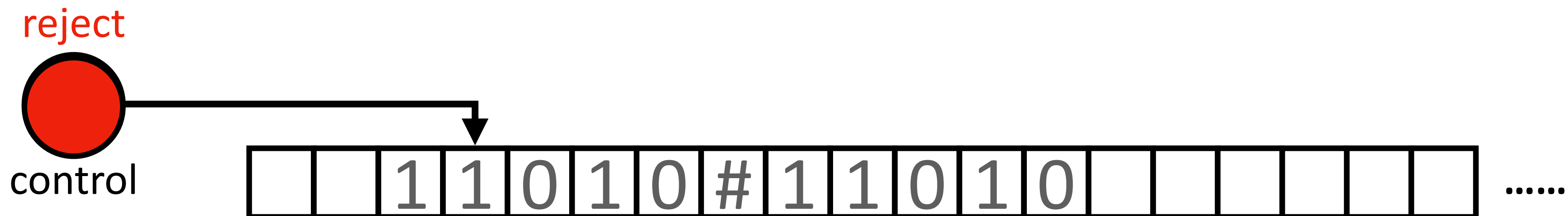


control

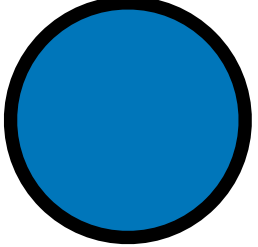
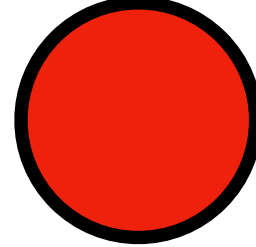


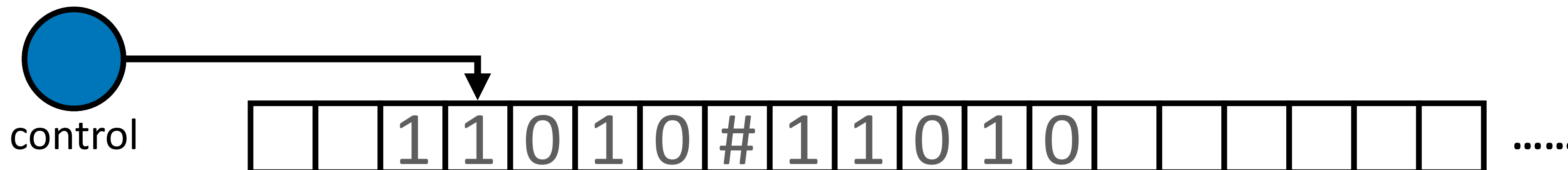
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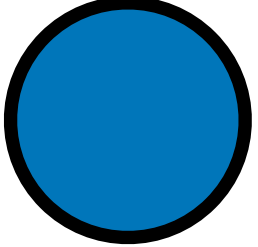
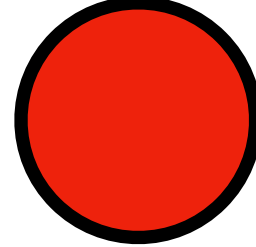


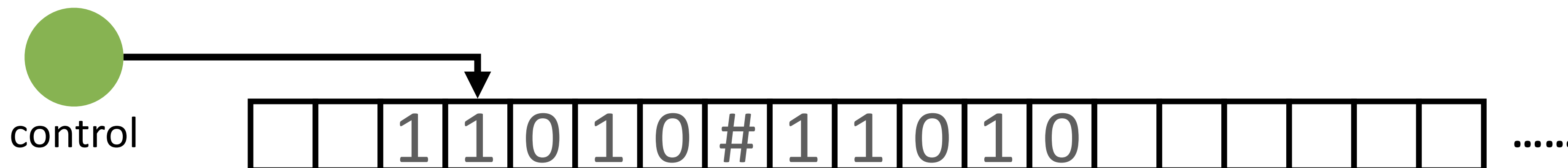
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- Output: *accept* or *reject* (both **halting** configurations)  
- Obtained by entering designated *accepting* and *rejecting* states
- When a Turing machine enters the *accept* state, it accepts the input immediately; when a Turing machine enters the *reject* state, it rejects the input immediately



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- If it does not enter the accept or reject states, TM will run forever (*loop*), and never halt



Turing Machine

- We can use Turing machines to solve problems!



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 - Does 1100010000000010 contains 2^k 0s for some integer k ?



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 - Is 15 a prime number?



Turing Machine

- We can use Turing machines to solve problems!
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 - Is 15 a prime number?
 - Is a graph G connected?



Turing Machine Example

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M = “On input string w :

1. Sweep left to right across the tape, crossing off every other 0.
2. If in stage 1 the tape contained a single 0, *accept*.
3. If in stage 1 the tape contained more than a single 0 and the number of 0s was odd, *reject*.
4. Return the head to the left-hand end of the tape.
5. Go to stage 1.”

Turing Machine Example

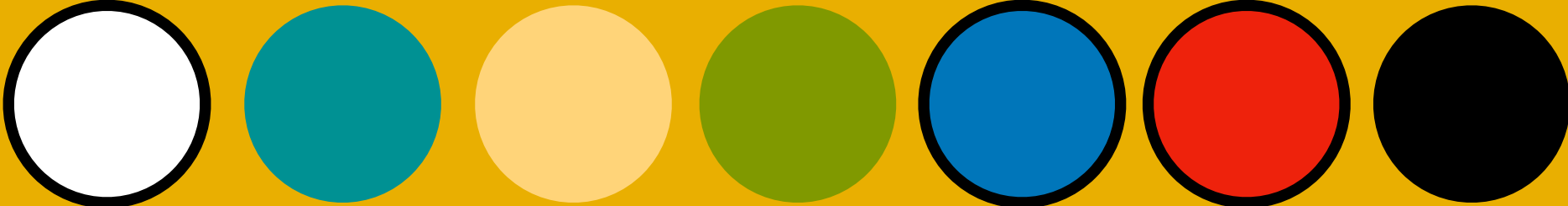
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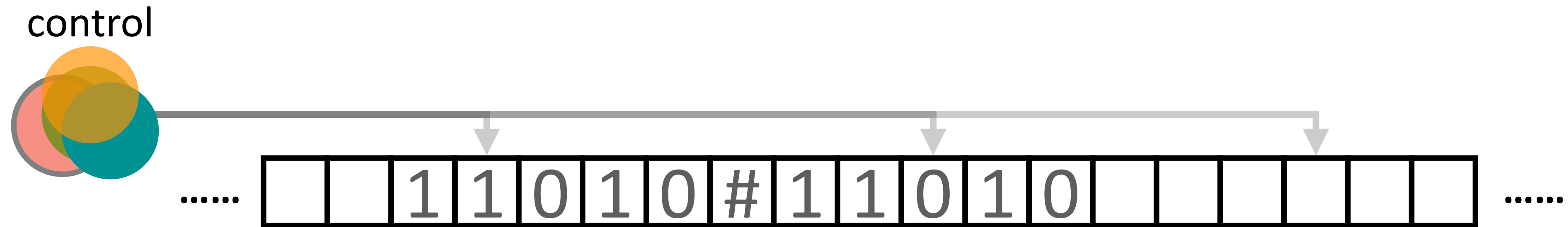
Turing machine



- An infinitely long tape/memory
 - Initially contains the (finite) **input sequence** and is blank everywhere else
- A tape head that can read and write symbols and move around on the tape
- Finite-state control 
 - The Turing machine may end up with an **accept** state or **reject** state
 - It **accepts** the input or **rejects** the input

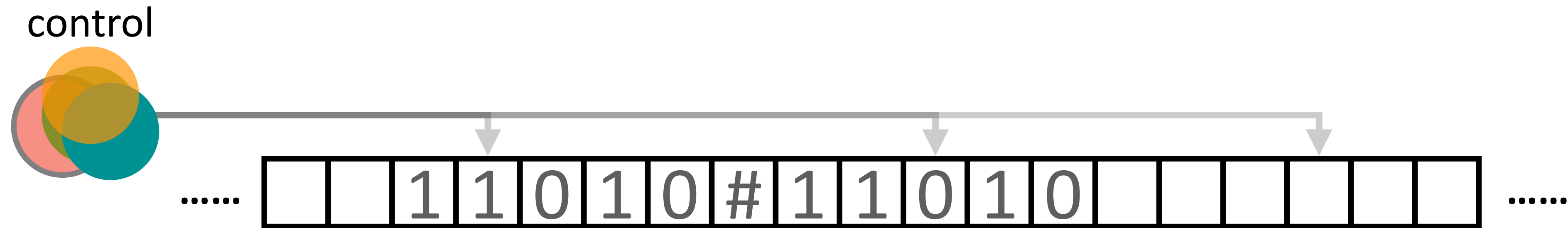
Nondeterministic Turing Machine

Nondeterministic Turing Machine



- It is like a (deterministic) Turing machine, but with non-deterministic control

Nondeterministic Turing Machine



- It is like a (deterministic) Turing machine, but with non-deterministic control
- For an input w , we can describe all possible computations of nondeterministic Turing machine by a *computation tree*

Nondeterministic Turing Machine

Deterministic

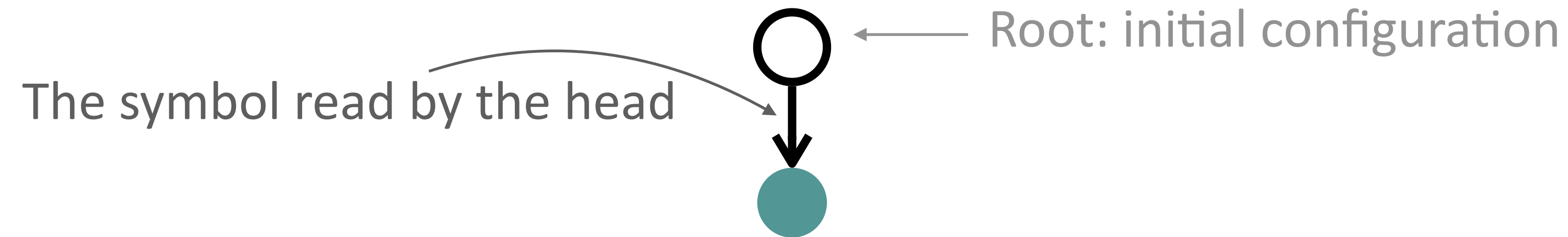


● : Configuration

(The current control state and
what the read-write head reads)

Nondeterministic Turing Machine

Deterministic

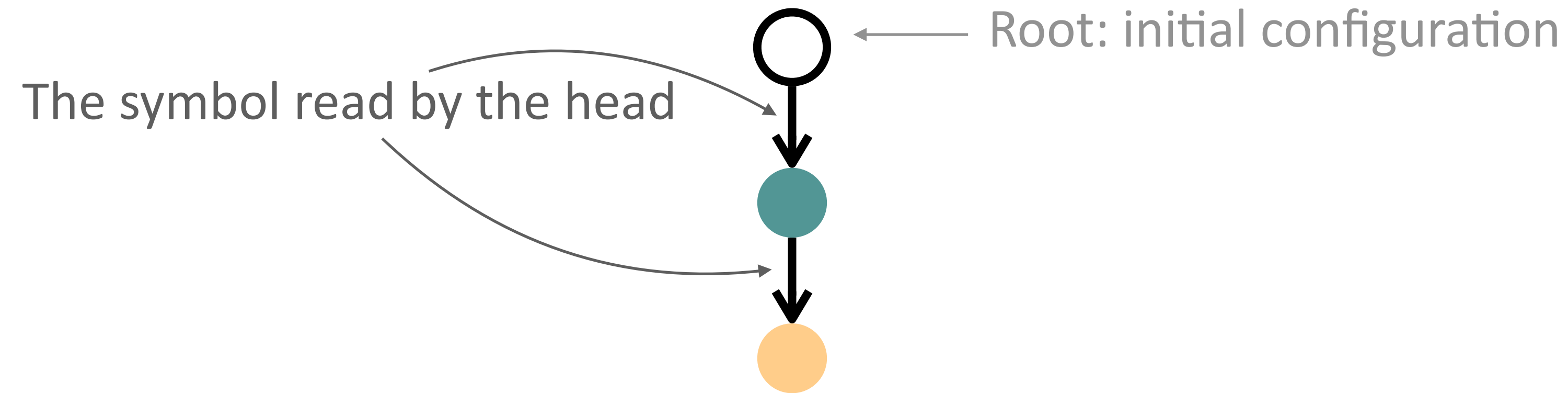


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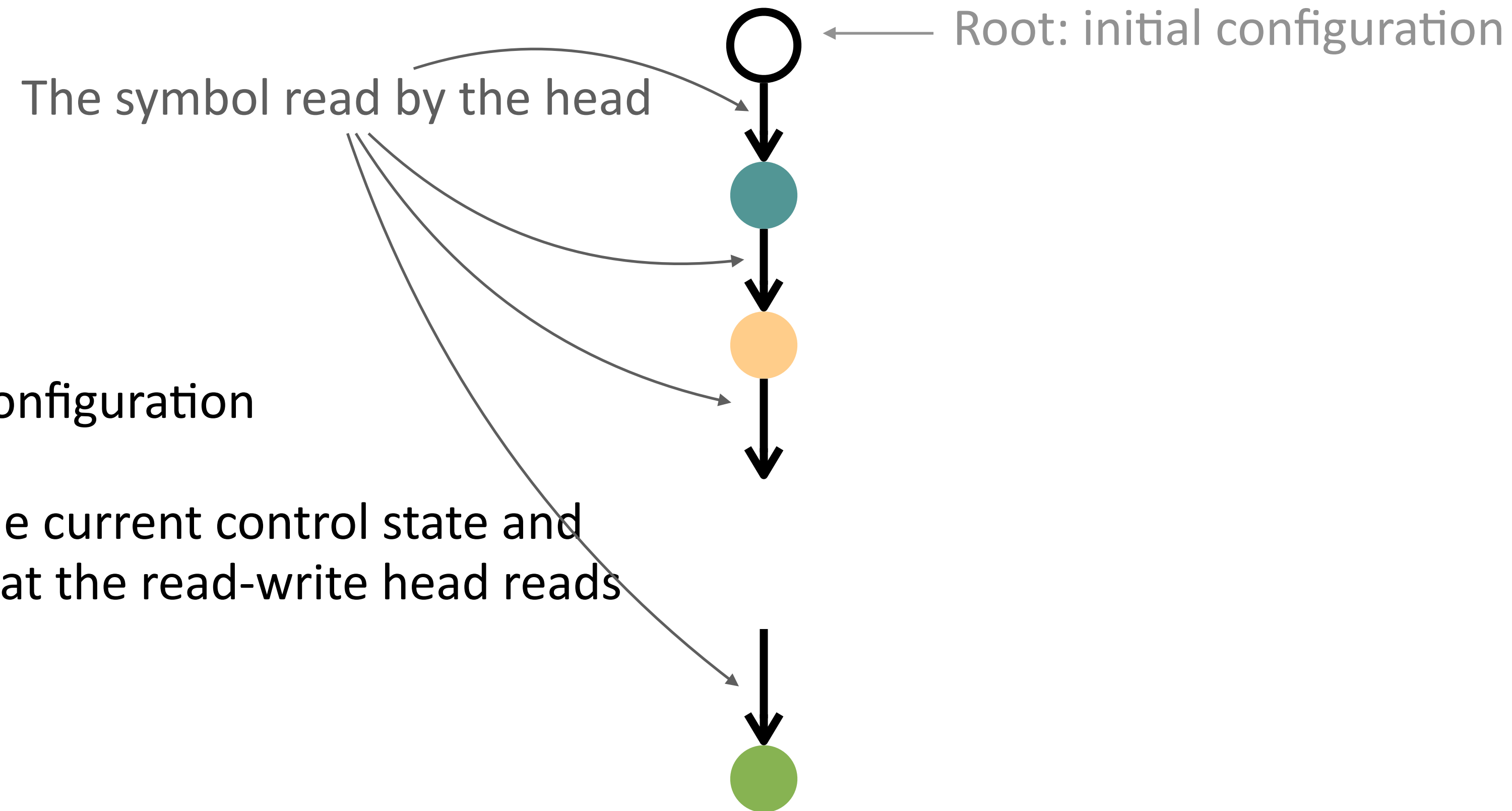


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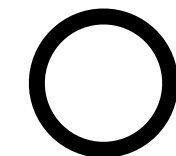
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Deterministic

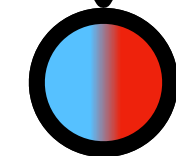
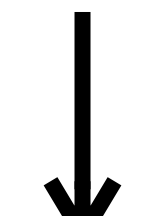


Nondeterministic Turing Machine

Deterministic



← Root: initial configuration



accept/reject

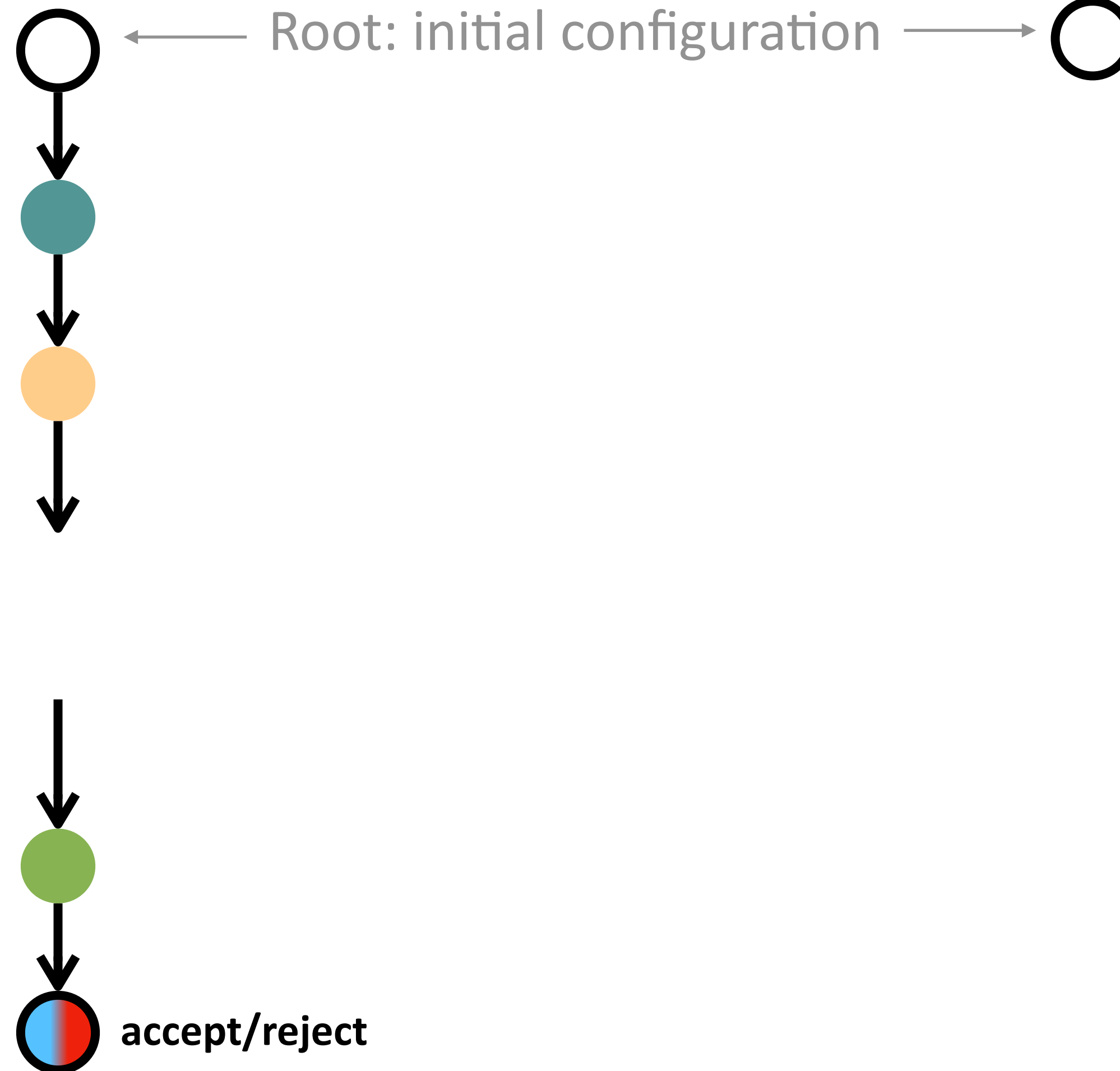
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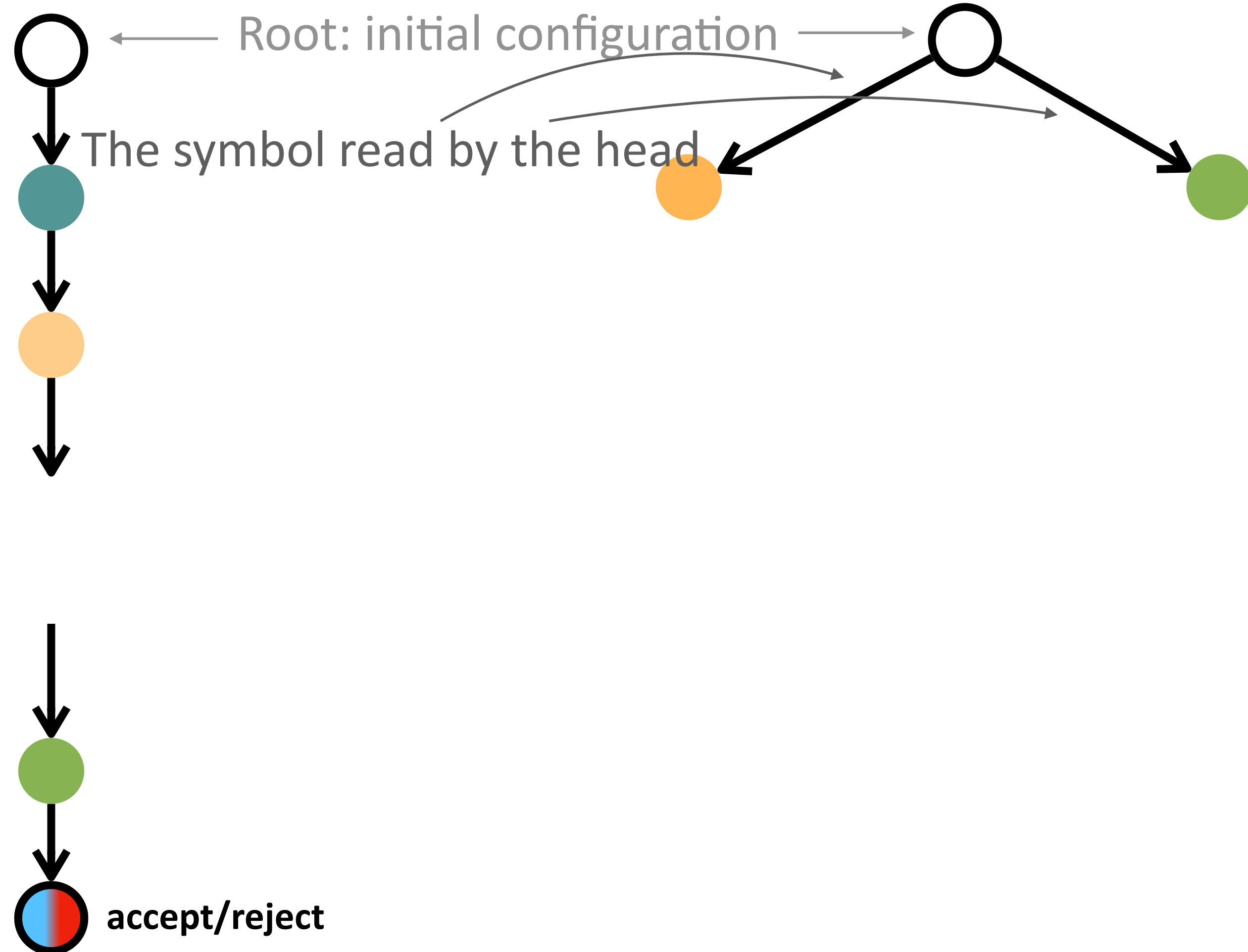
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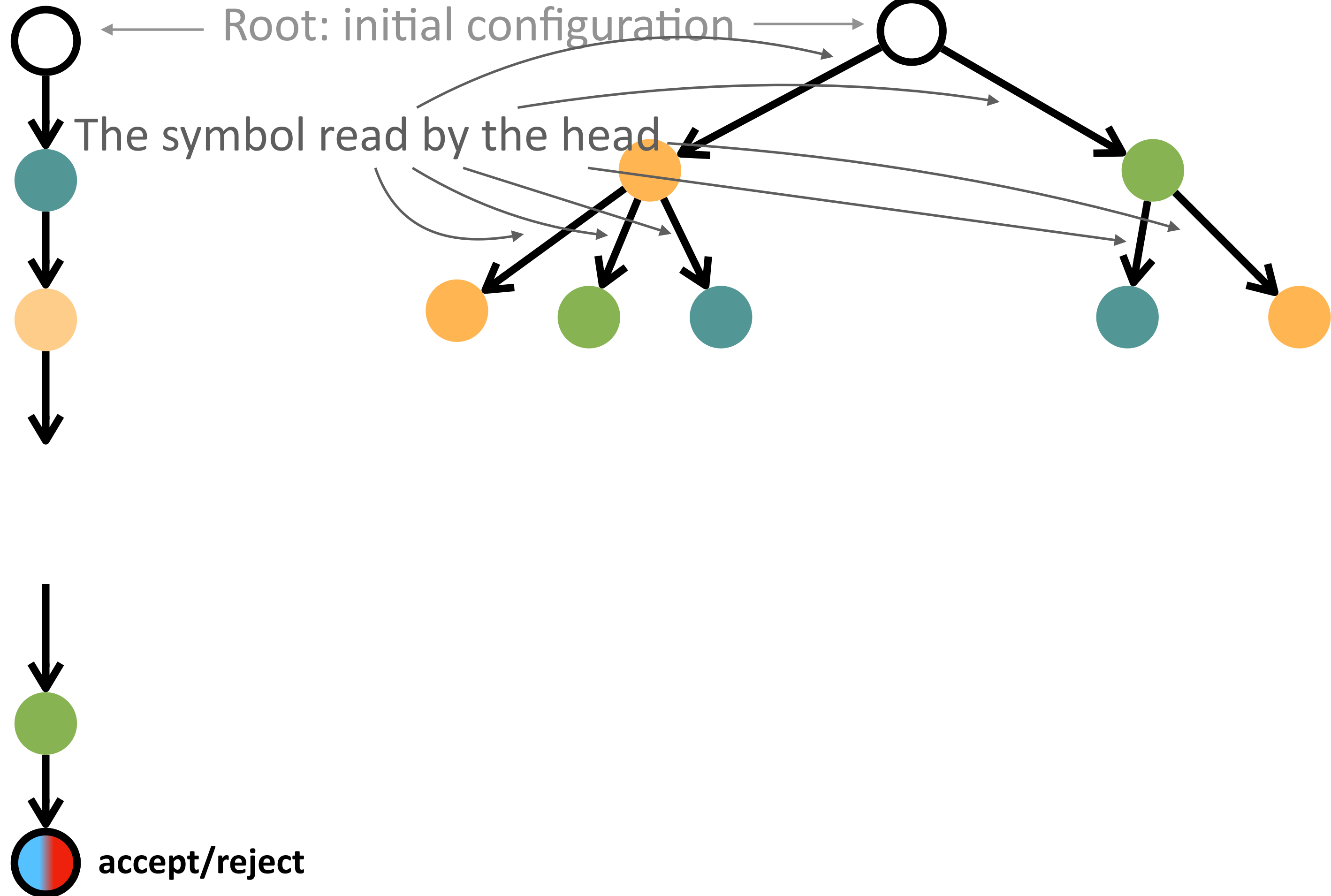
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Nondeterministic Turing Machine



accept/reject

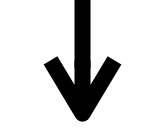
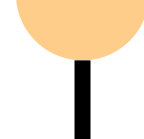
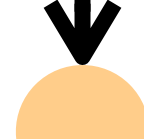
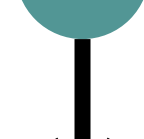
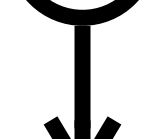
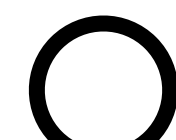
Configuration

(The current control state and what the read-write head reads

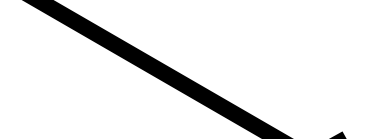
Nondeterministic Turing Machine

Deterministic

Nondeterministic

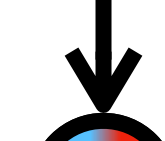
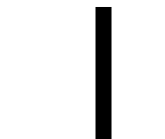


Root: initial configuration



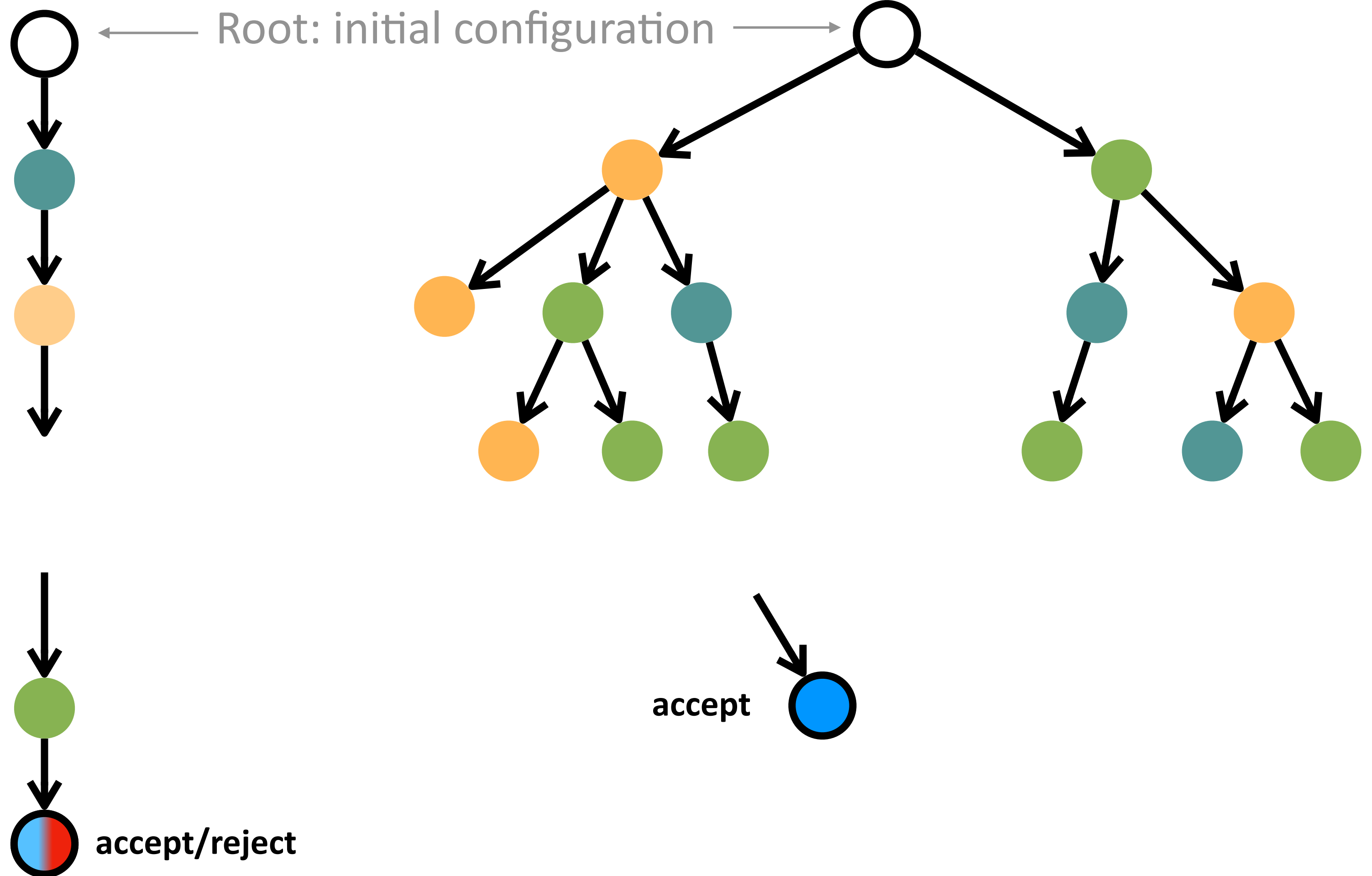
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accept/reject

Nondeterministic Turing Machine



accept/reject

accept

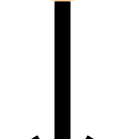
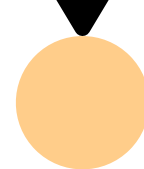
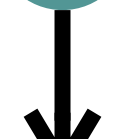
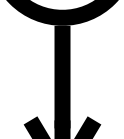
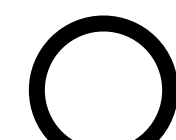
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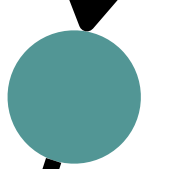
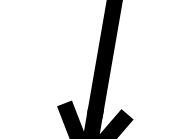
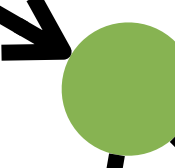
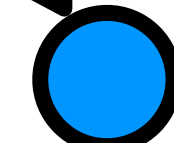


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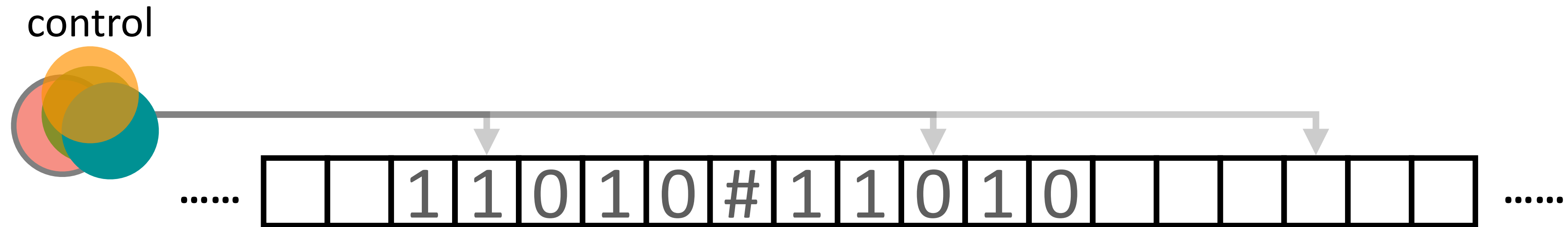
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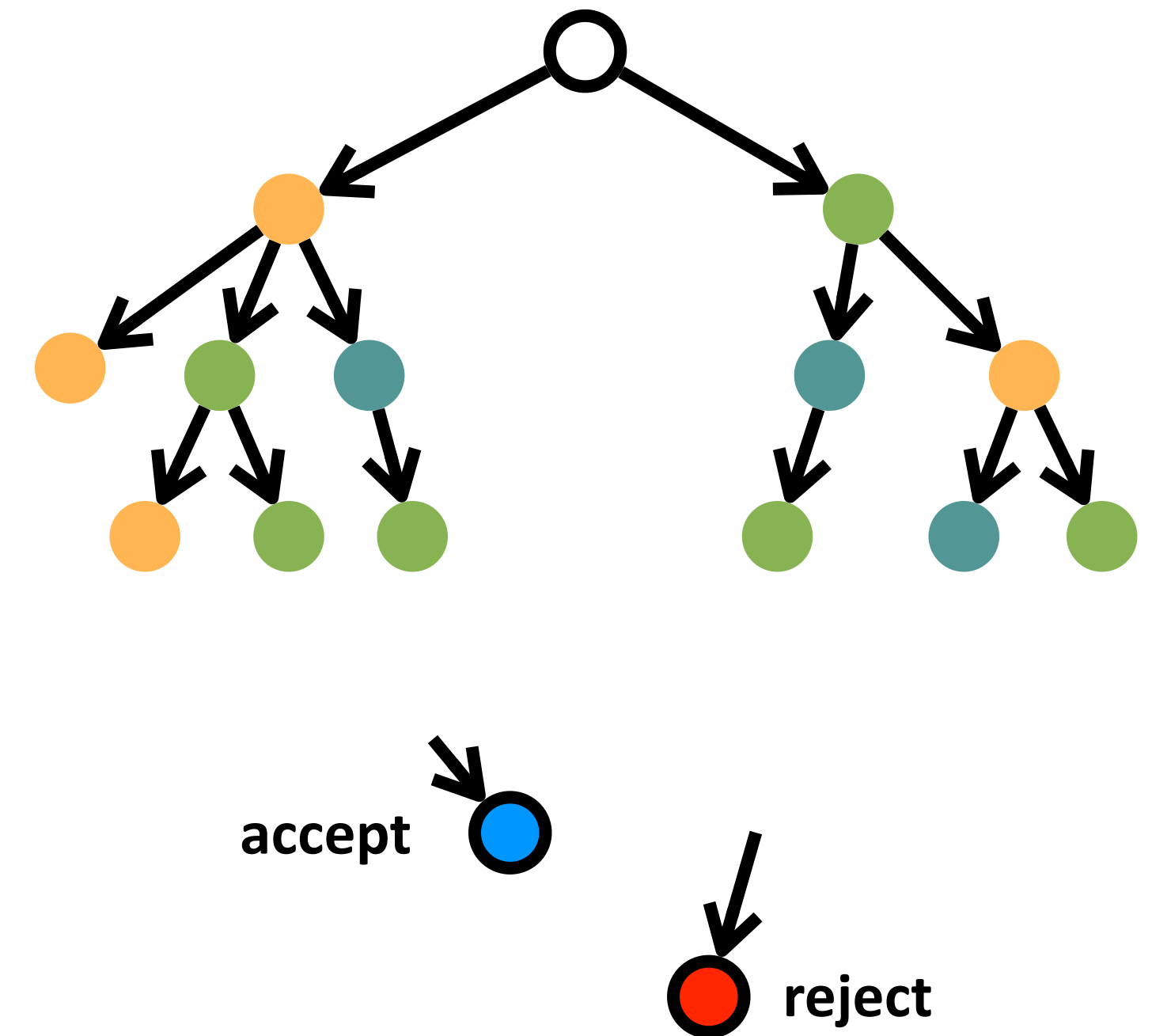
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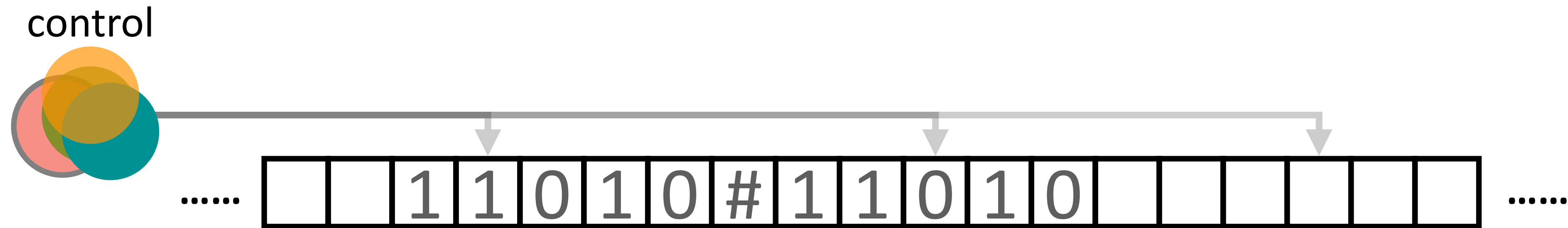
Nondeterministic Turing Machine



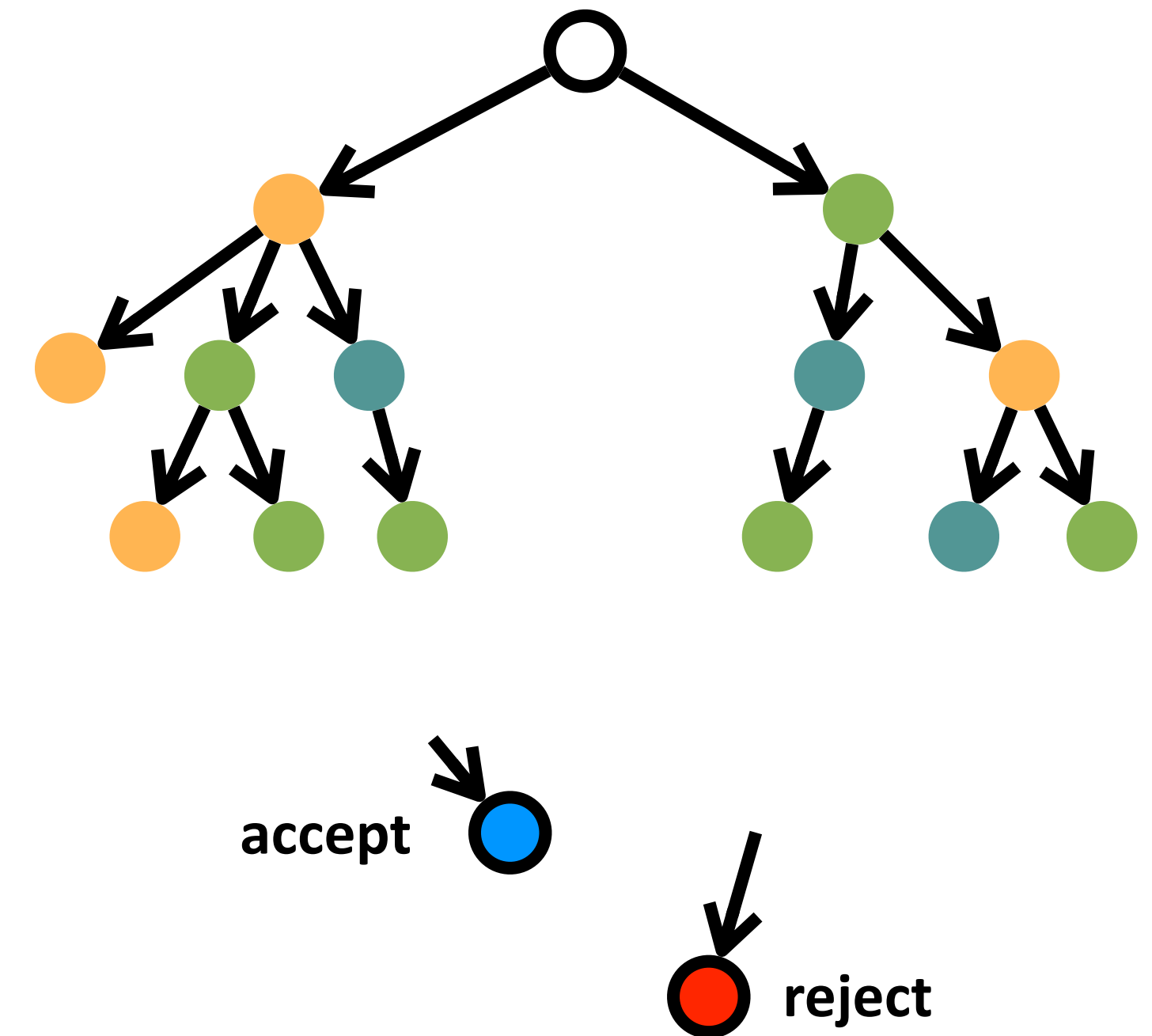
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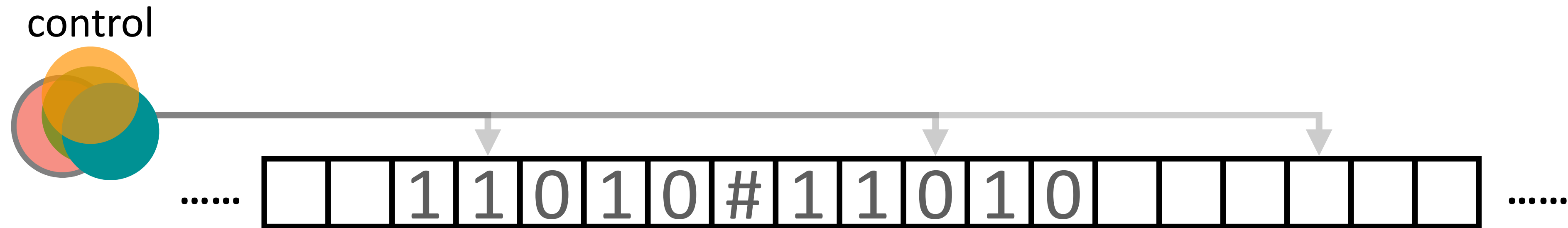
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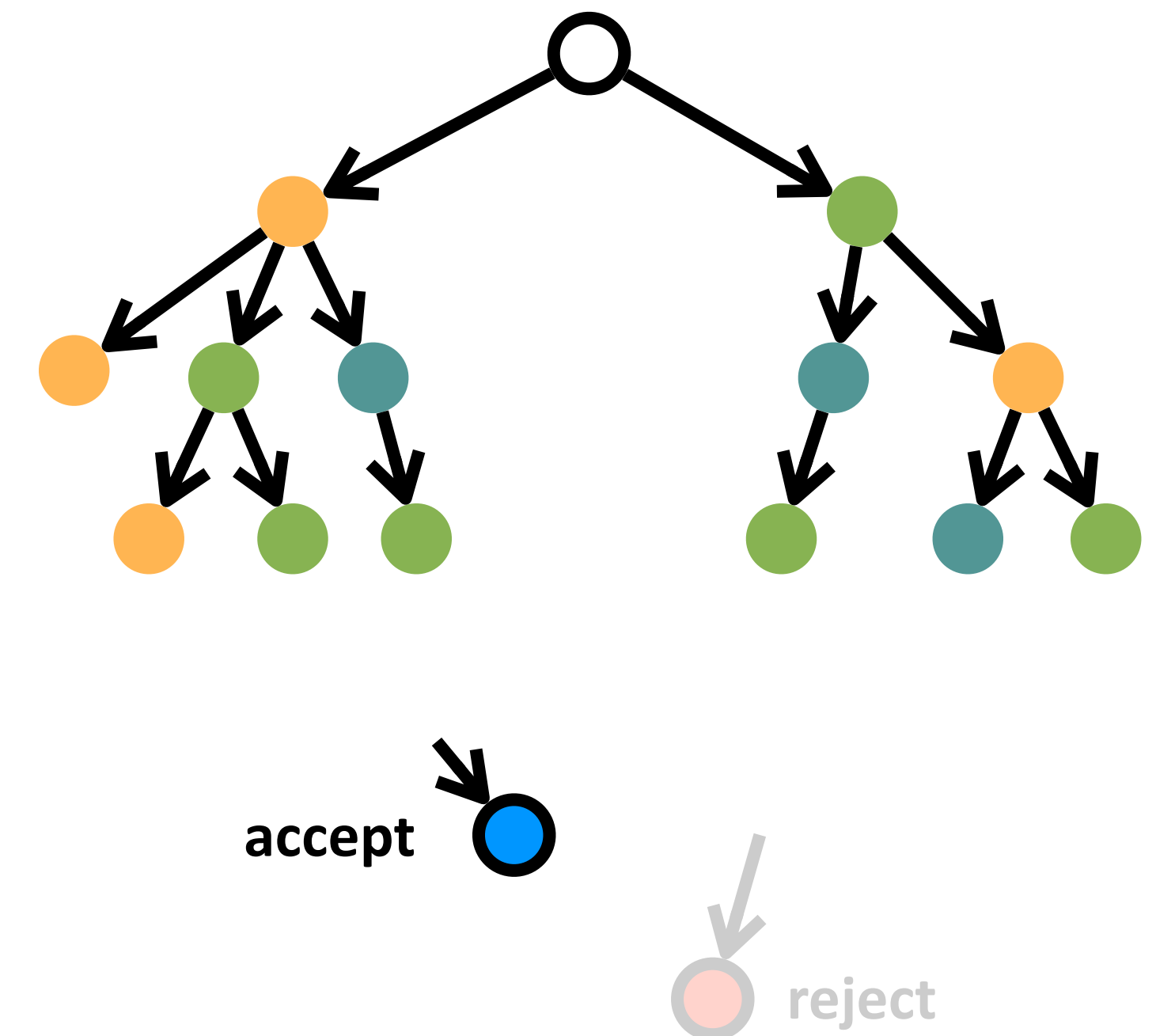
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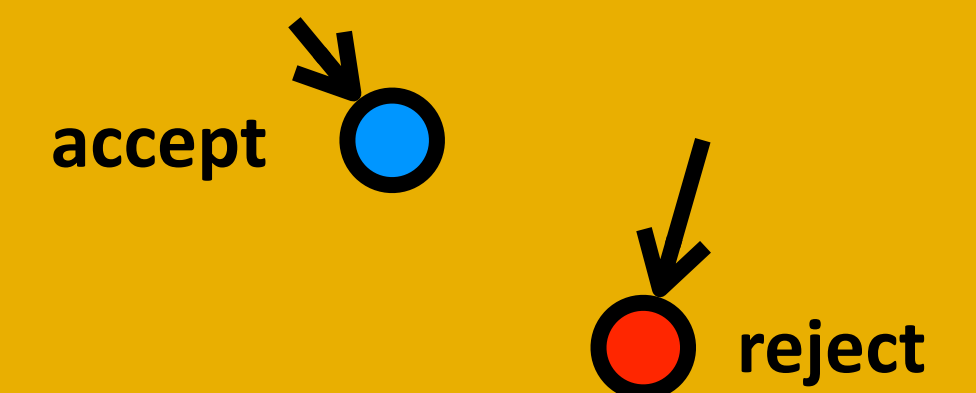
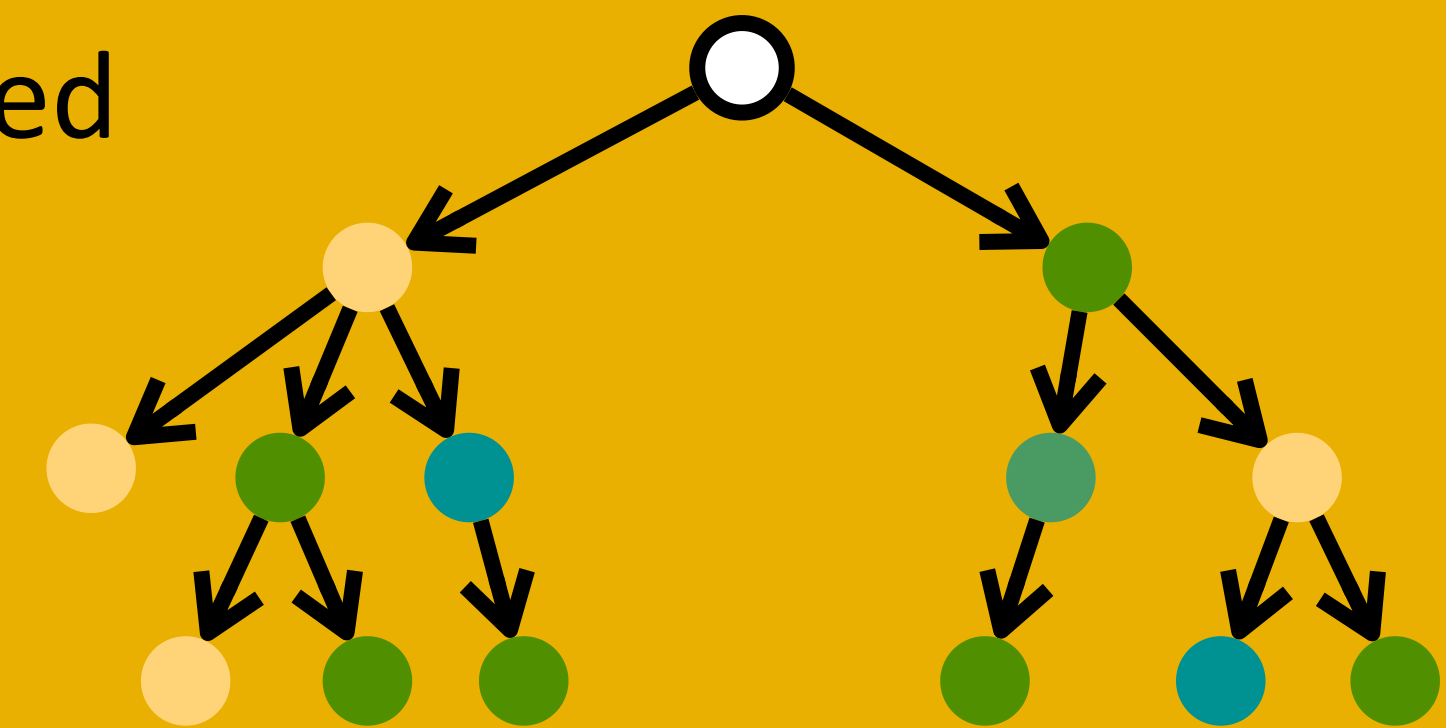
- It is like a (deterministic) Turing machine, but with non-deterministic control
 - Given an state and read a symbol, the non-deterministic Turing machine may enter different states
- The nondeterministic Turing machine *accepts* the input w if **some** branch of computation (i.e., a path from root to some node) leads to the **accept** state



Non-Deterministic Turing machine



- Like the (deterministic) Turing machine, but have non-deterministic behavior
- If there is a path ends at an accept state, the input is accepted



What is an algorithm/computer?

Church-Turing Thesis [1936]

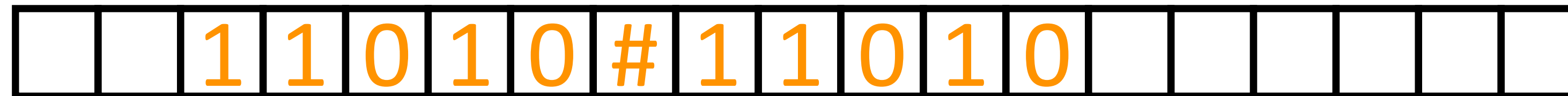
Real world computation = Turing machine computation

Overview

- Algorithms: Turing machine, Deterministic and non-deterministic
- Formal language framework: string and language
- Time complexity
 - Input size
 - Classes **P** and **NP**
 - Polynomial time verification

A Formal Language Framework for *Problems*

- Initially, there is a **string** of symbols on the Turing machine tape



A Formal Language Framework for *Problems*

- Definition: A *language* is a set of strings (that satisfy some constraints)
 - $\{1, 01, 001, 0001, 00001, \dots, 0^*1\}$
 - $\{0, 1\}^*$ Example: 010, 0, 1, 11111, ϕ , $\dots$

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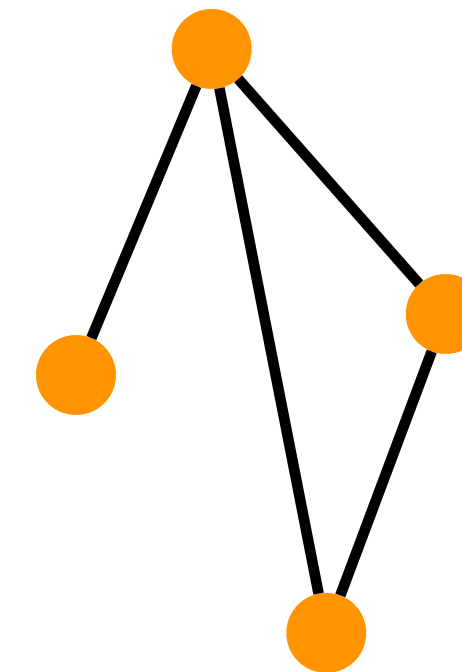
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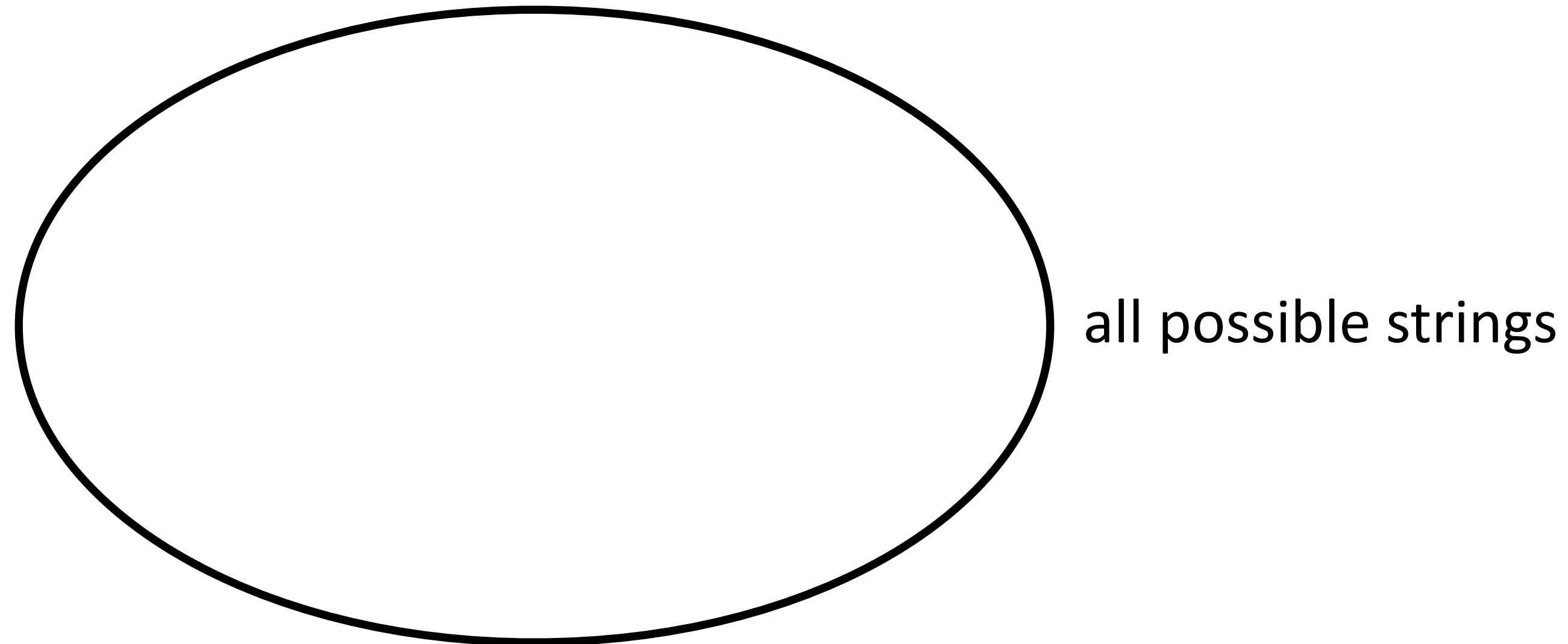
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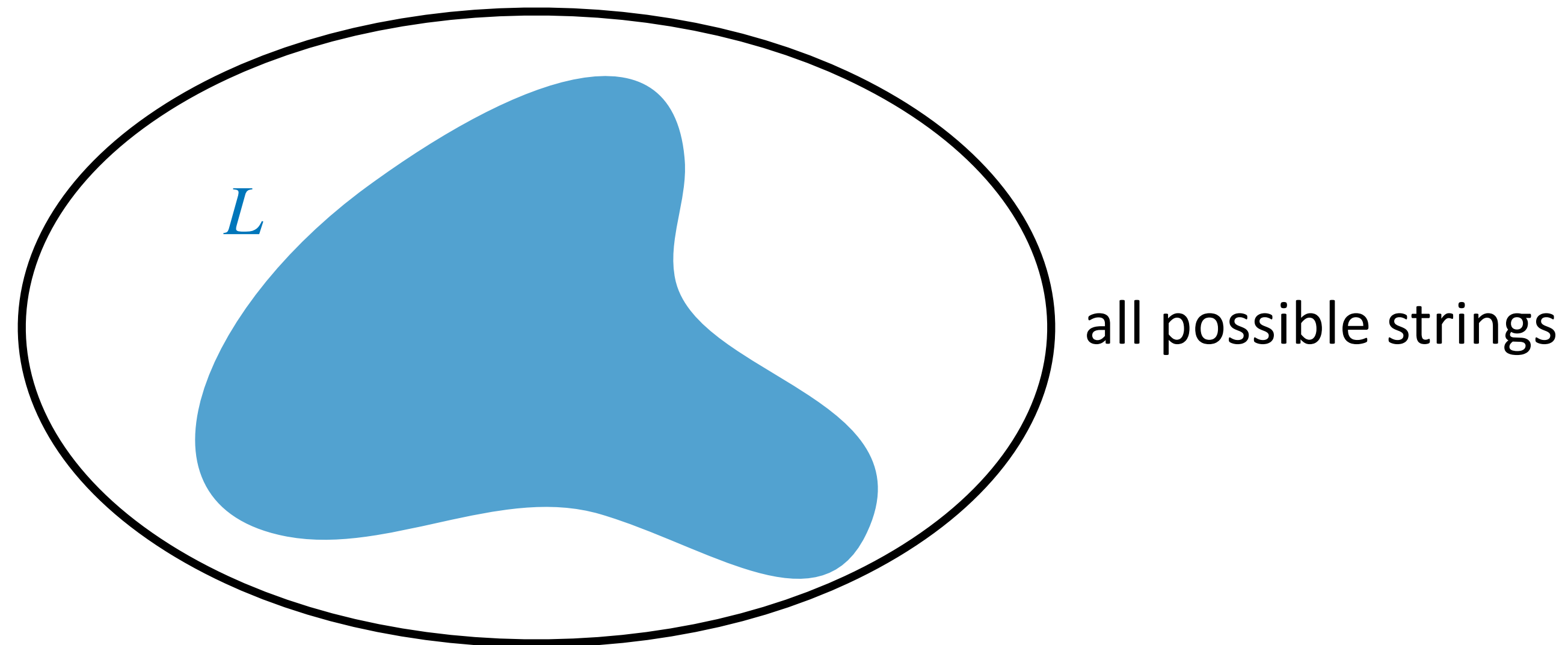
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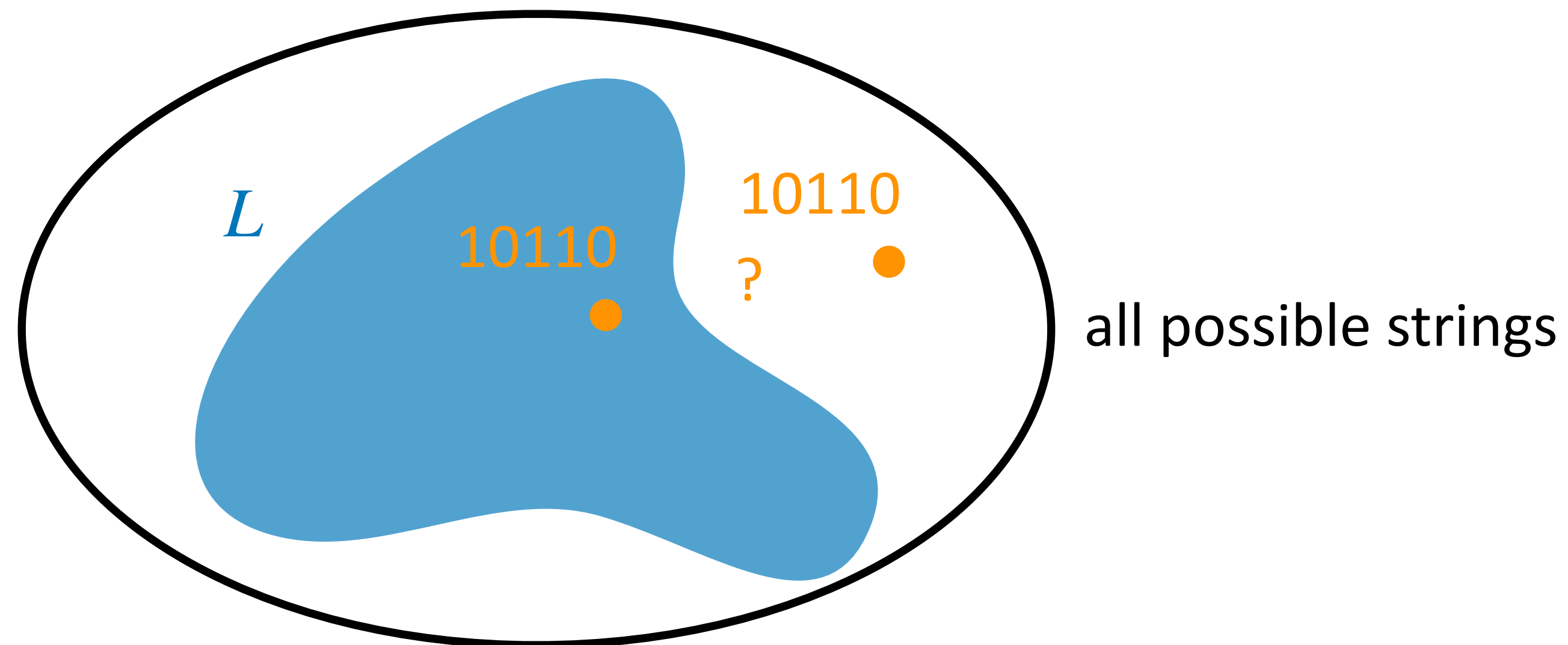
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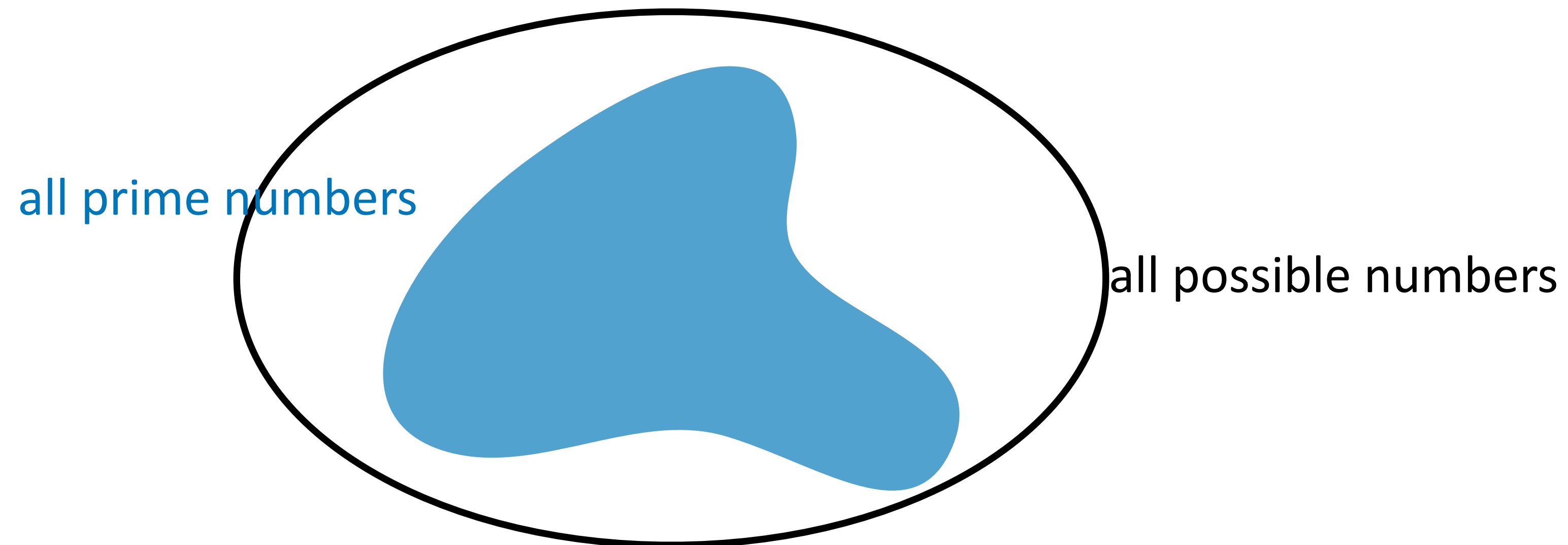
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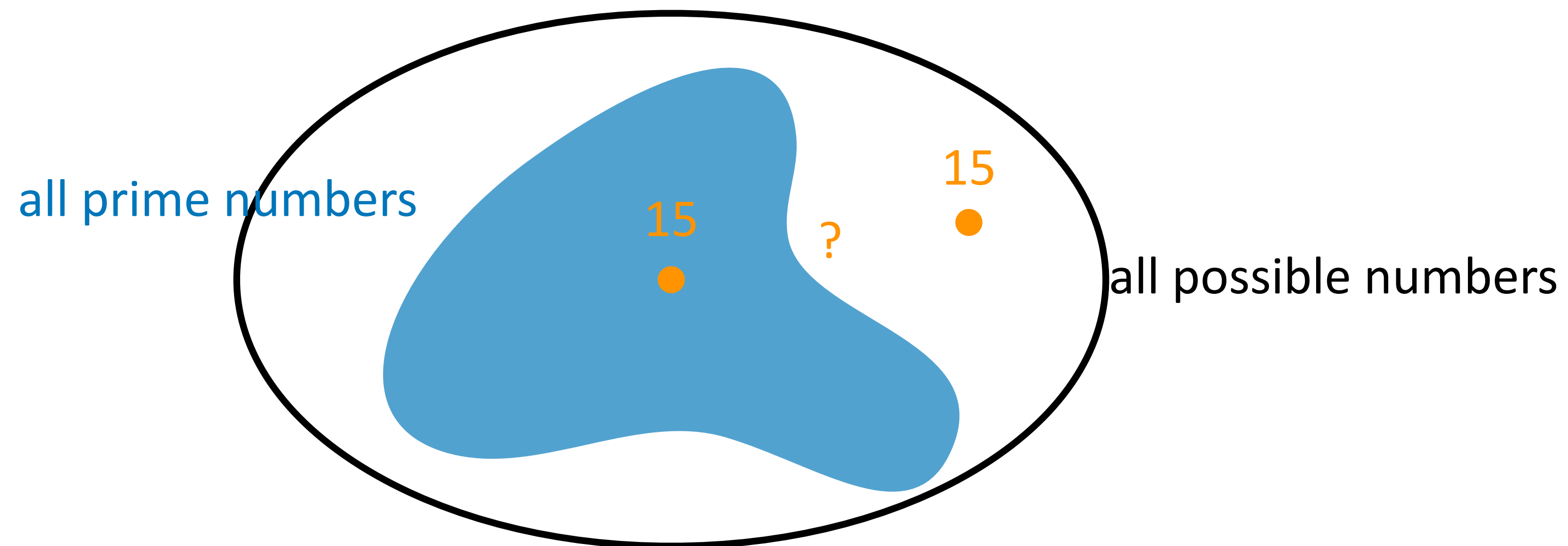
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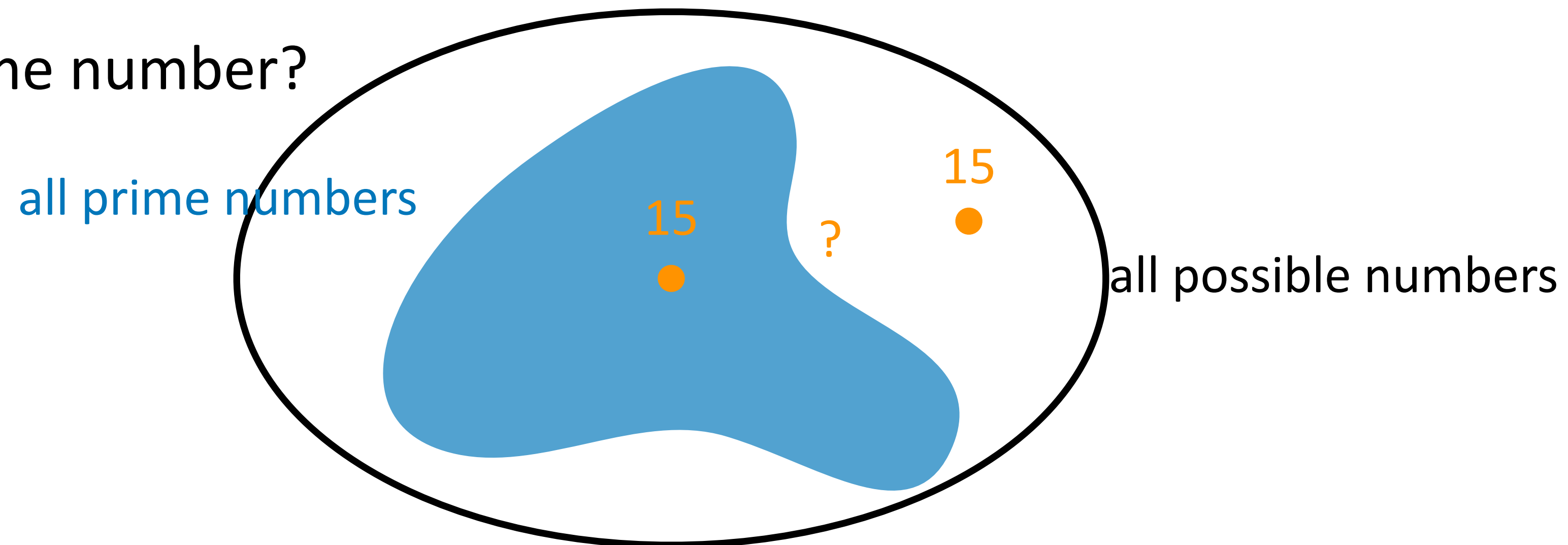
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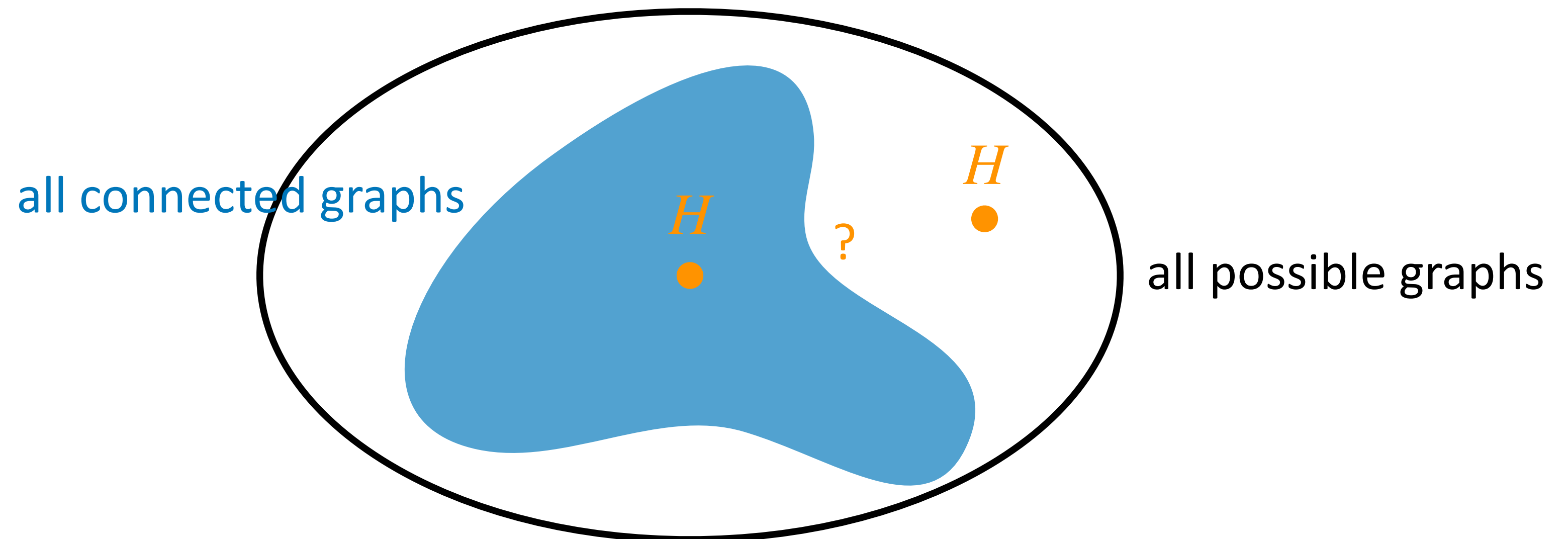


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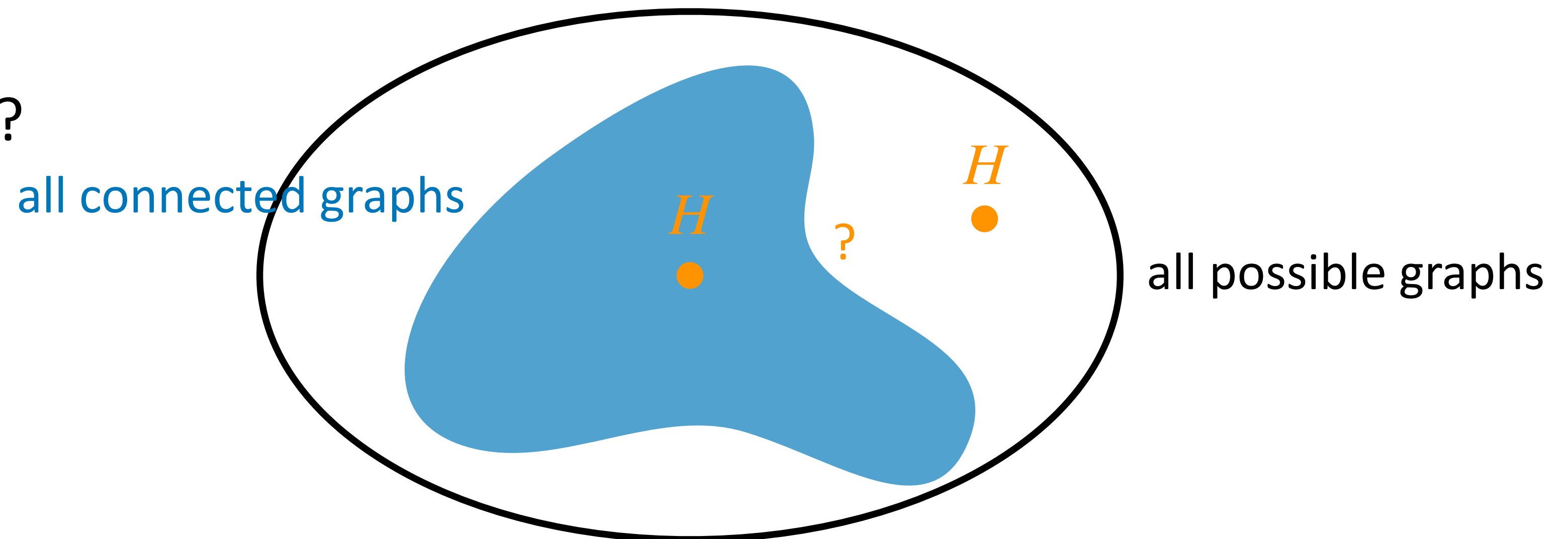
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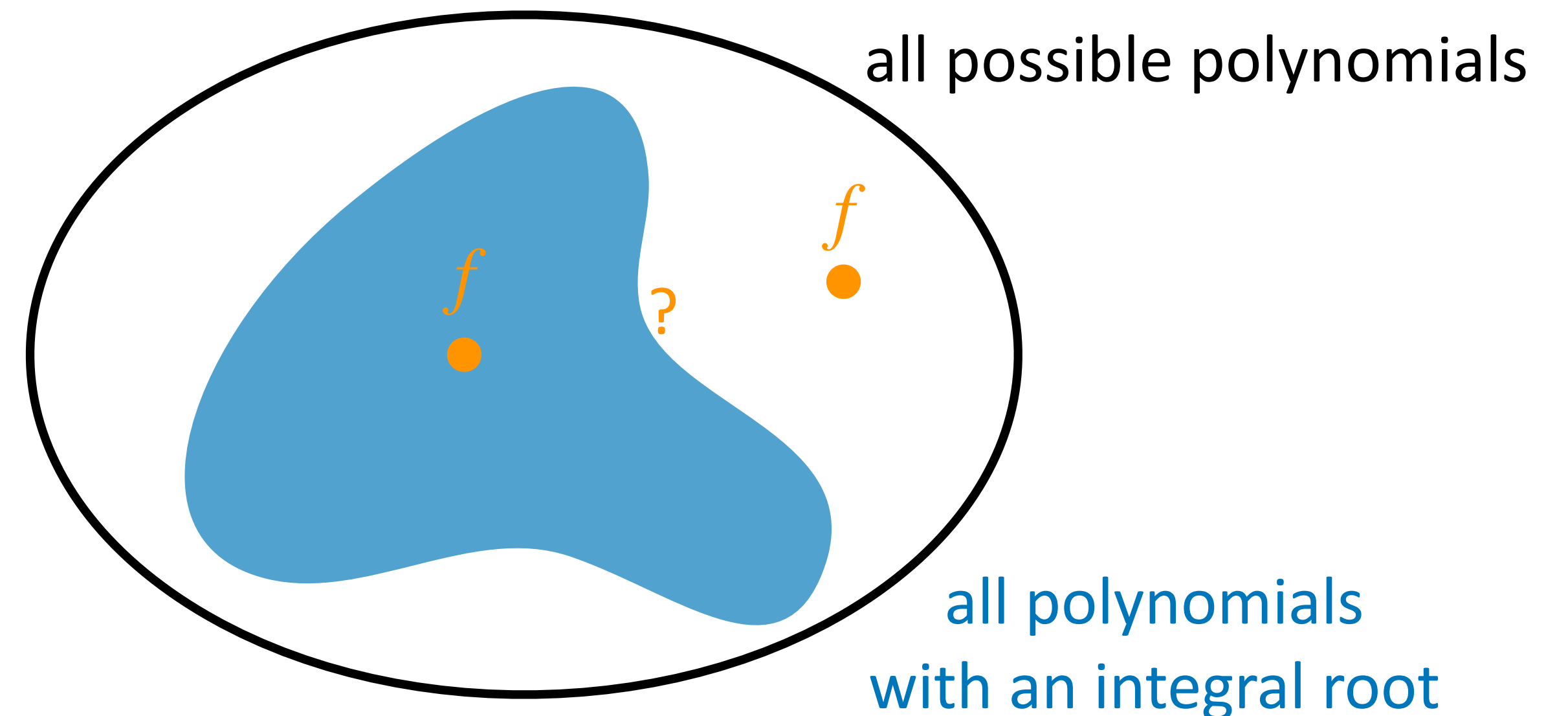


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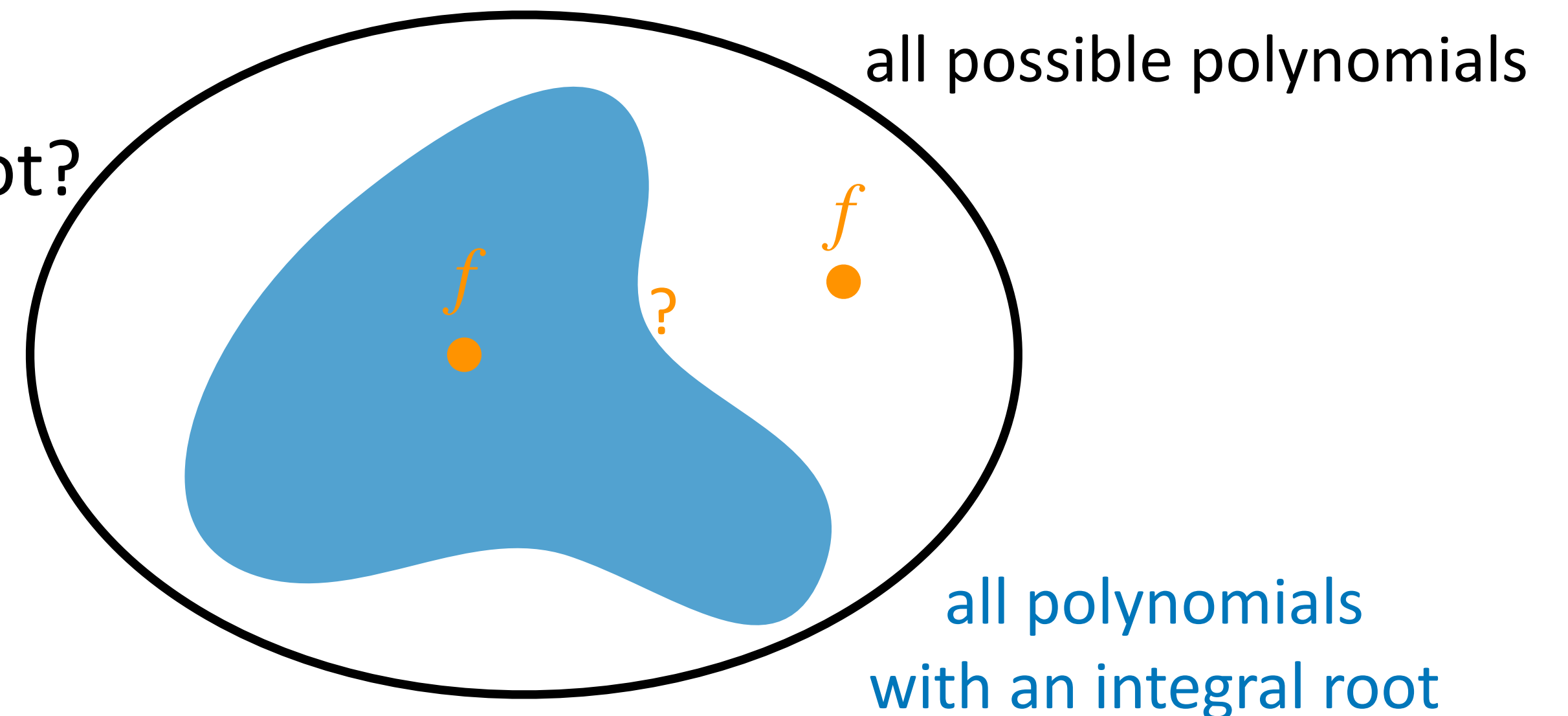
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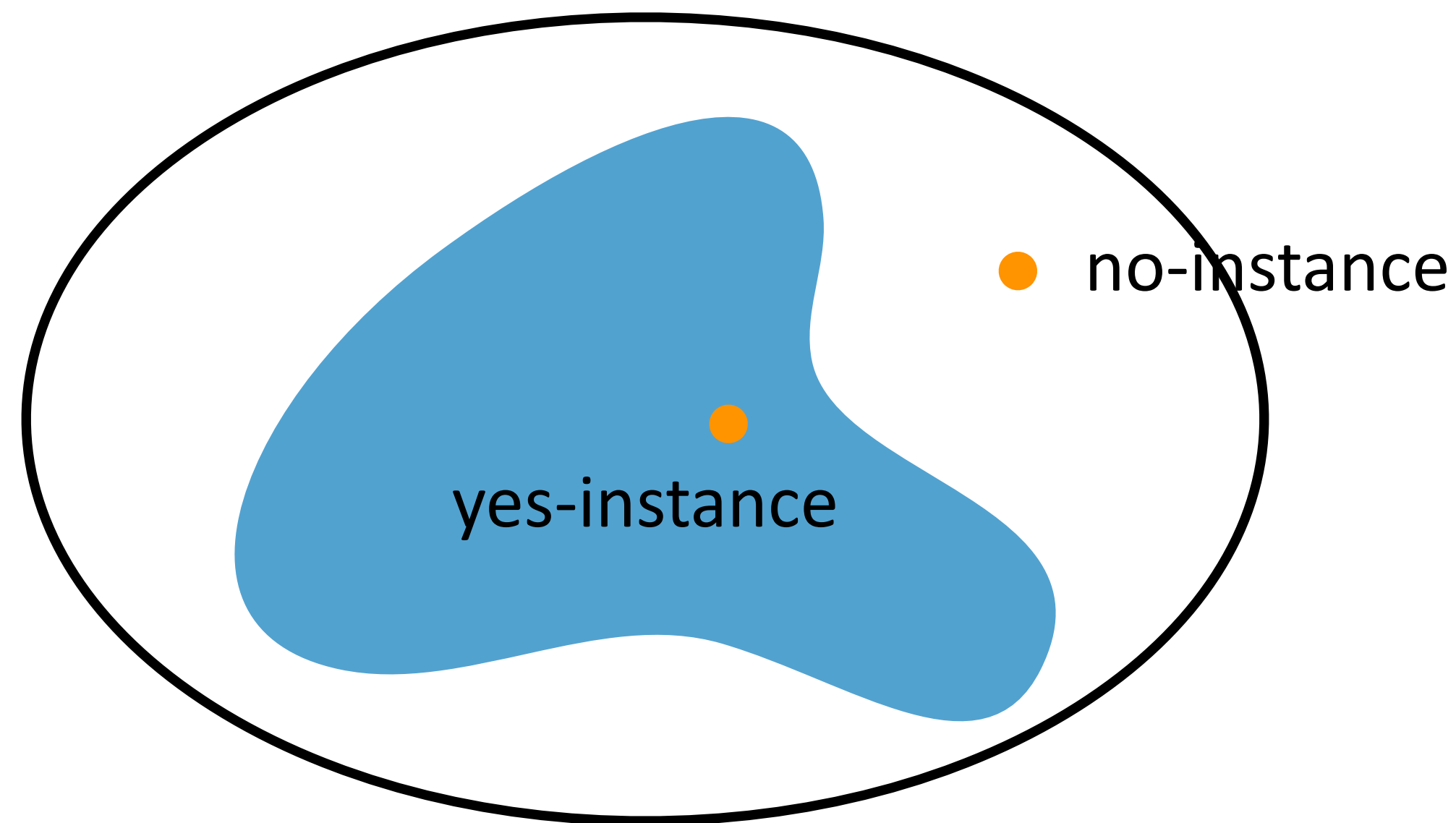


Yes-Instance and No-Instance

- Consider a language A . For any instance w , either $w \in A$ or $w \notin A$.
 - If $w \in A$, we call w a **yes-instance** (that is, a correct algorithm should return *accept* or *yes*)
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What Happened

- Following the vein of Turing machine concept, a **language** is a set of **strings**
 - Language $\Leftrightarrow$ **problem**
 - String $\Leftrightarrow$ **instance**
 - Asking if a string is in a language
 - $\Leftrightarrow$ if the instance satisfies the property that the problem asks
- Given a problem/language, a instance/string is a
 - **yes-instance**: an instance that satisfies the property that the problem asks
 - **no-instance**: an instance that does not satisfy the property that the problem asks

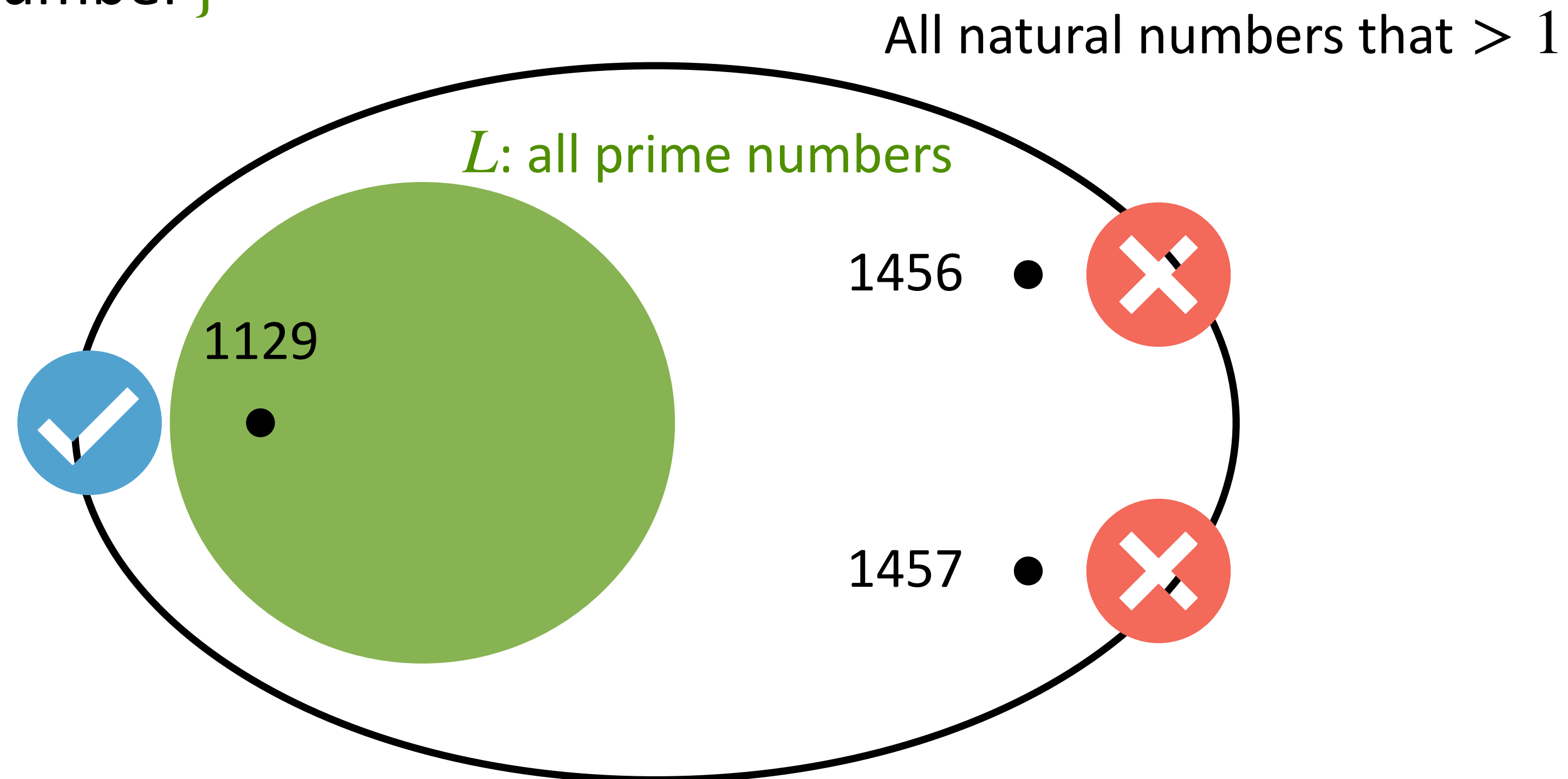
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- Ex: $L = \{\text{prime number}\}$



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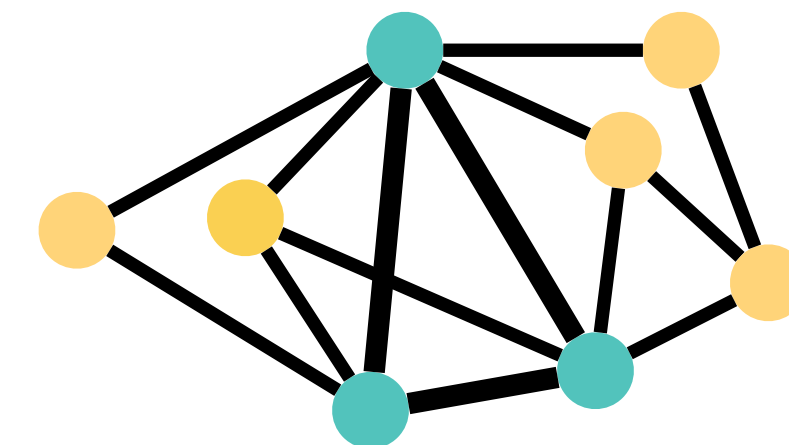
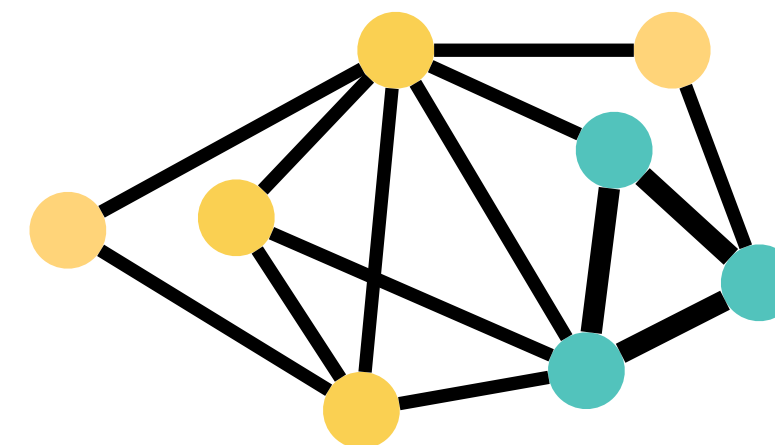
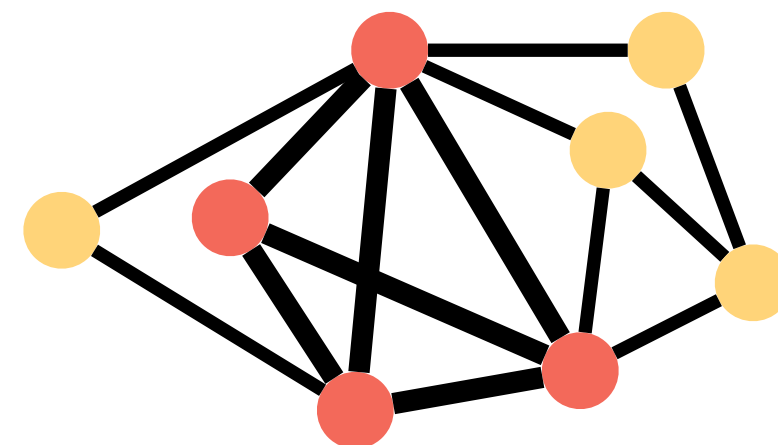
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 - Ex: Minimum vertex cover or Maximum independent set

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 - k is an additional parameter

Overview

- Algorithms: Turing machine, Deterministic and non-deterministic
- Formal language framework: string and language
- Time complexity
 - Input size
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Time Complexity

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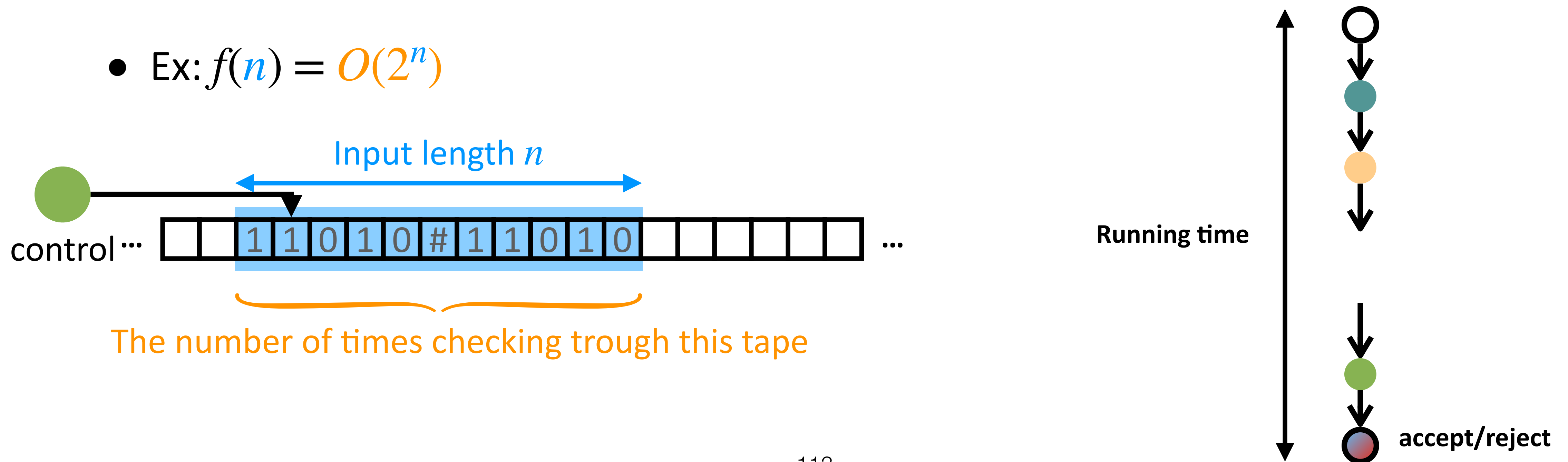
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Time Complexity

- Definition: Let M be a deterministic Turing machine that accepts or rejects all inputs. The **running time** or **time complexity** of M is the function $f: \mathcal{N} \rightarrow \mathcal{N}$, where $f(n)$ is the maximum number of steps that M uses on any input of length n .

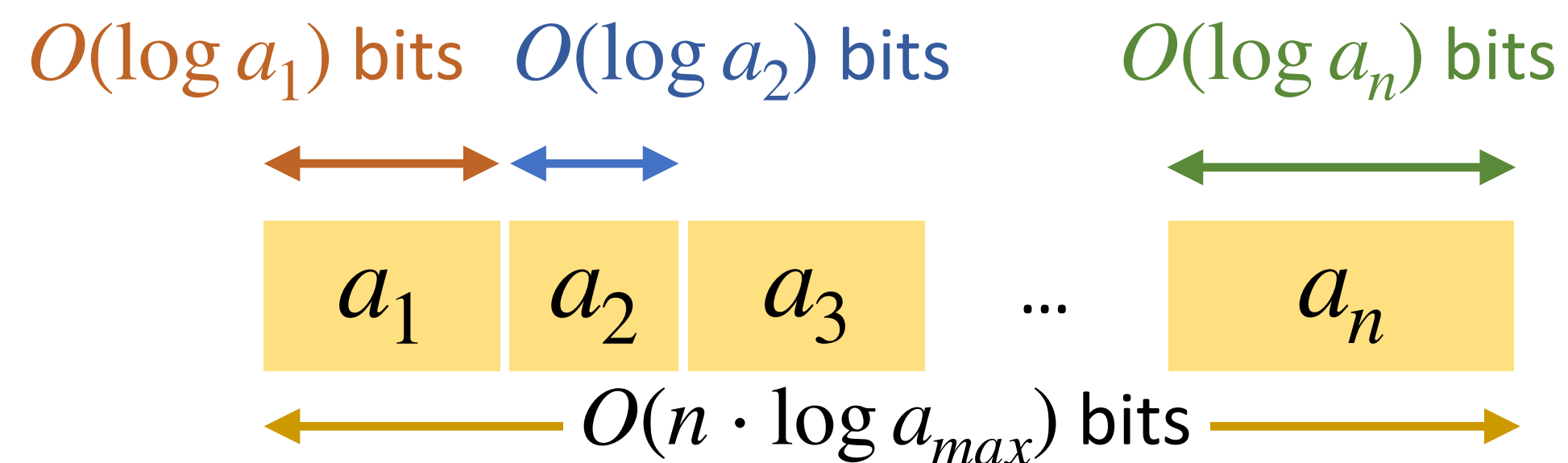
- Ex: $f(n) = O(n^2)$

- Ex: $f(n) = O(2^n)$



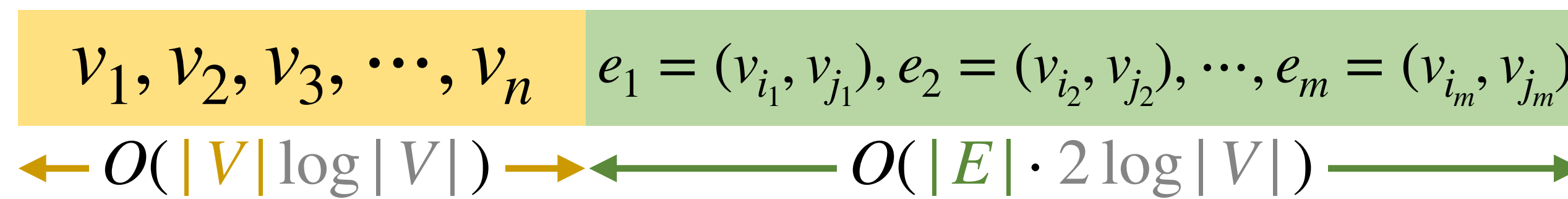
Input Size

- **PARTITION** = $\{ \langle S = \{a_1, a_2, \dots, a_n\} \rangle \mid S \text{ can be partitioned into two equal-sum subsets} \}$: a string w encoding the elements in S
- Input size: $O(n \log a_{\max})$ bits
 - n : number of items in the set S
 - $a_{\max}$: maximum value of the items in S . That is, for all $1 \leq i \leq n$, $a_i \leq a_{\max}$.



Input Size

- **CONNECT** = $\{\langle G \rangle \mid G \text{ is connected graph}\}$: a string w encoding a graph G
- Input size: using binary encoding to encode vertices and edges in G
 - Use an adjacency array, the input size is $O(|V| \log |V| + |V|^2) = O(|V|^2)$ bits
 - Use an adjacency list, the input size is $O(|V| \log |V| + |E| \cdot 2 \log |V|) = O(|V|^2 \log |V|)$ bits
 - The $O(\log |V|)$ bits are for encoding the vertex ID



Input Size

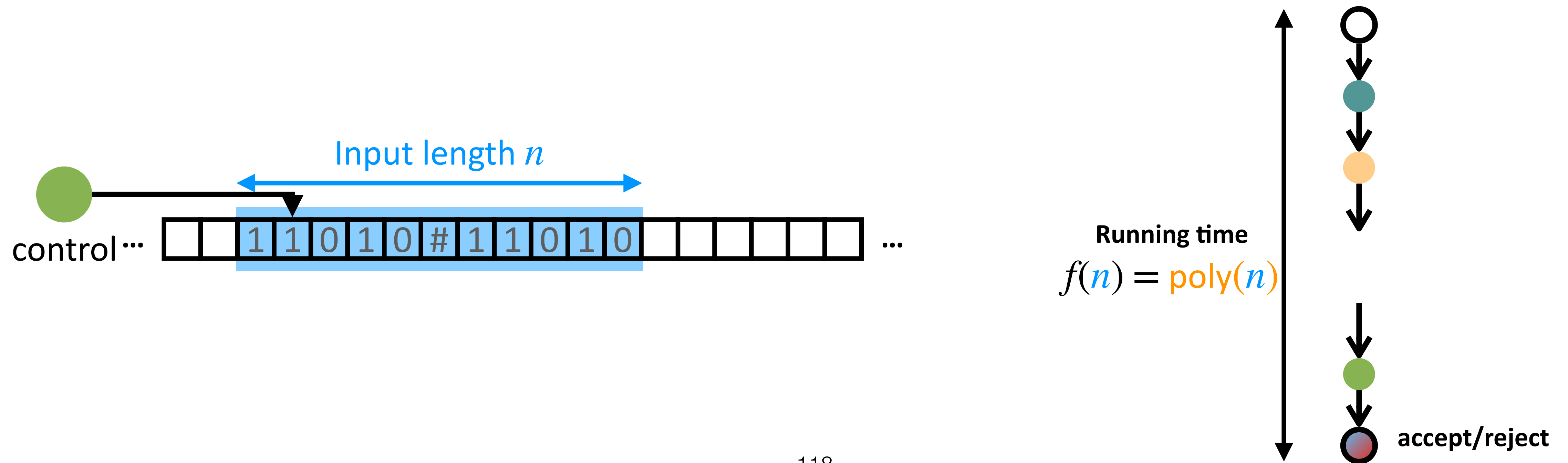
- **PRIME** = {prime number}: a string w representing number n
- Input size?

Overview

- Algorithms: Turing machine, Deterministic and non-deterministic
- Formal language framework: string and language
- Time complexity
 - Input size
 - Classes **P** and **NP**
 - Polynomial time verification

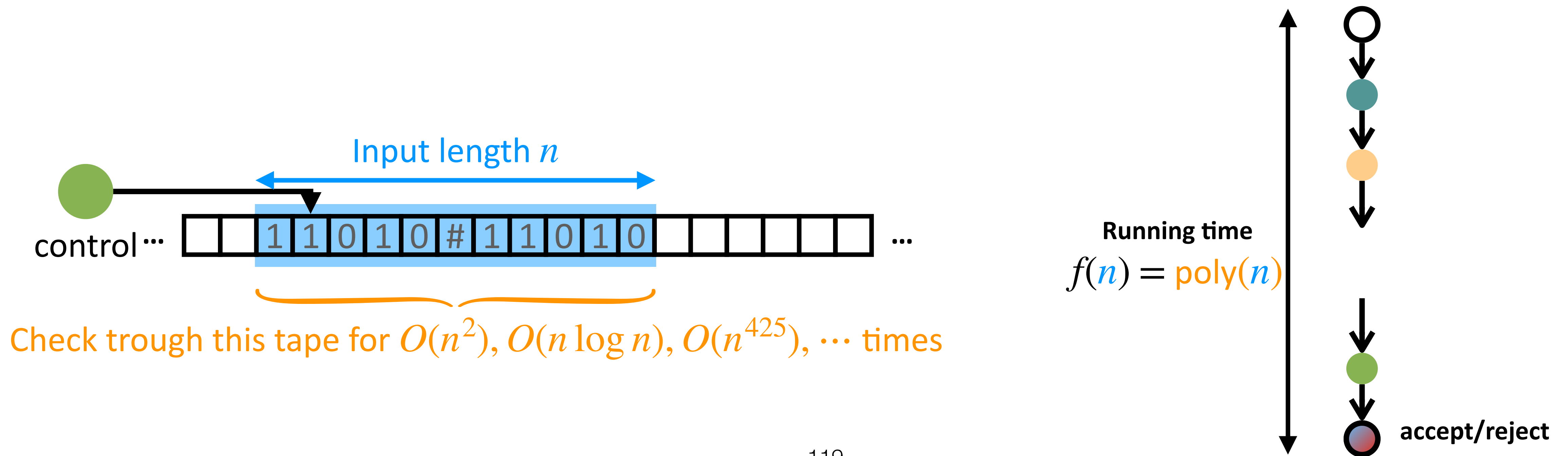
The Class P

- Definition: **P** is the class of languages that can be accepted or rejected in polynomial time by a deterministic single-tape Turing machine.



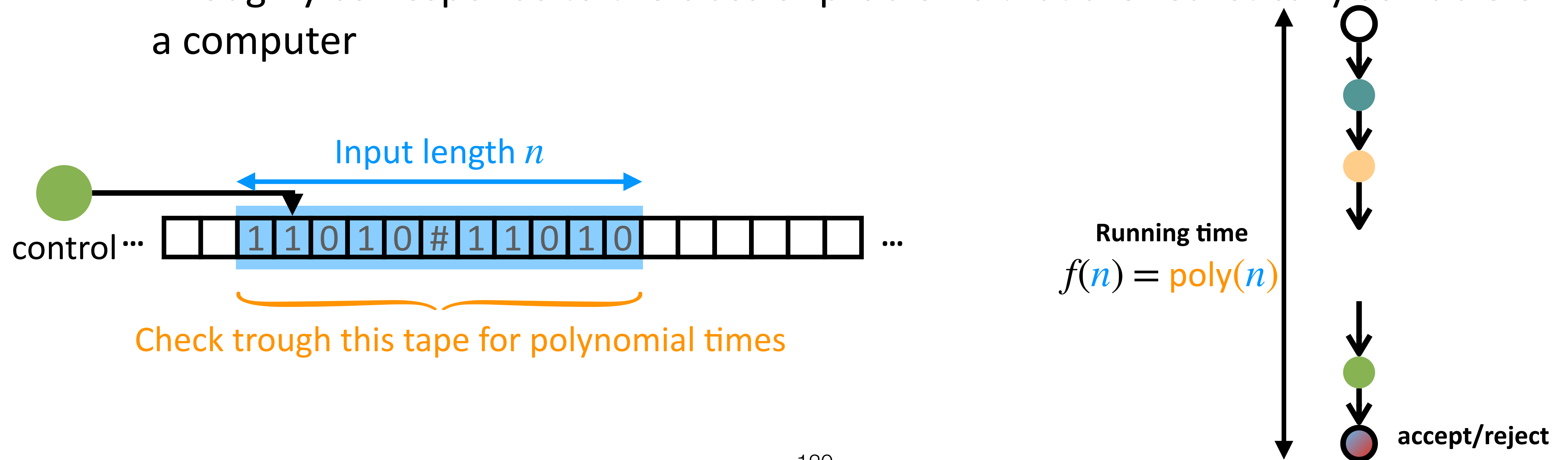
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 - Ex: $O(n^2)$, $O(n \log n)$, $O(n^{425})$, ...



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 - Ex: $O(n^2)$, $O(n \log n)$, $O(n^{425})$, ...
 - **P** roughly corresponds to the class of problems that are realistically solvable on a computer



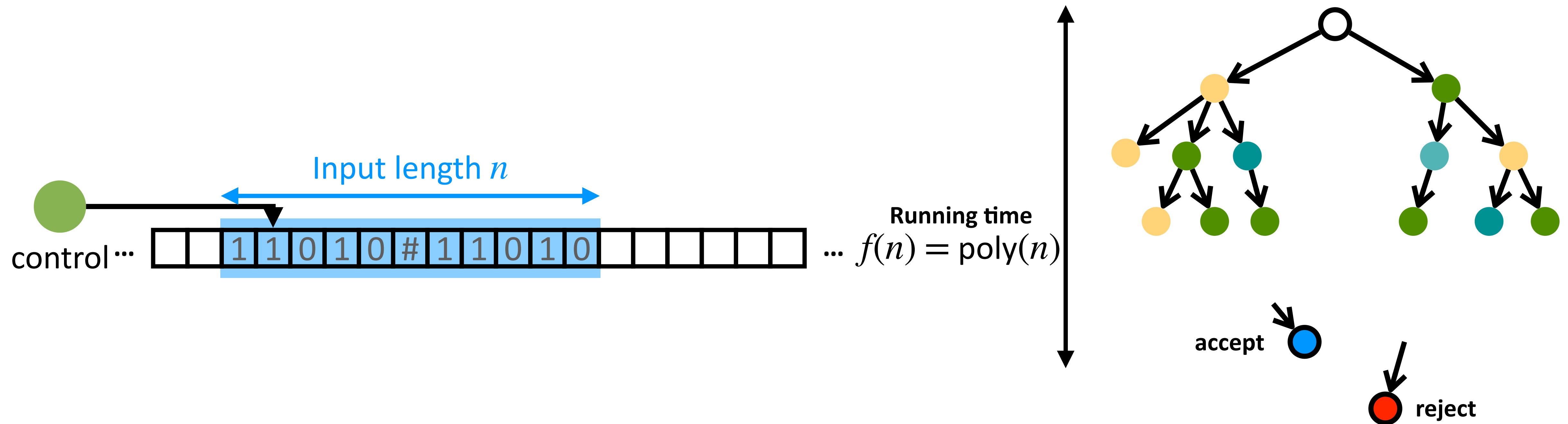
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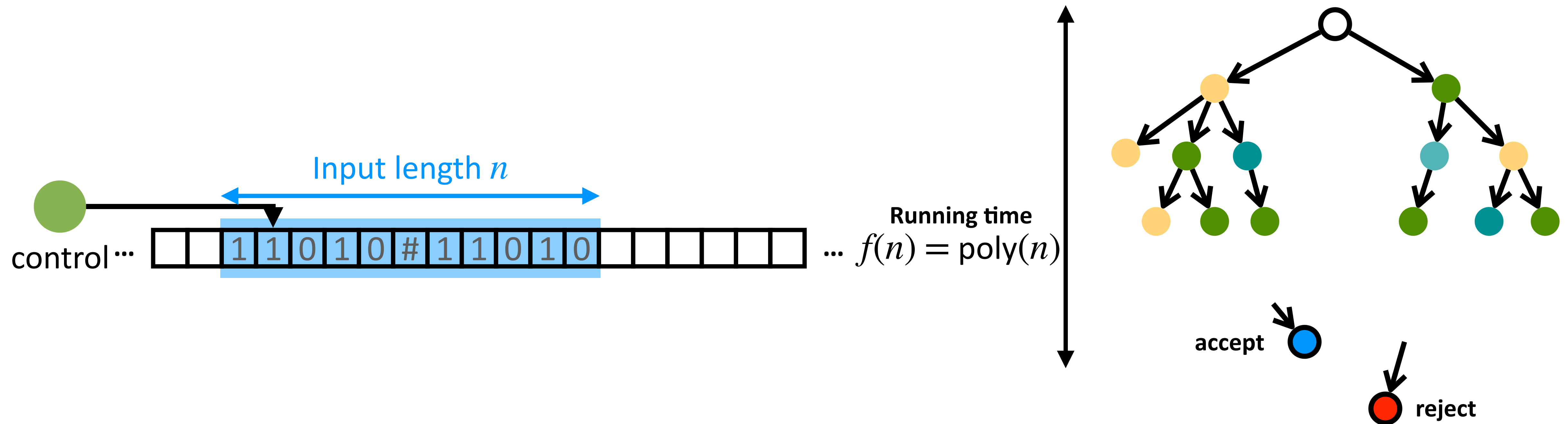
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- Similarly, we can define the running time of a non-deterministic Turing machine N



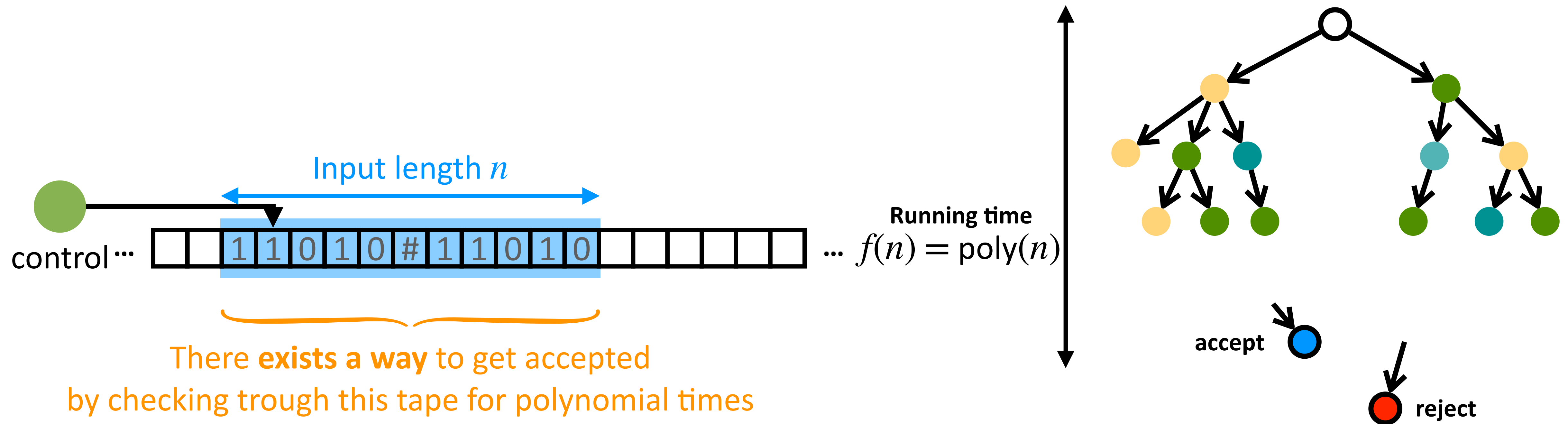
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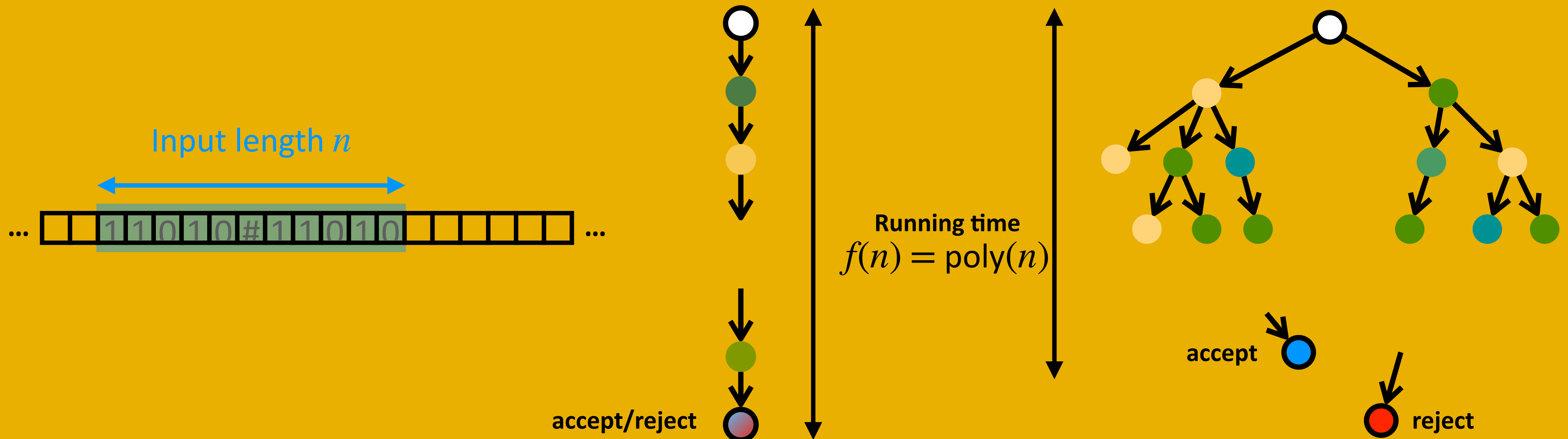
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What Happened

- The class **P** is the class of languages that are accepted or rejected in polynomial time by a *deterministic* Turing machine
- The class **NP** is the class of languages that are accepted in polynomial time by a *non-deterministic* Turing machine.



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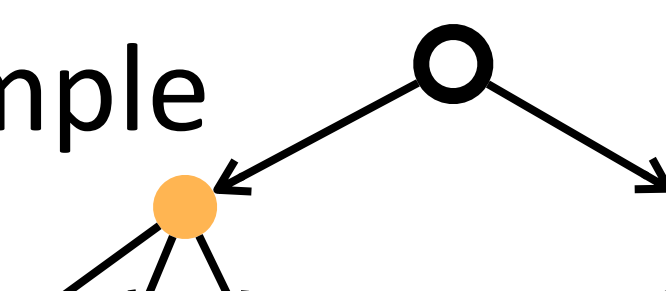
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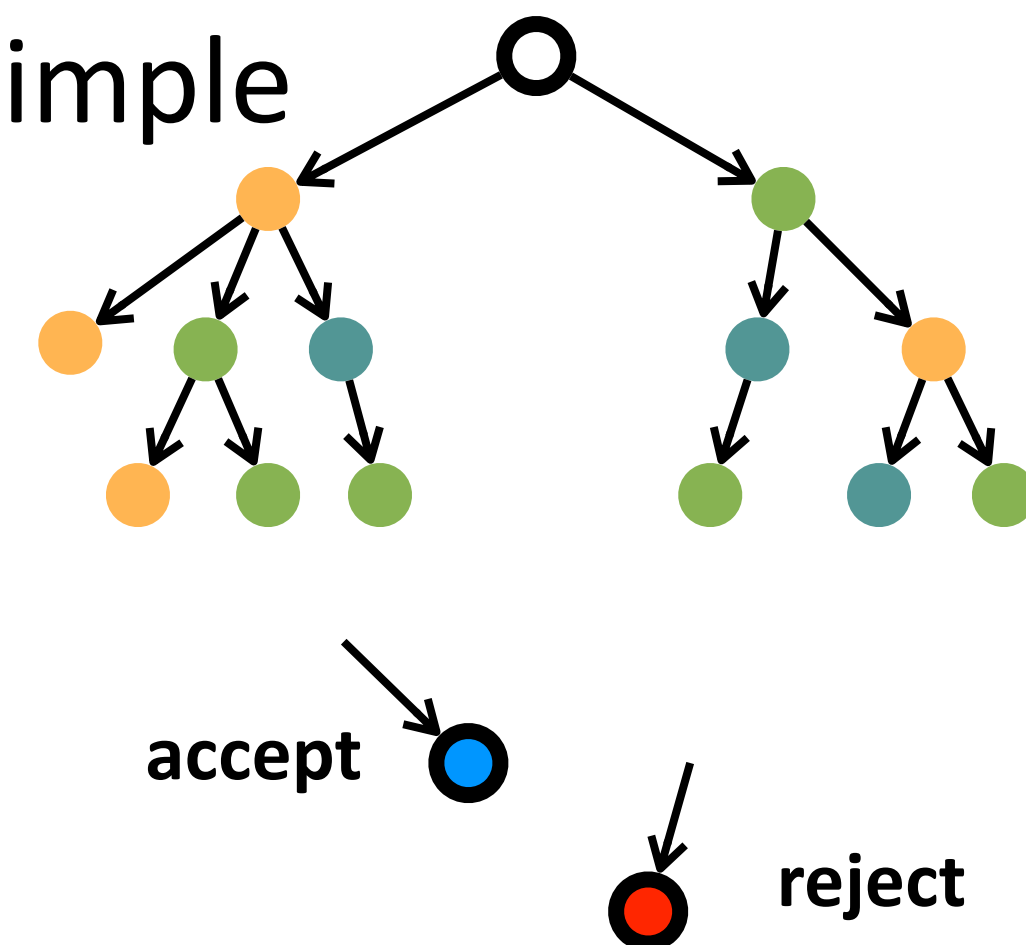
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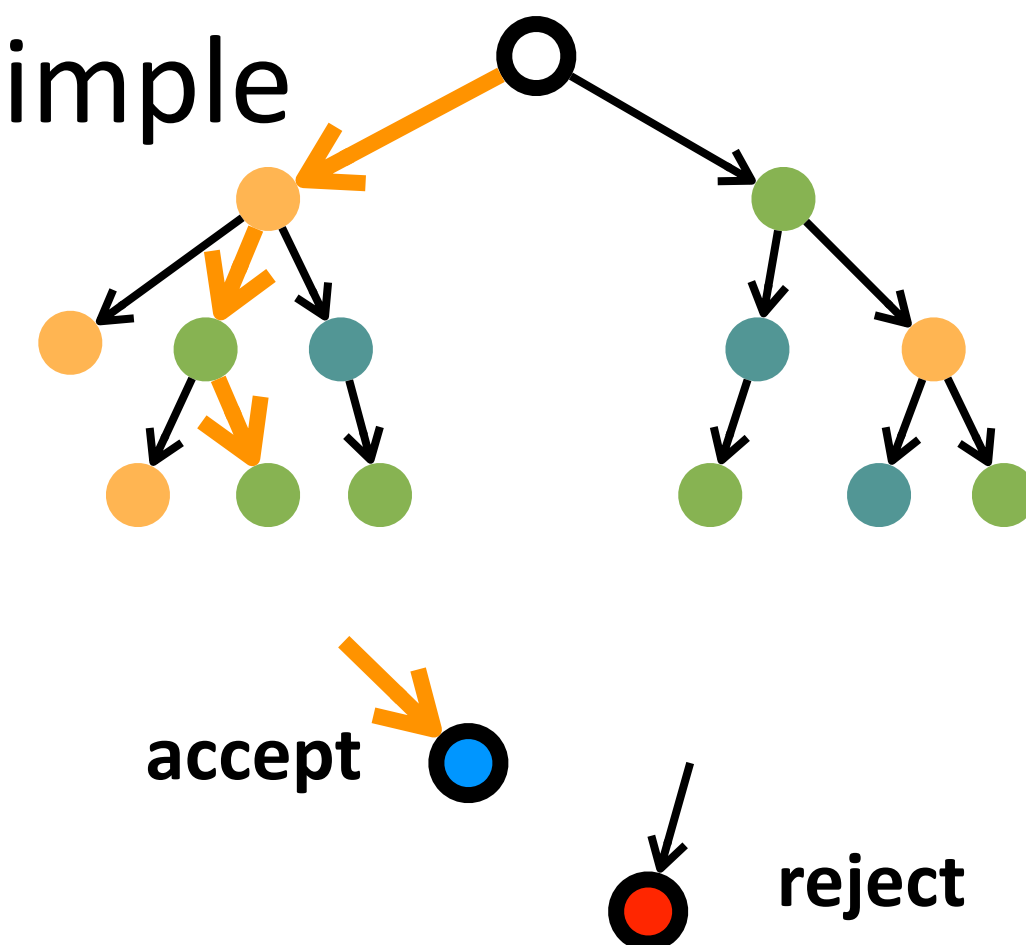
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A curved orange arrow originates from the word "hint" and points to the variable c in the set definition.

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hint

Is w in A ?

The diagram illustrates a 1D convolution operation. A horizontal sequence of boxes represents the input, with ellipses (...) at both ends. A green rectangular box highlights a segment of 10 boxes in the middle of the sequence. These 10 boxes contain the values: 1, 1, 0, 1, 0, #, 1, 1, 0, 1, 0. Below this highlighted segment, the label w is written in green, indicating that this segment represents the kernel w .

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hint

- c is called a **certificate** or **proof**, which is an additional information to verify that the string w is a member of A
- You don't need to worry about the time complexity for coming up with c
- Just assume there is an angel that can provide you any c you want for free



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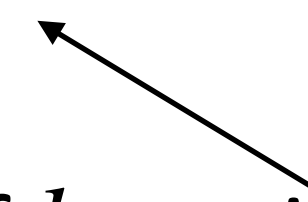
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A set of k vertices with edge
between every pair of vertices

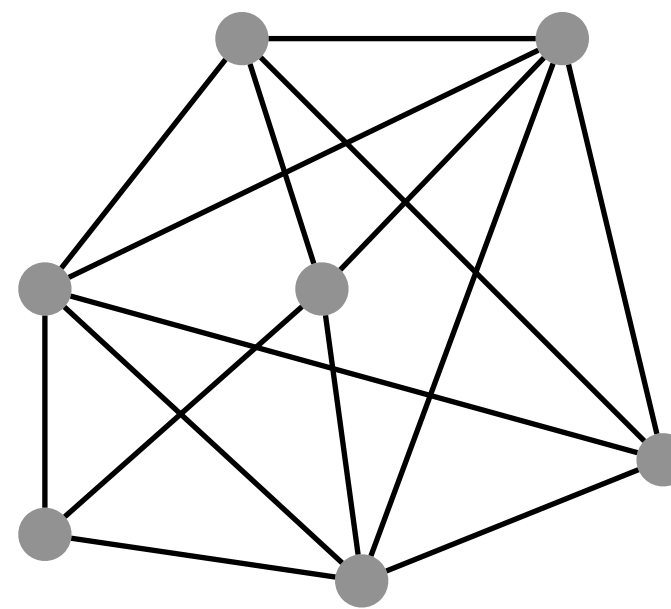


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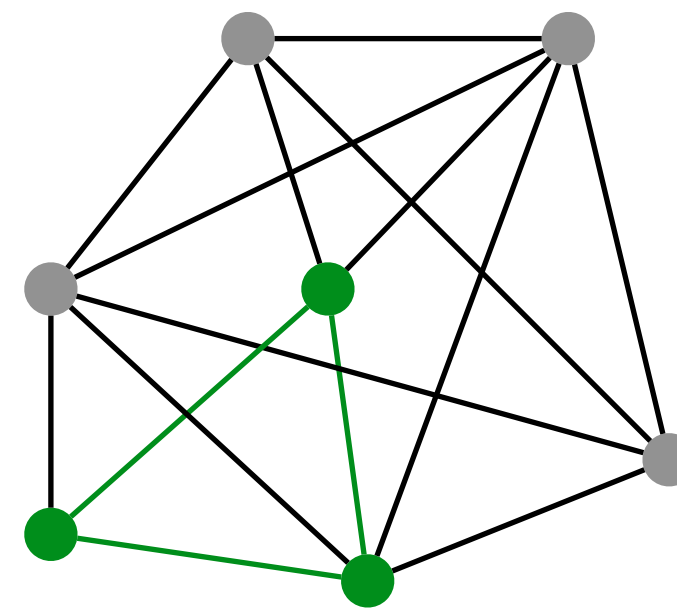


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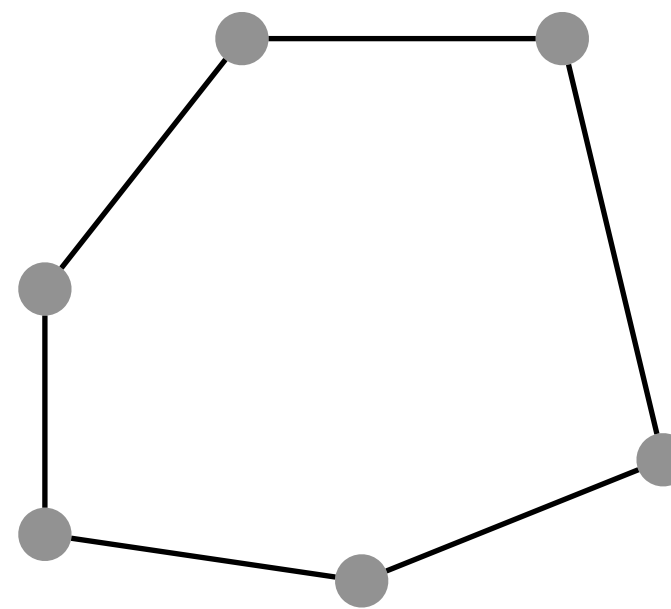
✓ $\langle G, 3 \rangle$ is a yes-instance

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✗ $\langle G, 3 \rangle$ is a no-instance

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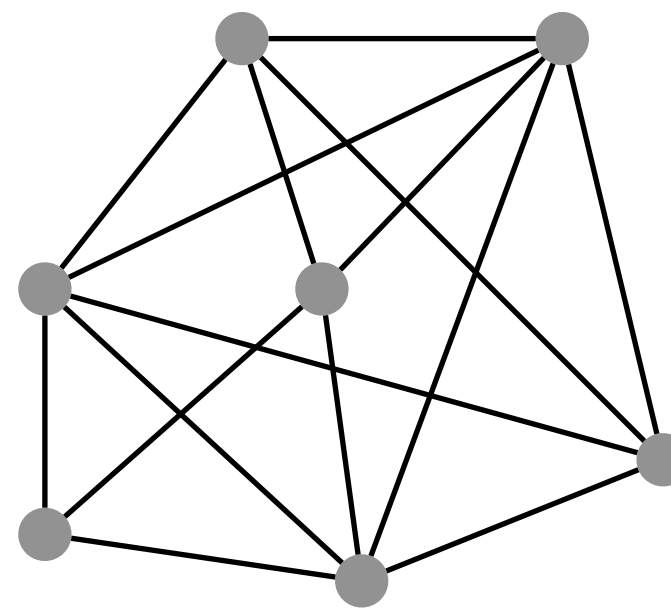
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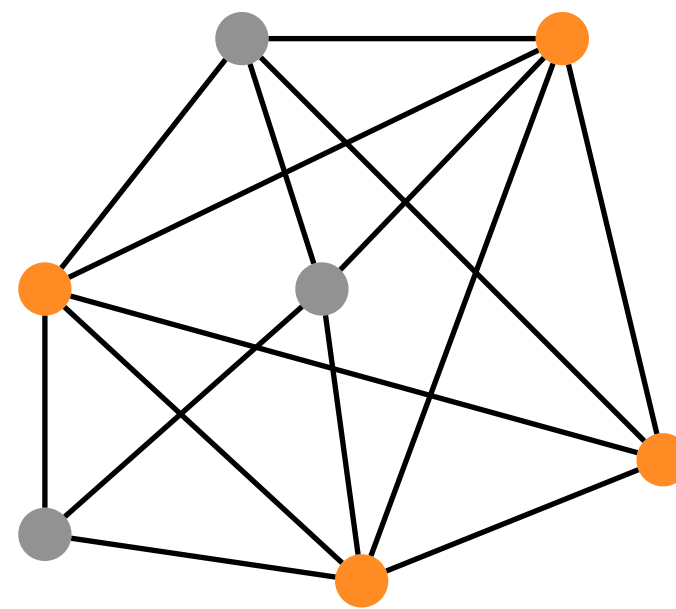


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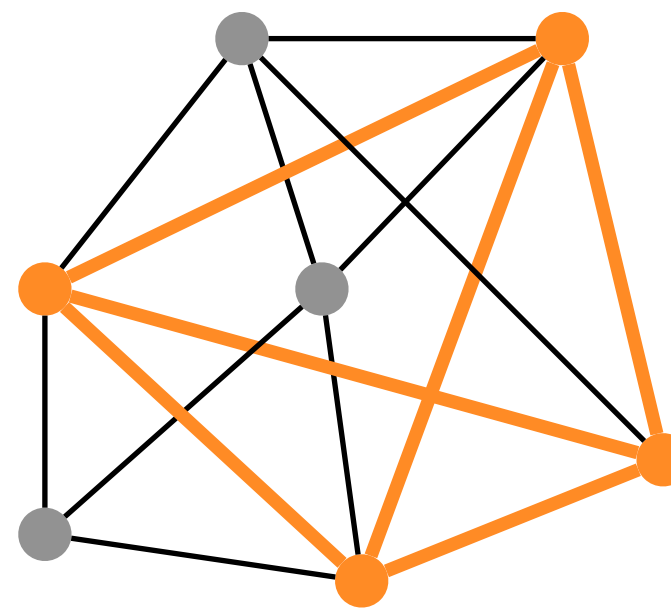


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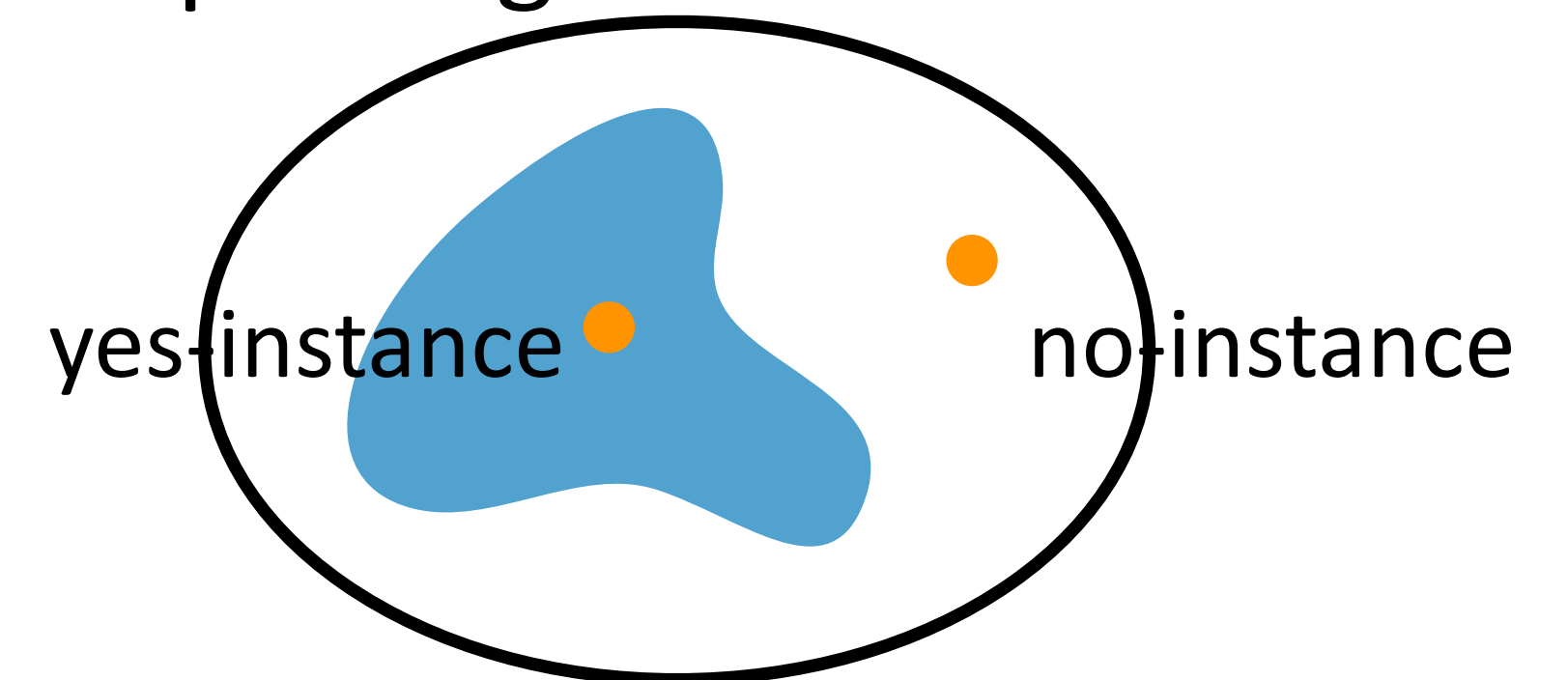
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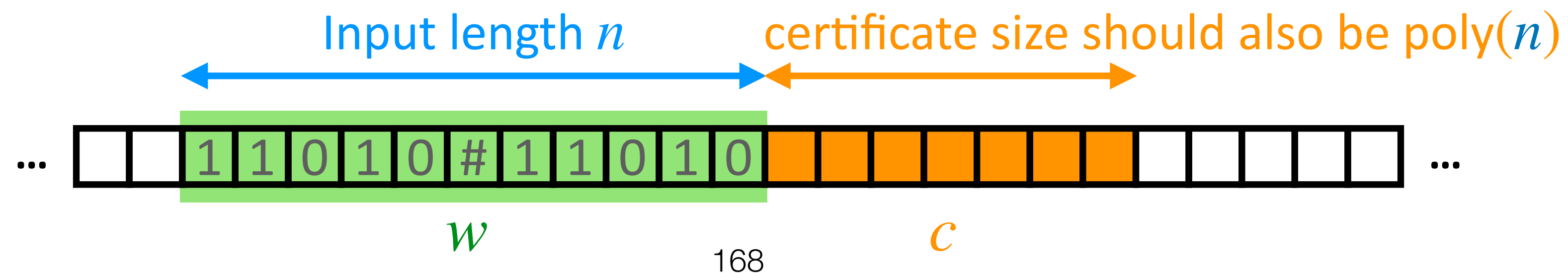
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 - A language A is **polynomial-time verifiable** if it has a polynomial time **verifier**

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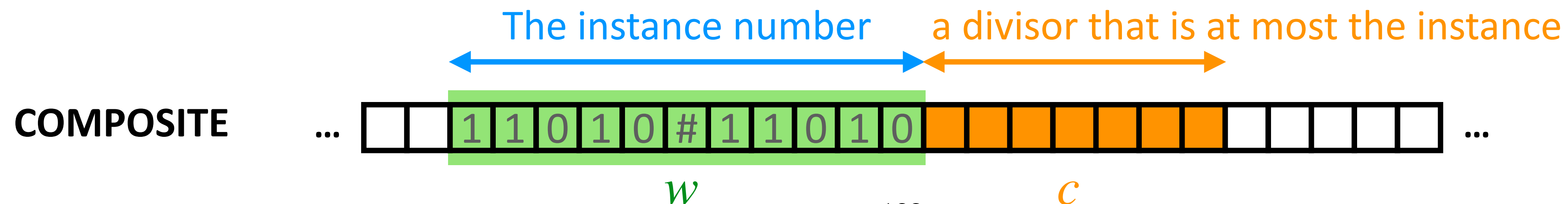


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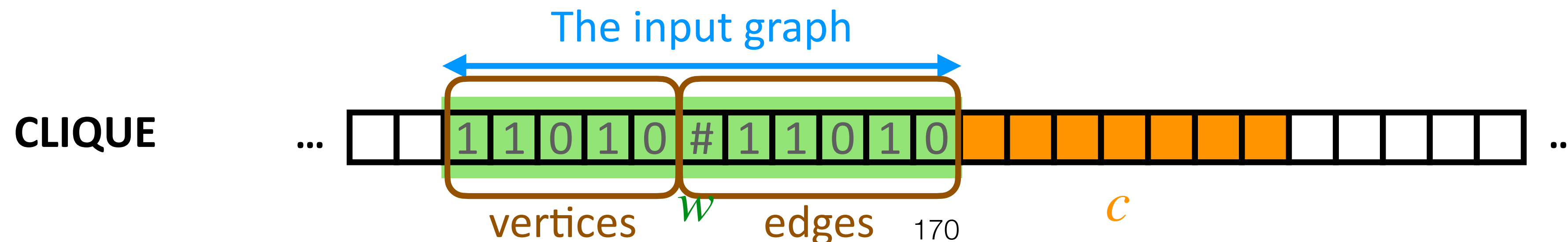


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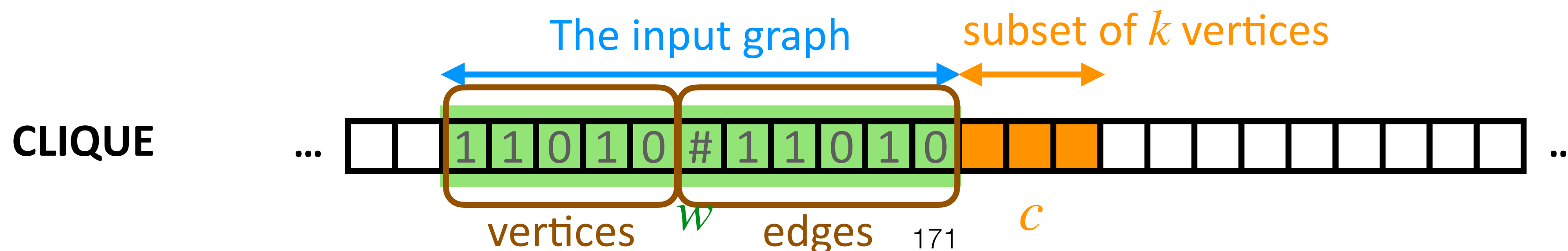


Polynomial Time Verifier

- Definition: A **verifier** for a language A is an algorithm V , where

$$A = \{w \mid V \text{ accepts } \langle w, c \rangle \text{ for some string } c\}.$$

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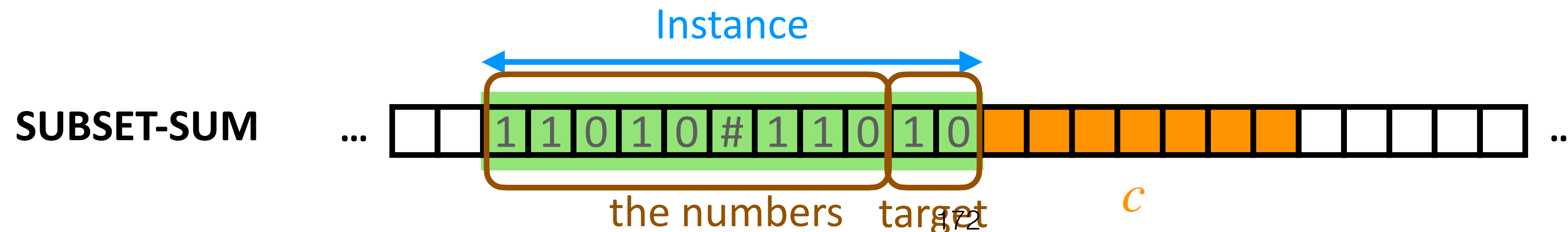


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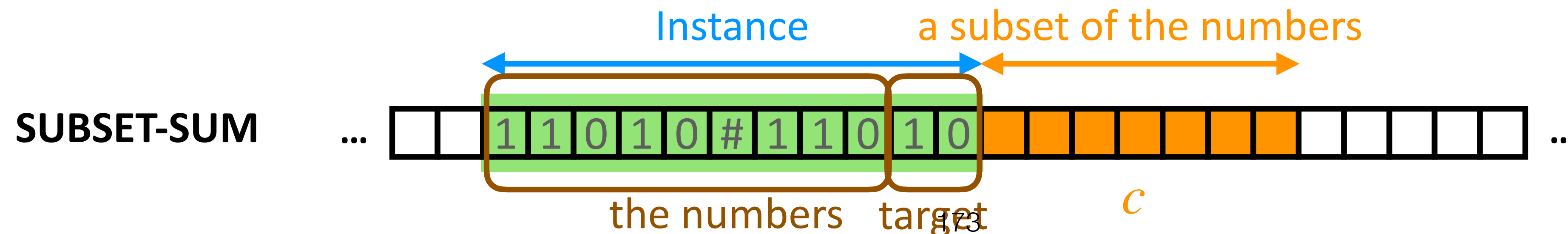


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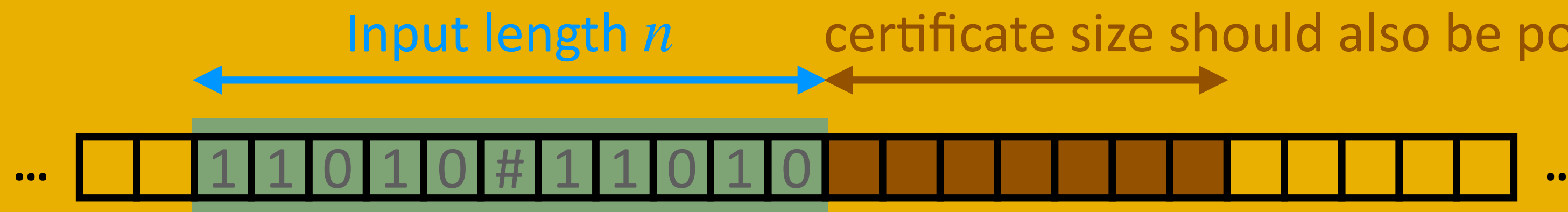
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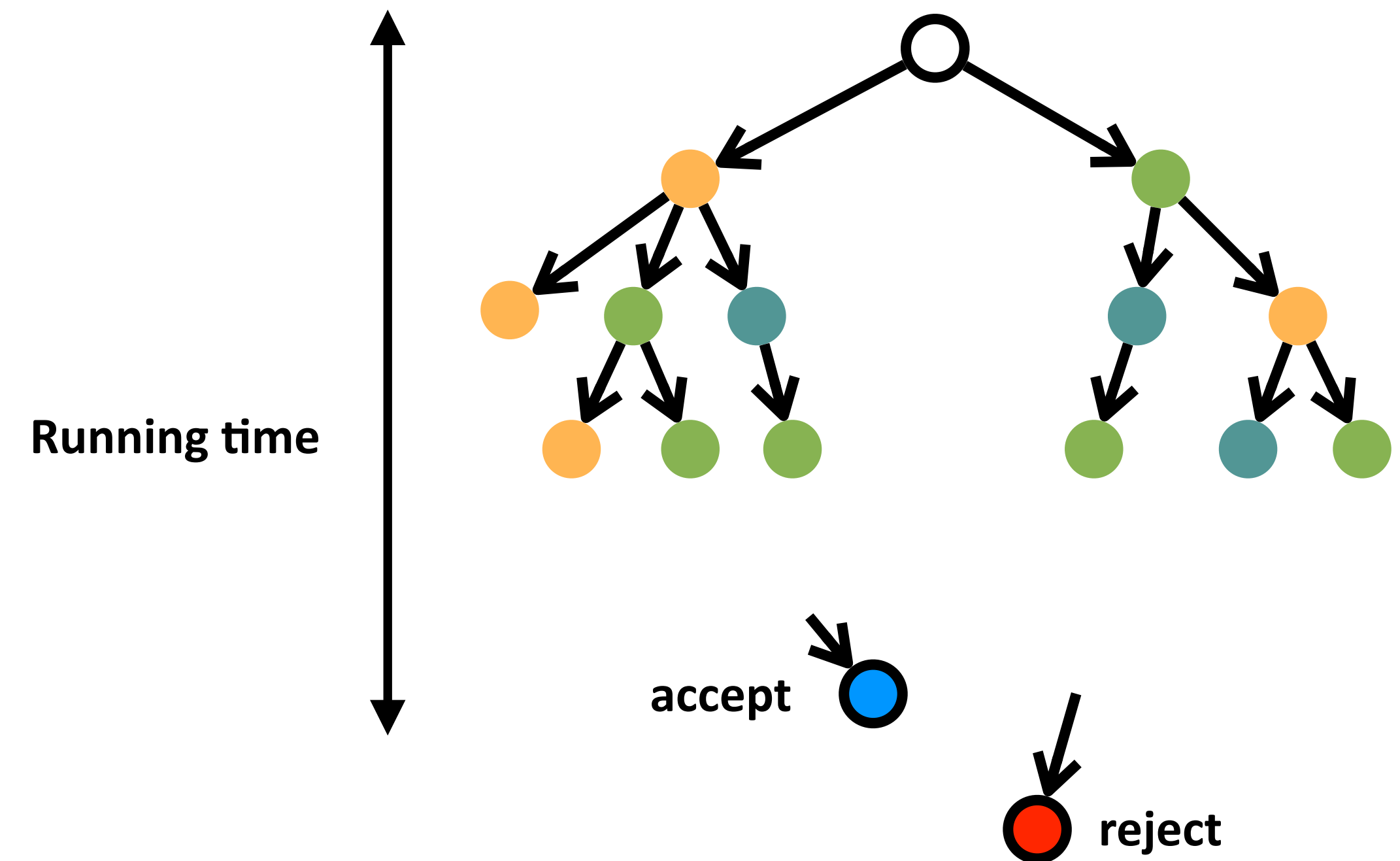
What Happened

- A language A is **verifiable** if for any of its yes-instances w , there exists a piece of hint (certificate) c such that using this hint c , one can be convinced that w is indeed a yes-instance of A
 - Only yes-instances have certificates
- **Polynomial-time verifiable**: the verification can be done in time of polynomial in input length
 - The hint size should also be polynomial
 - It does NOT mean that the hint c should be constructed within polynomial time!



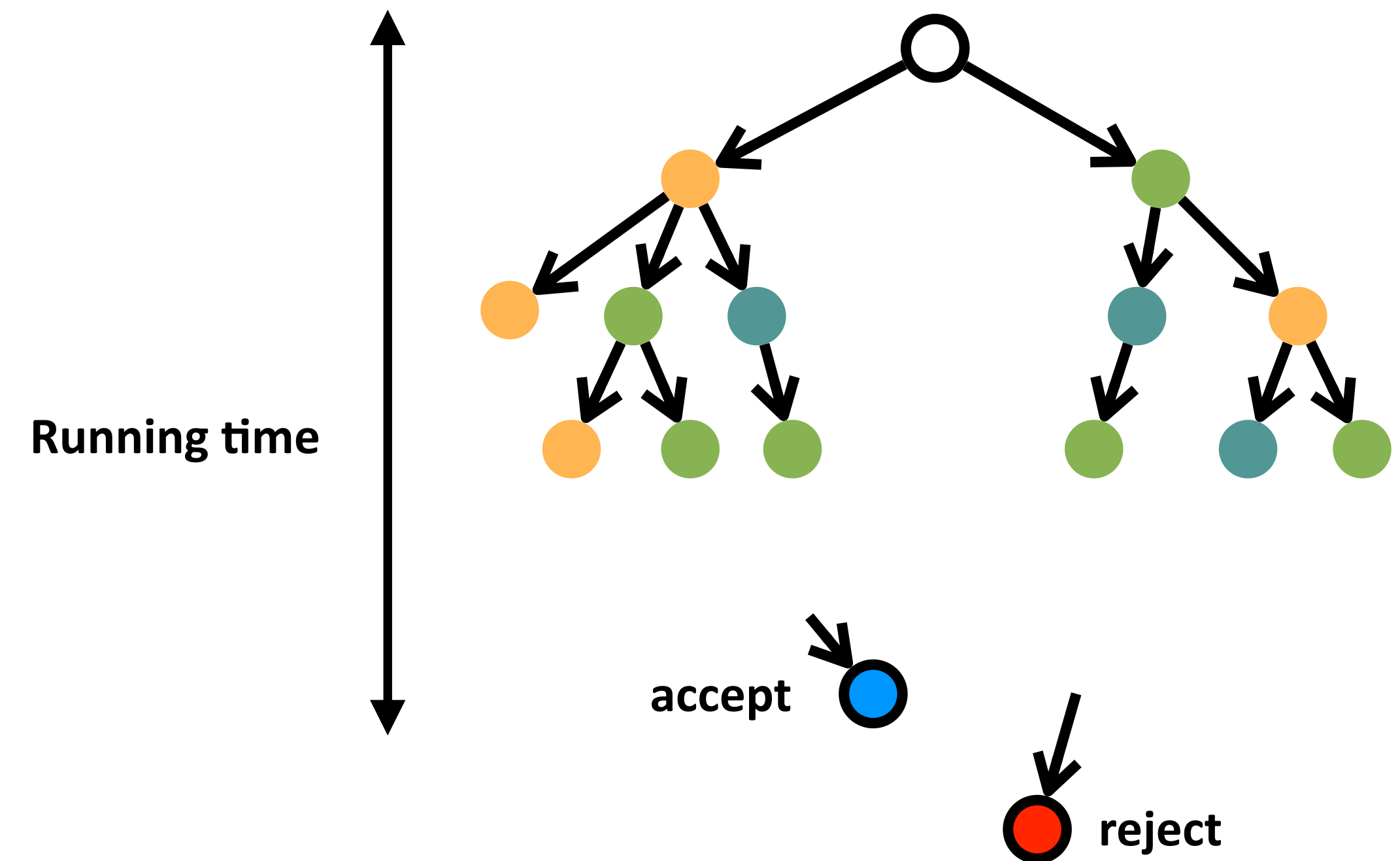
The Class NP — Alternative Definition

- Definition: **NP** is the class of languages that are accepted or rejected in polynomial time by a nondeterministic Turing machine.

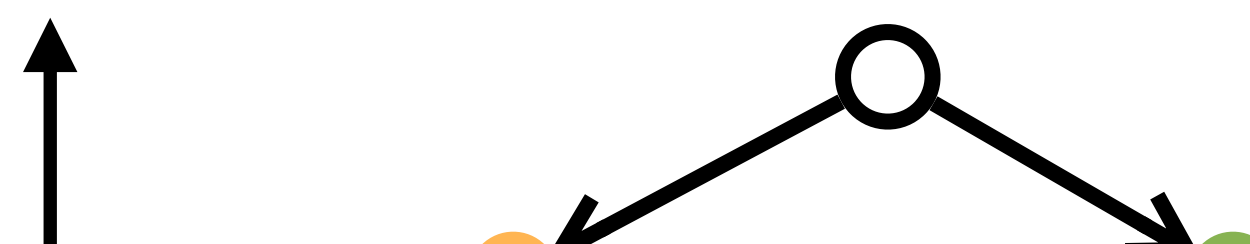


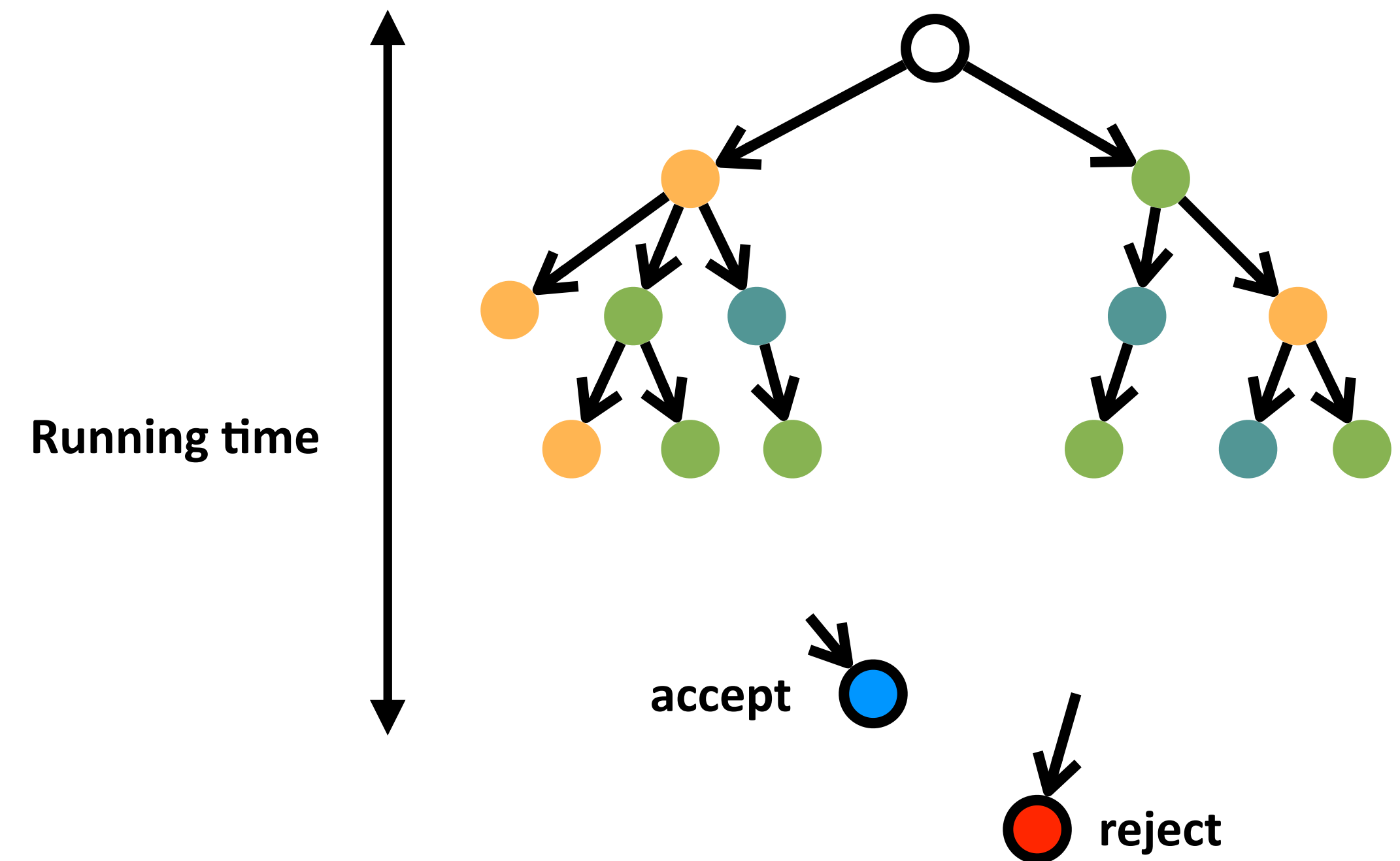
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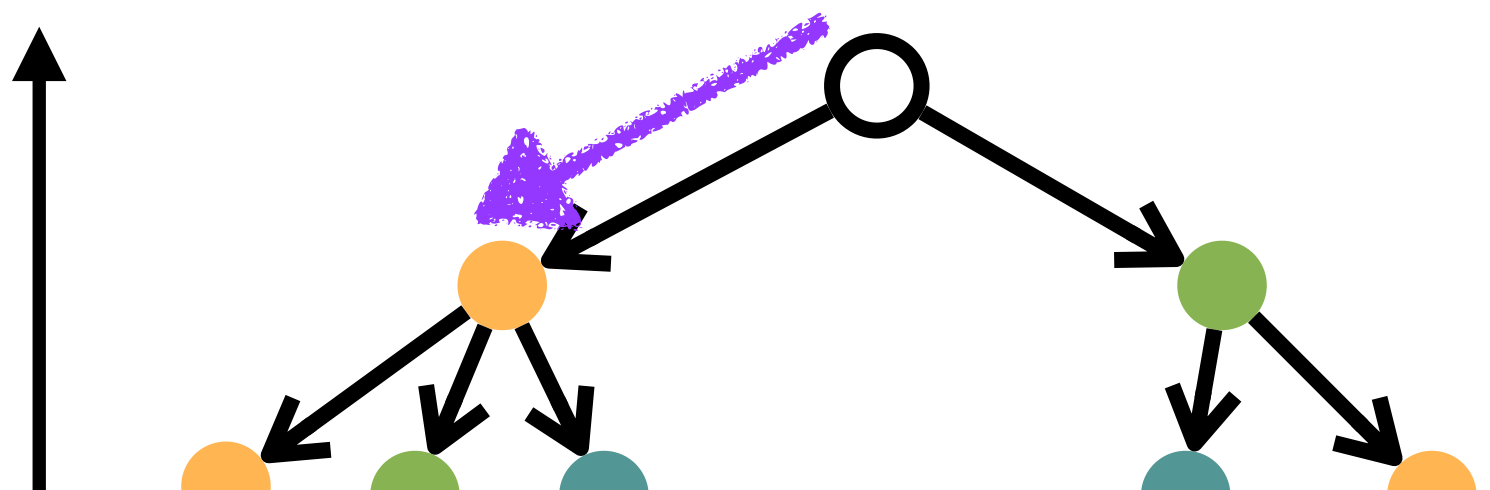


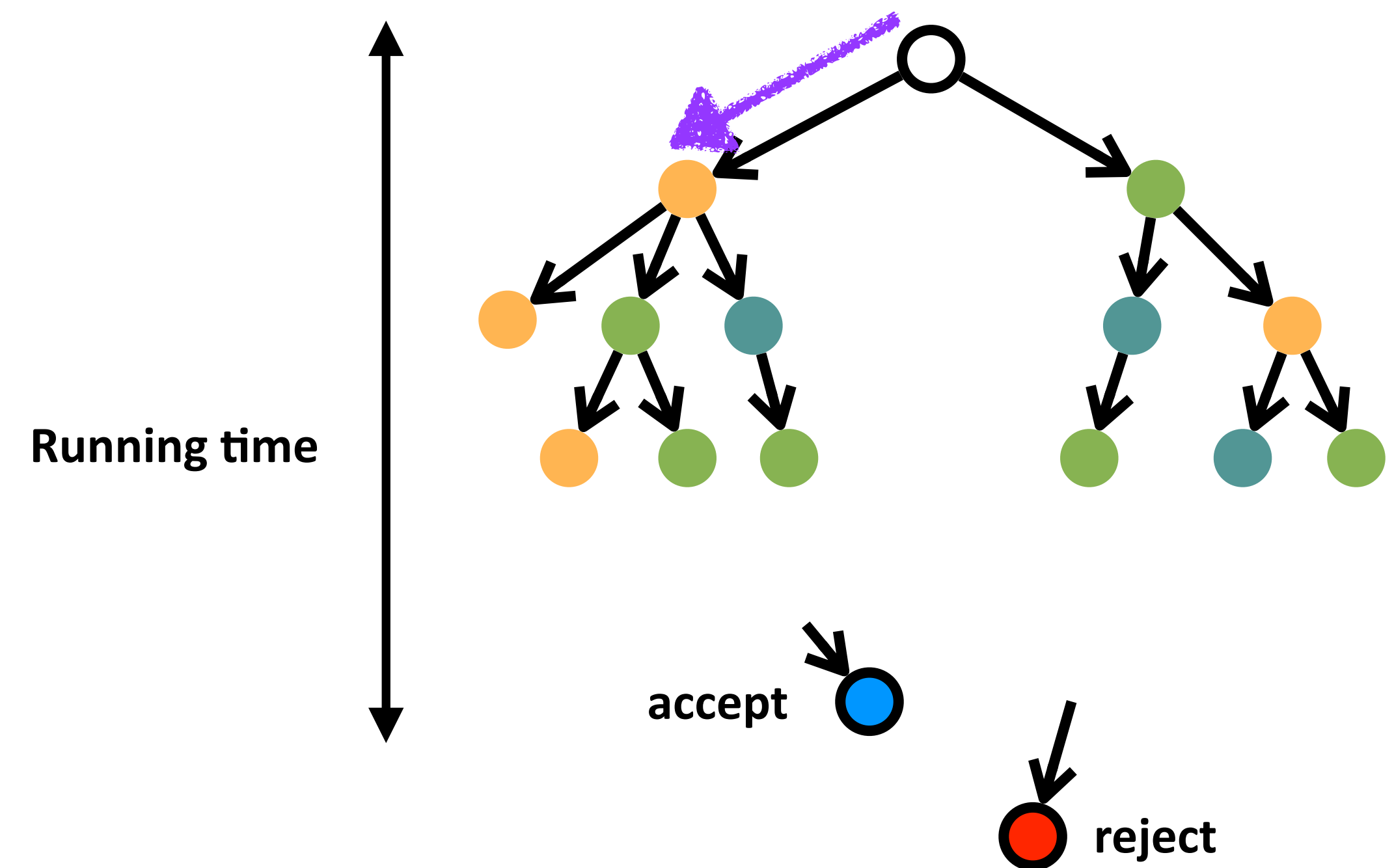
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- Definition: **NP** is the class of languages that are **verifiable** in polynomial time on a **deterministic Turing machine**.
 - Any non-deterministic Turing machine can be simulated by a deterministic Turing machine
- 
- ```
graph TD; A(()) --> B(()); A --> C(()); B --> D(()); C --> E(())
```

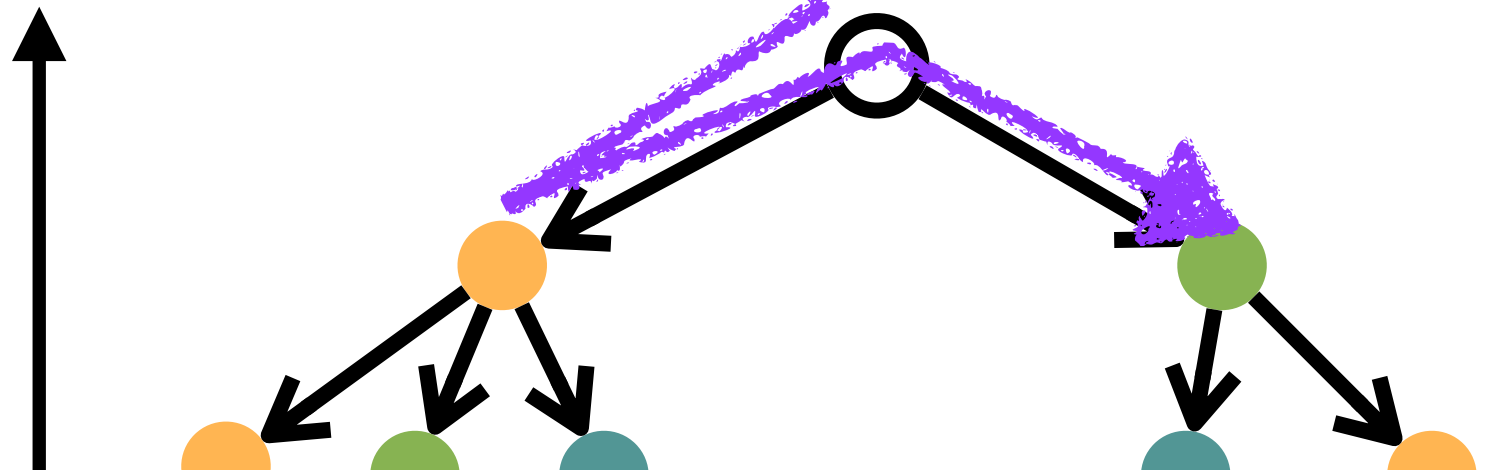


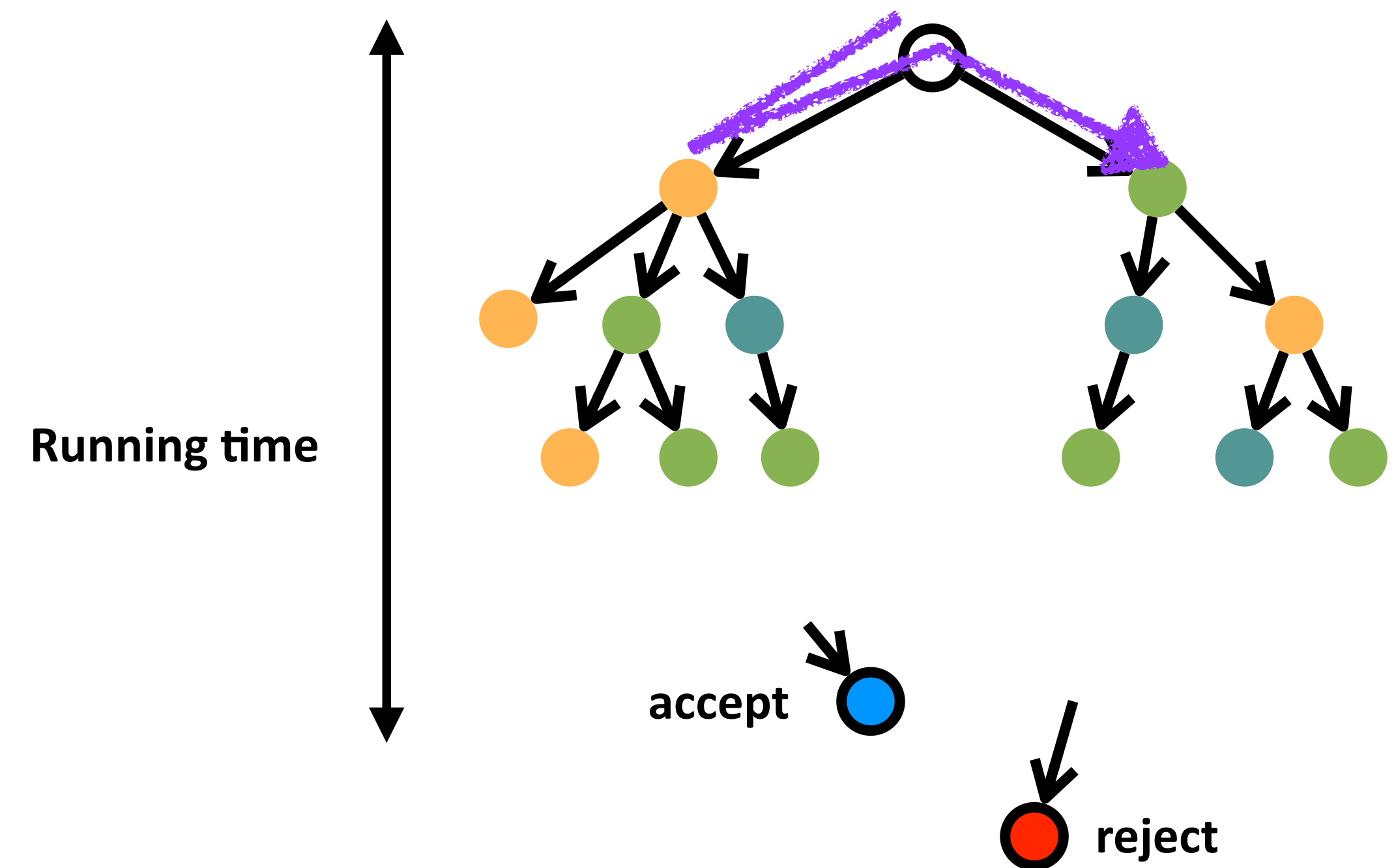
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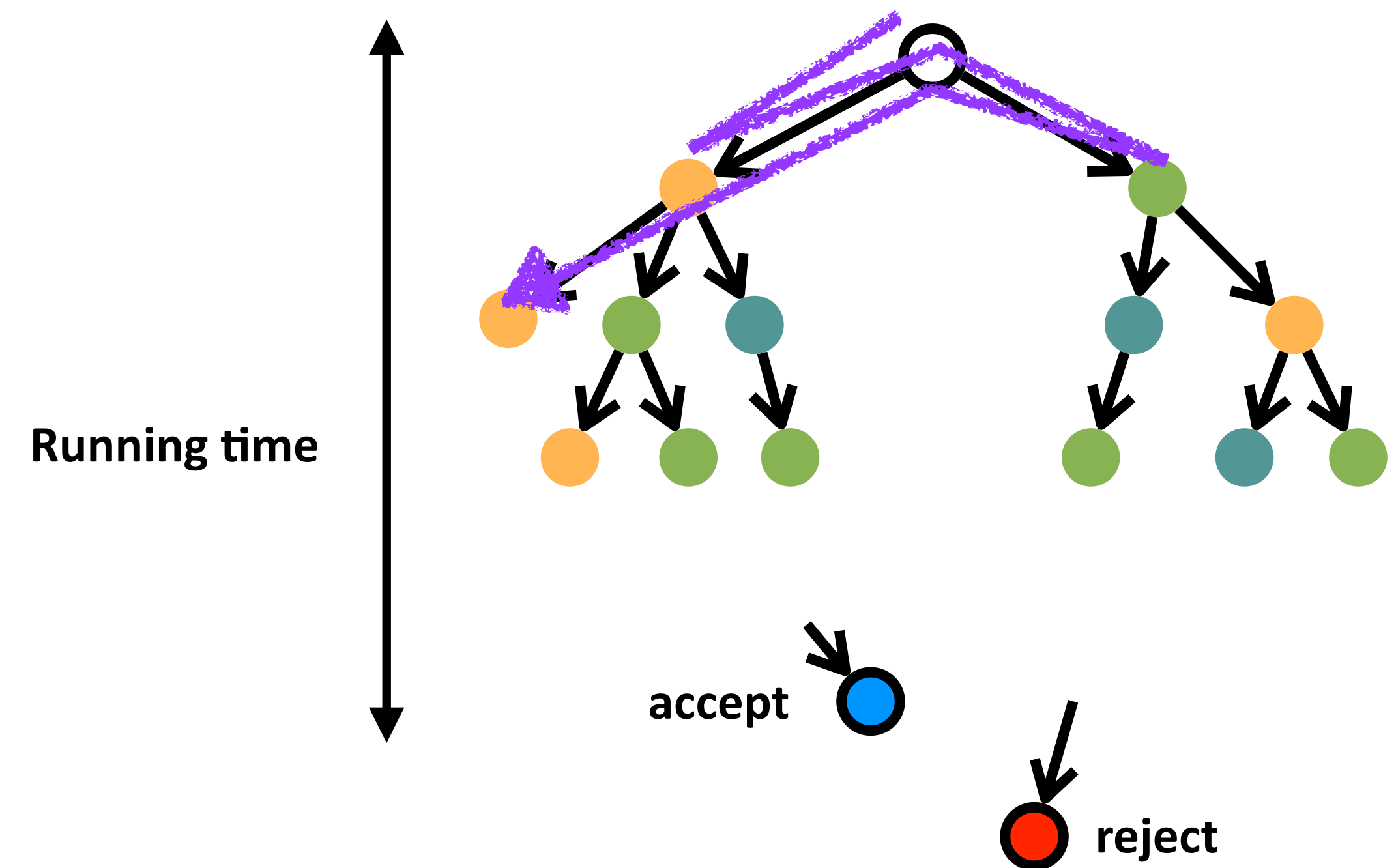
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- ```
graph TD; Root(( )) --> Orange1(( )); Root --> Green1(( )); Orange1 --> Orange2(( )); Orange1 --> Green2(( )); Orange1 --> Teal1(( )); Green1 --> Teal2(( )); Green1 --> Orange3(( ))
```

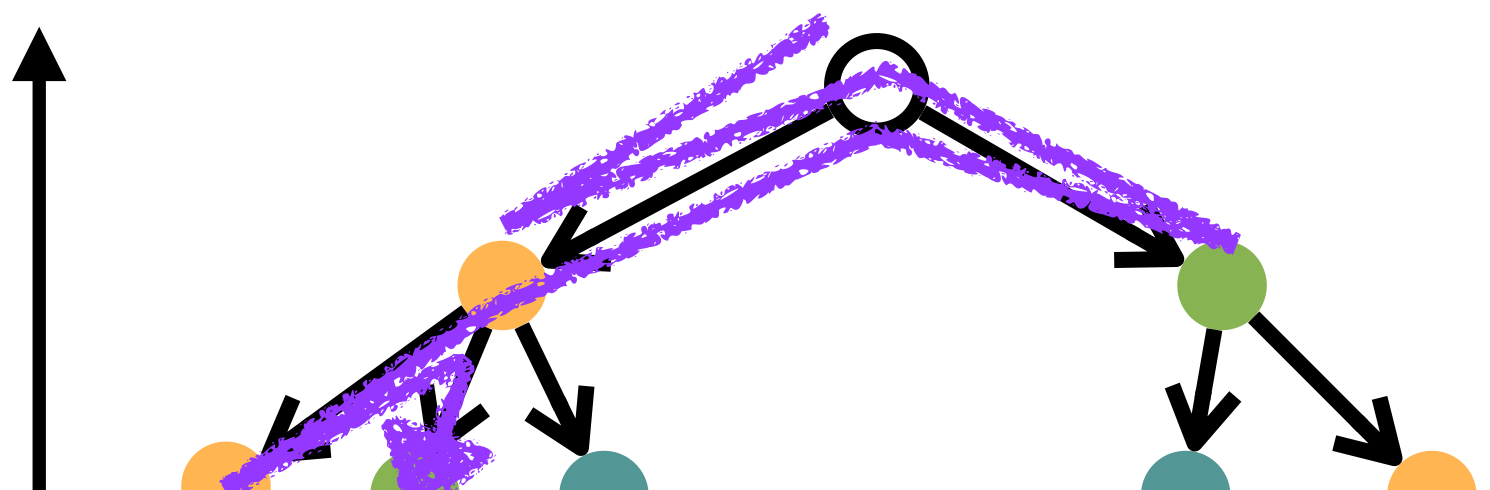


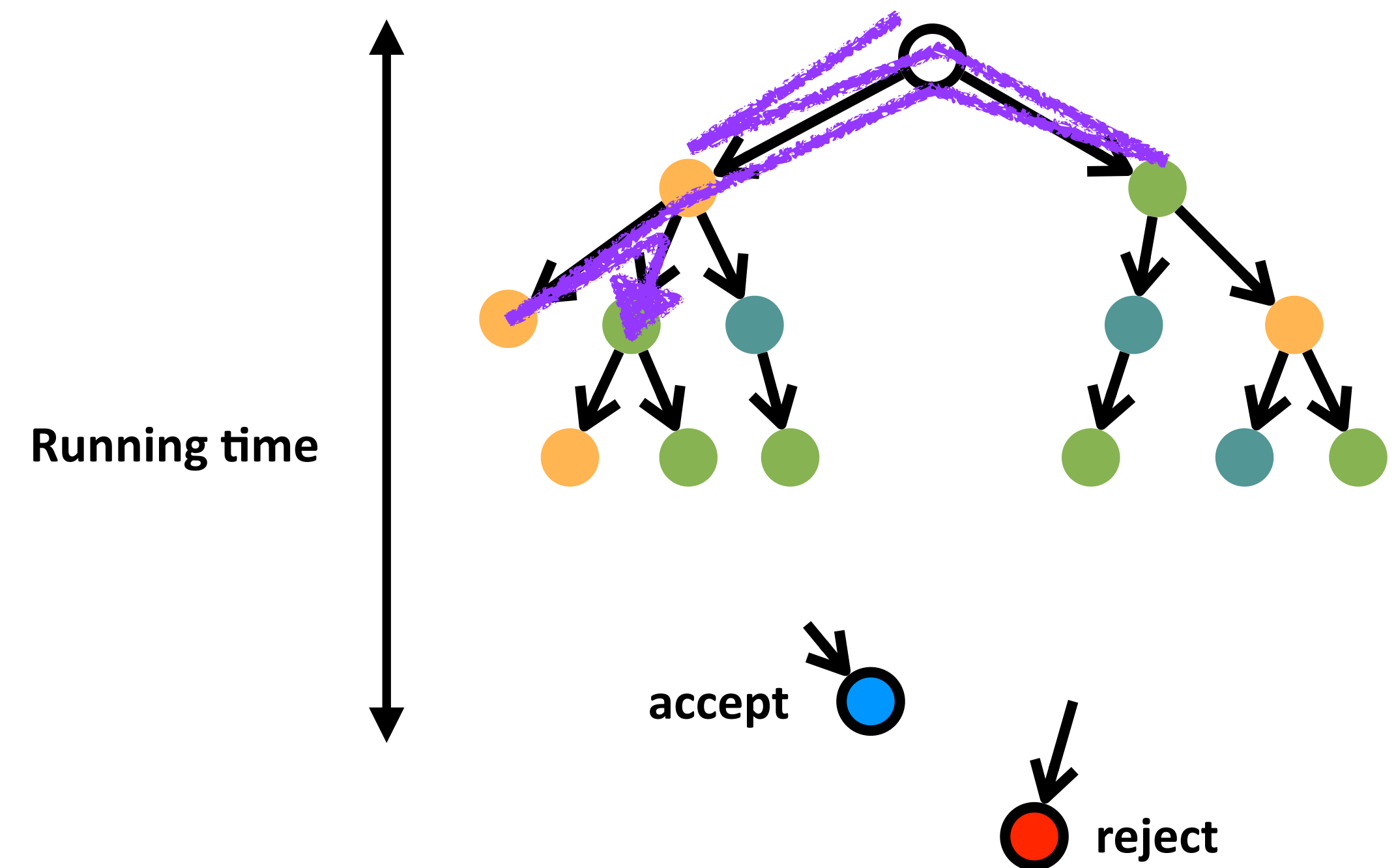
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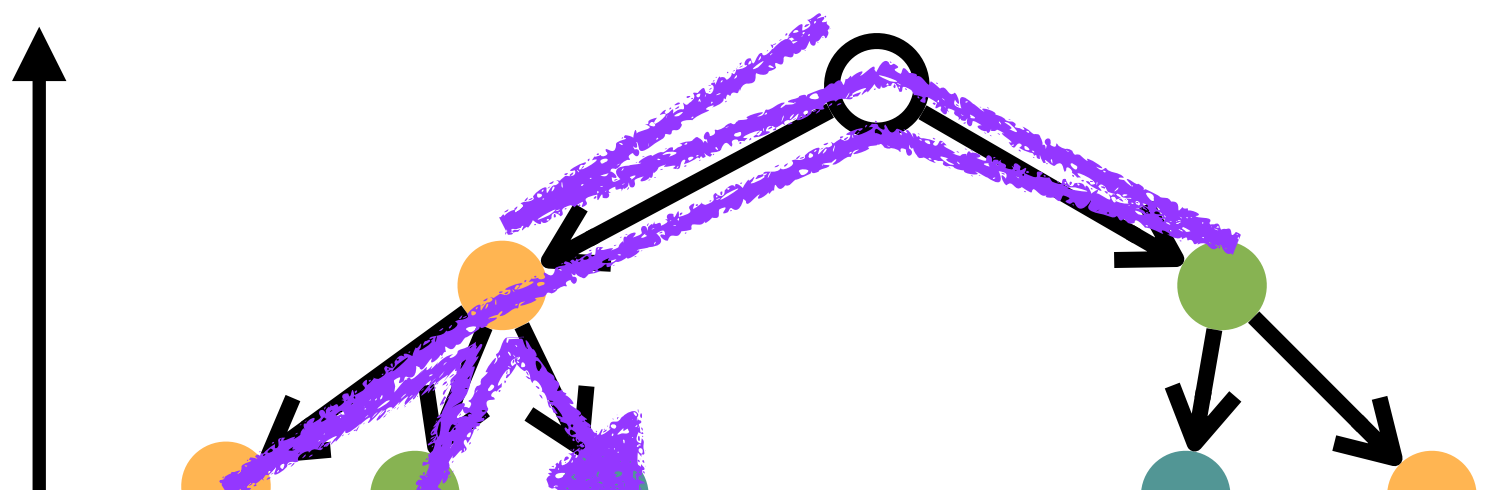


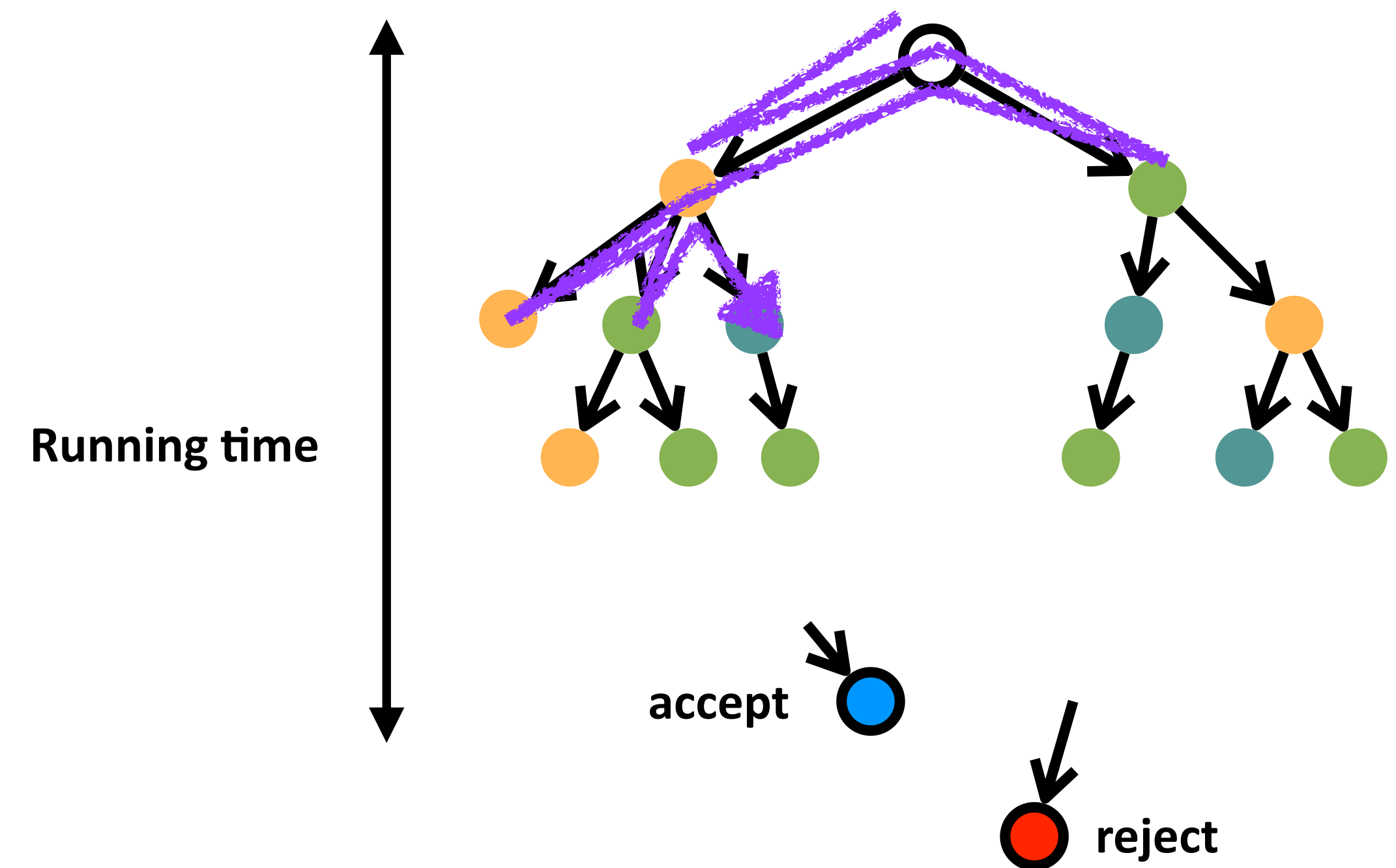
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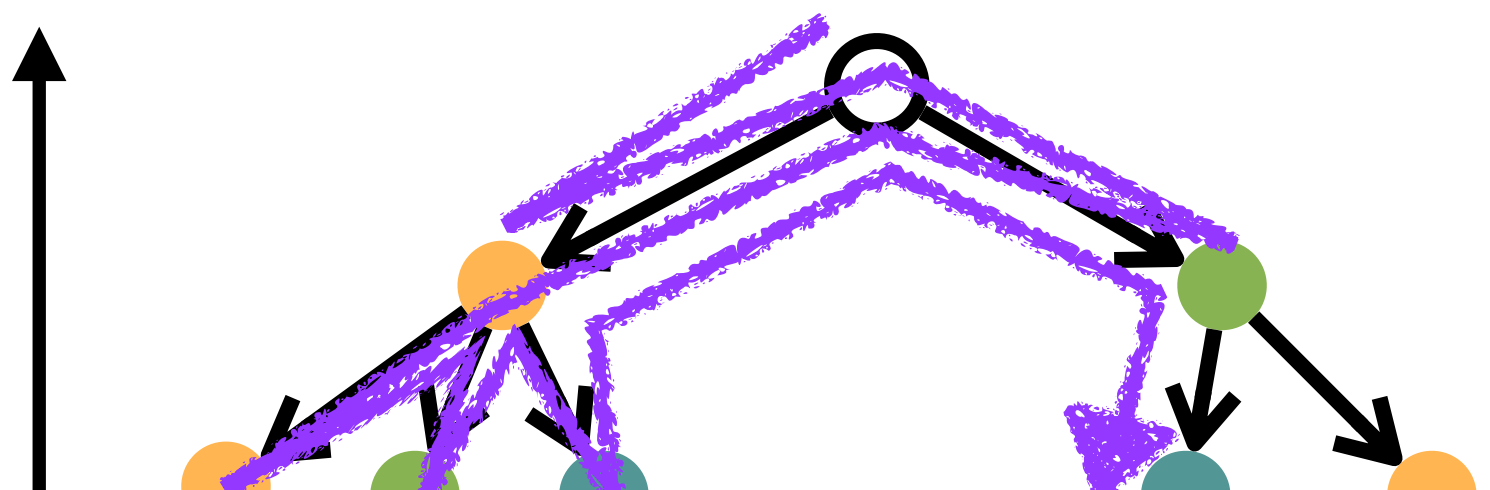


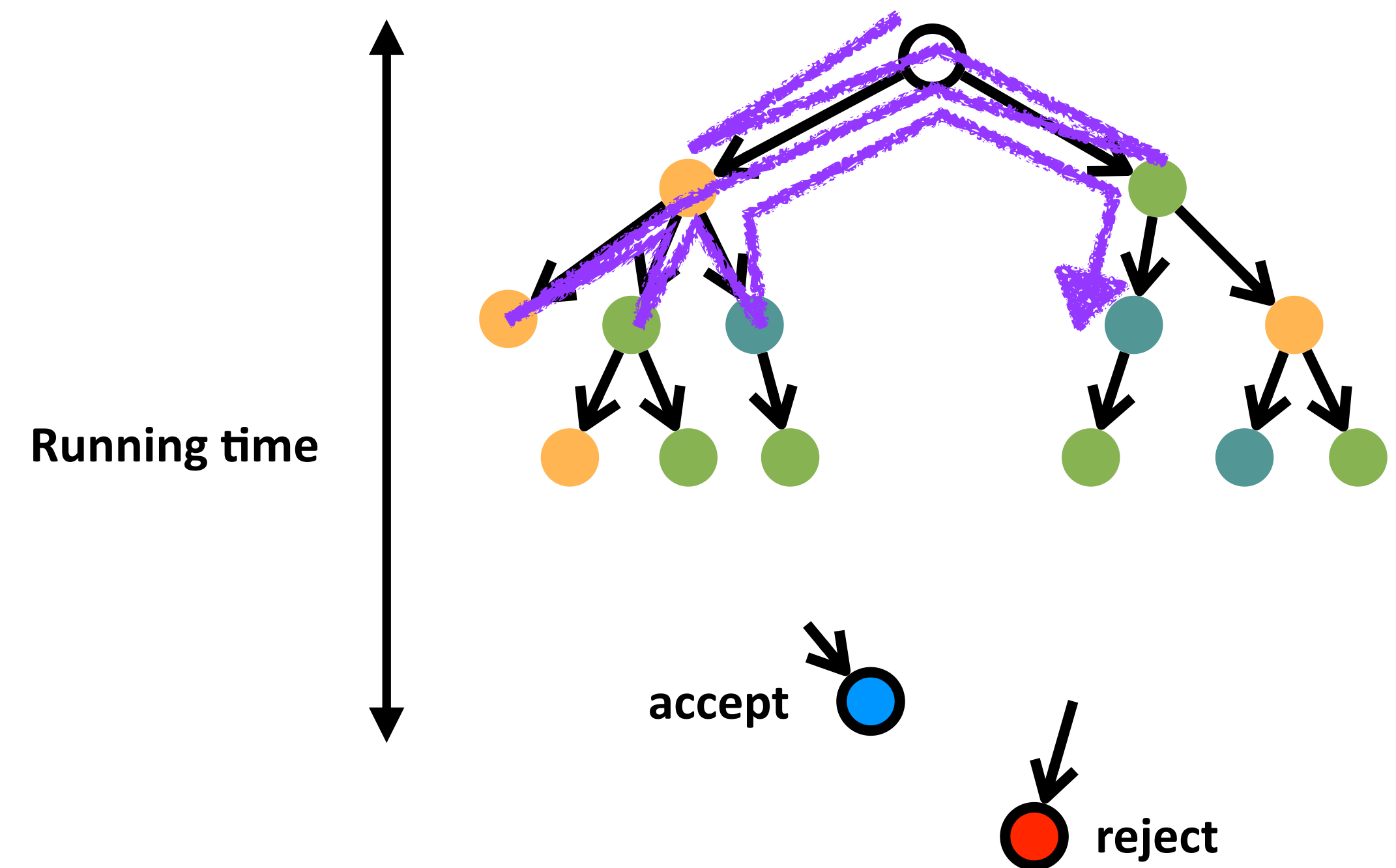
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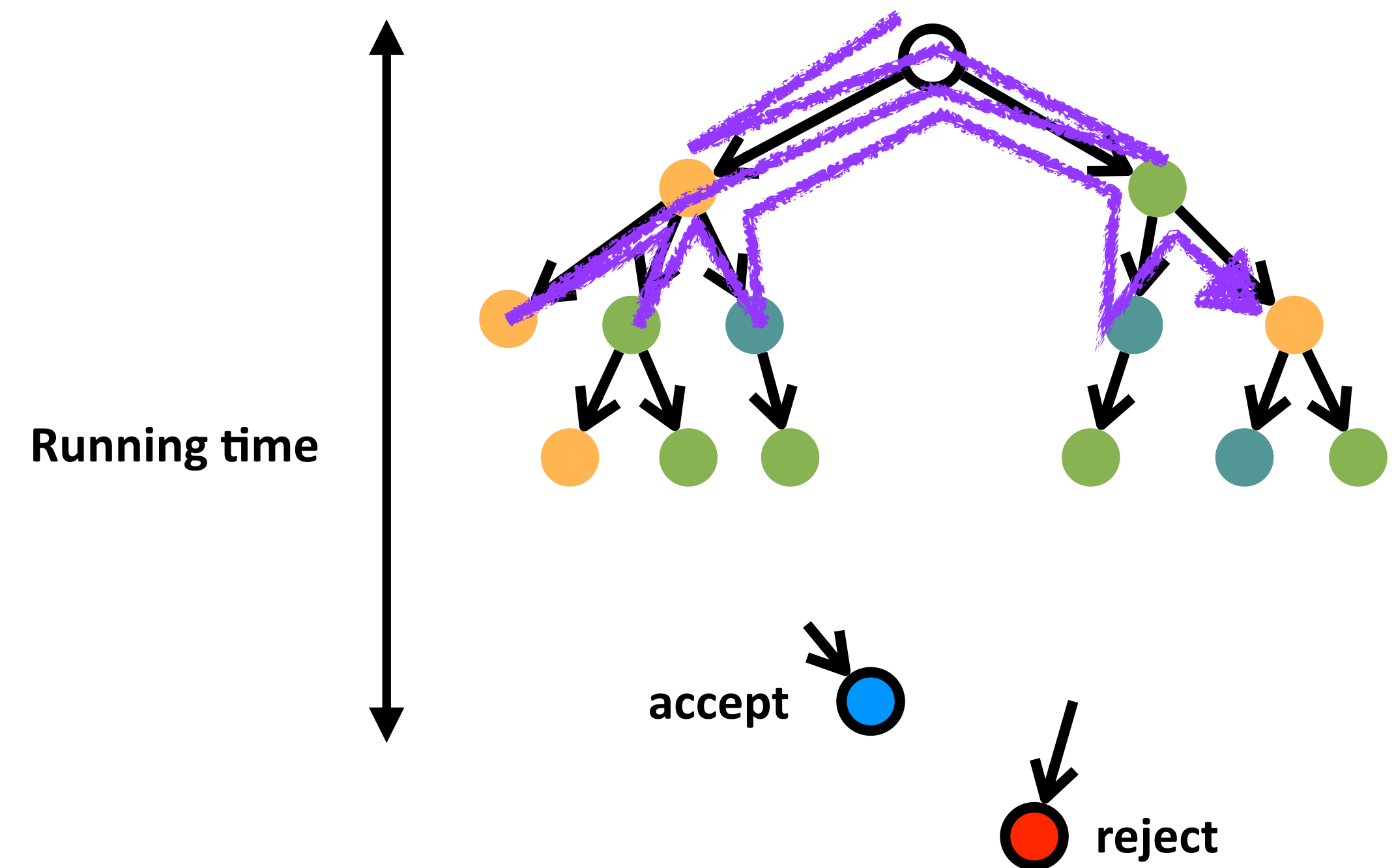
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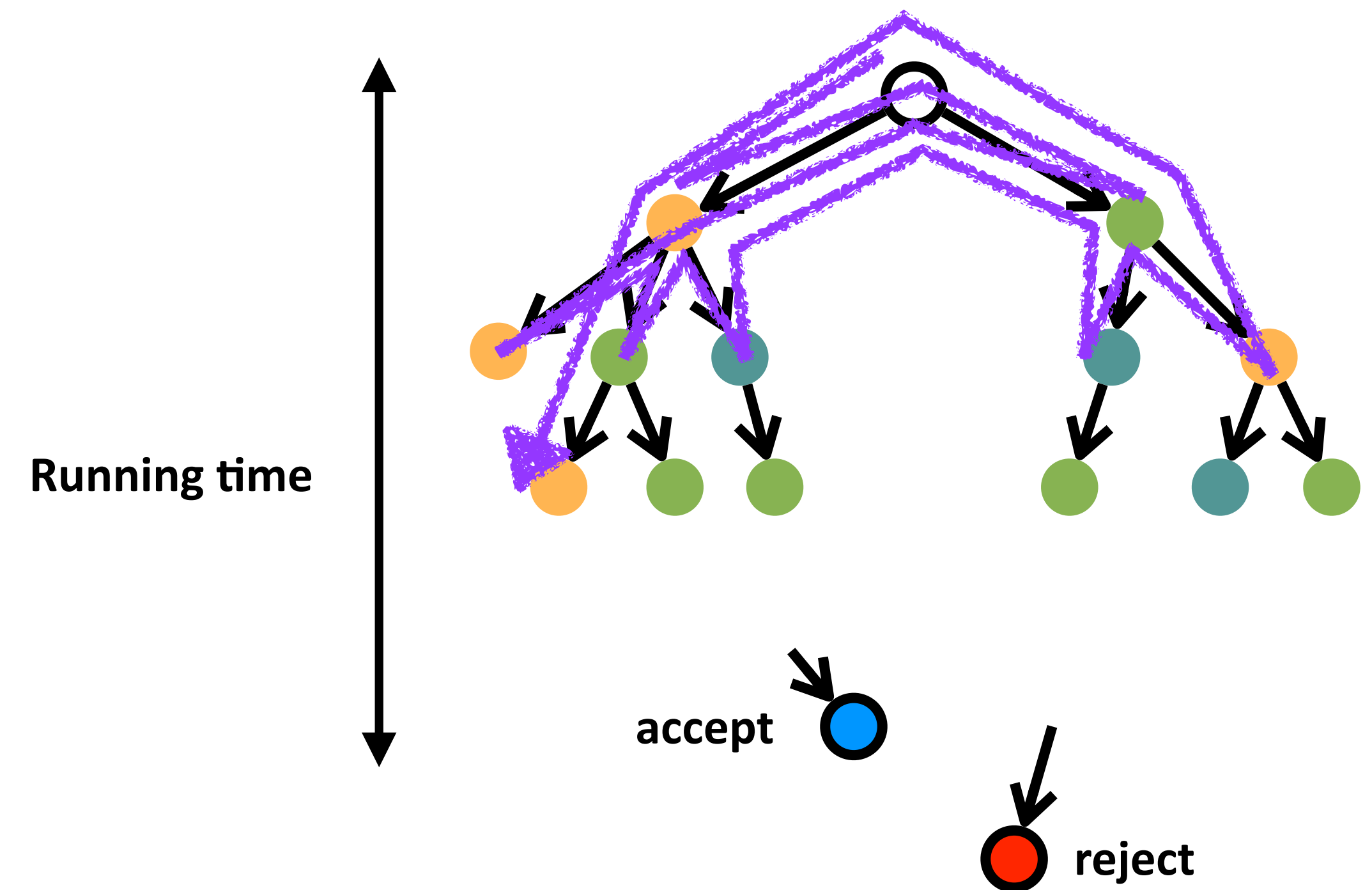
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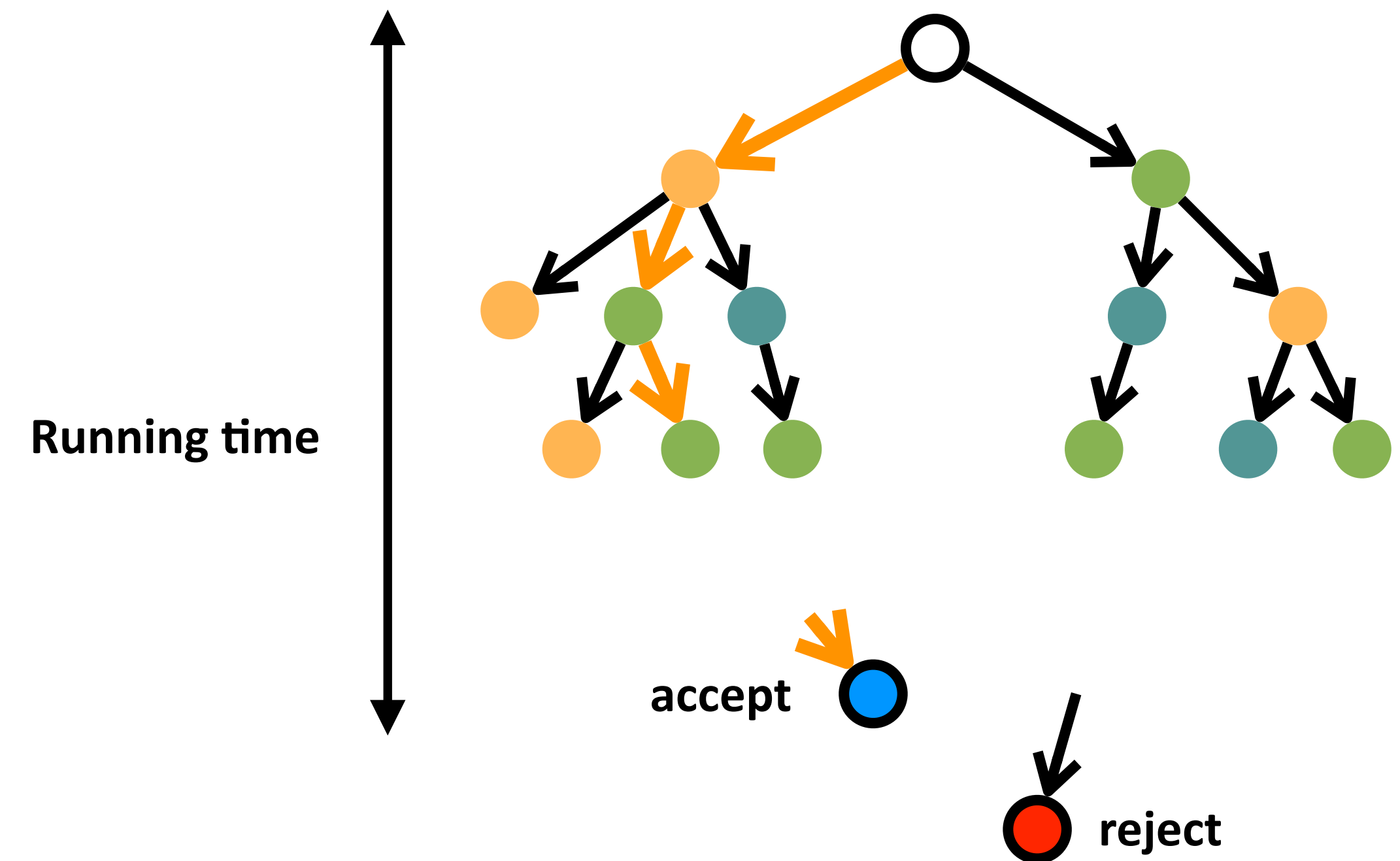
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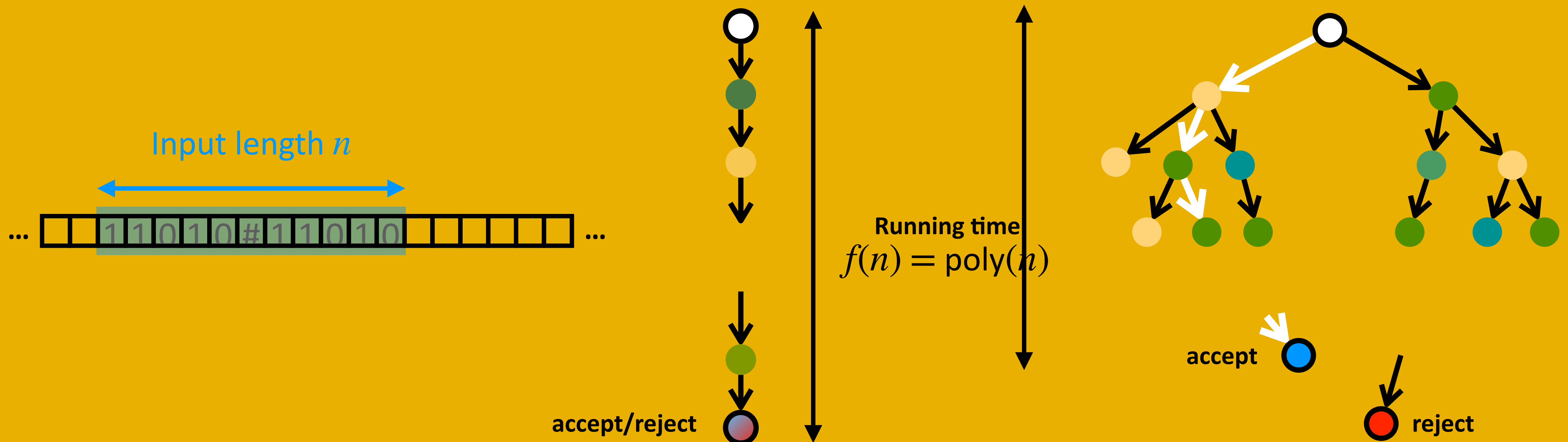
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 - Any non-deterministic Turing machine can be **simulated** by a deterministic Turing machine
 - It needs more than polynomial time
 - But if we know some **hint**, we know the path to an accept state with polynomial length
-
- Running time



What Happened

- The class **P** is the class of languages that are *accepted* or *rejected* in polynomial time by a deterministic Turing machine
- The class **NP** is the class of languages that can be *verified* in polynomial time by a deterministic Turing machine.



Prove Language L is in $\mathbf{P}$

- To prove that a language L is in $\mathbf{P}$, we need to:
 - Design a Turing machine M
 - Show that M correctly accepts or rejects all input
 - Show that M runs in polynomial time

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design a Turing machine $\equiv$ design an algorithm

Use Polynomial Time Verifier to Prove that A is in **NP**

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<Proof Idea>

1. Assume that there is a certificate c with size polynomial in the length of w
2. Design a verifier V on input $\langle w, c \rangle$ that **accepts** all $w \in A$ and **rejects** all $w \notin A$
3. Show that V runs in polynomial time (in the length of w)

CLIQUE is in NP

- **CLIQUE** = $\{\langle G, k \rangle \mid G \text{ is an undirected graph with a } k\text{-clique}\}$
 - A string c that encodes a clique with size k in G is a good certificate

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Let string c that encodes a clique with size k in G as a certificate

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<Proof>

Let string c that encodes a clique with size k in G as a certificate

$V =$ “On input $\langle \langle G, k \rangle, c \rangle$:

1. Test whether c is a set of k nodes in G
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3. If both 1 and 2 pass, *accept*; otherwise, *reject*.”

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Prove A is in **NP** $\Leftrightarrow$ Design a **polynomial time verifier** to decide A (with help from some c)

<Proof Idea>

1. Show that for any yes instance w , there is a polynomial-size certificate c .

2. Design a verifier V on input $\langle w, c \rangle$ that *accepts* all $w \in A$ and *rejects* all $w \notin A$

3. Show that V runs in polynomial time (in the length of w)

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- SUBSET-SUM = $\{ \langle S, t \rangle \mid S = \{x_1, \dots, x_k\} \text{ and for some } \{y_1, \dots, y_m\} \subseteq \{x_1, \dots, x_k\}, \text{ we have } \sum y_i = t \}$
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Step 1 takes at most linear time to scan through the input. Step 2 takes $|c| < |S|$ summations. Step 3 takes at most $|c|$ times of scanning through the input. Hence, V runs in polynomial time in the input length.

Boolean Formula

- Boolean formula: an expression involving **Boolean variables** and operations

- Example:

- $\phi = \bar{x} \wedge y \wedge z$

- $\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$

literals

- (Boolean) variables: x, y, z

- The Boolean variables can take on the values **TRUE** (1) and **FALSE** (0)

Boolean Formula

- Boolean formula: an expression involving **Boolean variables** and operations
 - Example:
 - $\phi = \underset{0}{\bar{x}} \wedge \underset{1}{y} \wedge \underset{1}{z}$
 - $\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$
 - (Boolean) variables: x, y, z
- The Boolean variables can take on the values **TRUE** (**1**) and **FALSE** (**0**)

Boolean Formula

- Boolean formula: an expression involving **Boolean variables** and operations
 - Example:
 - $\phi = \bar{x} \wedge y \wedge z$ $x = \text{TRUE}, y = \text{TRUE}, z = \text{TRUE}$
 - $\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$
 - (Boolean) variables: x, y, z
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Boolean Formula

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 - Example:
 - $\phi = \bar{x} \wedge y \wedge z$
 0 1 1
 - $\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$
 - (Boolean) variables: x, y, z
- The Boolean variables can take on the values **TRUE** (1) and **FALSE** (0)

$$x = \text{TRUE}, y = \text{TRUE}, z = \text{TRUE}$$

Boolean Formula

- Boolean formula: an expression involving **Boolean variables** and operations
 - Example:
 - $\phi = \underset{0}{\bar{x}} \wedge \underset{1}{y} \wedge \underset{1}{z} = \text{FALSE}$ $x = \text{TRUE}, y = \text{TRUE}, z = \text{TRUE}$
 - $\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$
 - (Boolean) variables: x, y, z
- The Boolean variables can take on the values **TRUE** (**1**) and **FALSE** (**0**)

Boolean Formula

- Boolean formula: an expression involving **Boolean variables** and operations
 - Example:
 - $\phi = \bar{x} \wedge y \wedge z$
 - $\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$ $x = \text{TRUE}, y = \text{TRUE}, z = \text{FALSE}$
 - (Boolean) variables: x, y, z
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Boolean Formula

- Boolean formula: an expression involving **Boolean variables** and operations
 - Example:
 - $\phi = \bar{x} \wedge y \wedge z$
 - $\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$
 $\begin{matrix} 0 & 1 & 1 & 1 \end{matrix}$
 - (Boolean) variables: x, y, z
- The Boolean variables can take on the values **TRUE** (**1**) and **FALSE** (**0**)

$x = \text{TRUE}, y = \text{TRUE}, z = \text{FALSE}$

Boolean Formula

- Boolean formula: an expression involving **Boolean variables** and operations
 - Example:
 - $\phi = \bar{x} \wedge y \wedge z$
 - $\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z}) = \text{FALSE}$ $x = \text{TRUE}, y = \text{TRUE}, z = \text{FALSE}$

$\begin{matrix} 0 & 1 & 1 & 1 \end{matrix}$

$\begin{matrix} x & y & z & \end{matrix}$
 - (Boolean) variables: x, y, z- The Boolean variables can take on the values **TRUE** (**1**) and **FALSE** (**0**)

Boolean Formula

- Boolean formula: an expression involving **Boolean variables** and operations
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 - $\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$
 - (Boolean) variables: x, y, z
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- A Boolean formula is **satisfiable** if some **assignment** of *TRUEs* and *FALSEs* to the **variables** make the formula true

Boolean Formula

- Boolean formula: an expression involving **Boolean variables** and operations
 - Example:
 - $\phi = \bar{x} \wedge y \wedge z$ $x = \text{FALSE}, y = \text{TRUE}, z = \text{TRUE}$
 - $\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$
 - (Boolean) variables: x, y, z
 - The Boolean variables can take on the values **TRUE** (1) and **FALSE** (0)
 - A Boolean formula is **satisfiable** if some **assignment** of *TRUEs* and *FALSEs* to the **variables** make the formula true

Boolean Formula

- Boolean formula: an expression involving **Boolean variables** and operations
 - Example:
 - $\phi = \bar{x} \wedge y \wedge z$ $x = \text{FALSE}, y = \text{TRUE}, z = \text{TRUE}$
 - $\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$
 - (Boolean) variables: x, y, z
 - The Boolean variables can take on the values **TRUE** (1) and **FALSE** (0)
 - A Boolean formula is **satisfiable** if some **assignment** of *TRUEs* and *FALSEs* to the **variables** make the formula true
 - $\text{SAT} = \{ \langle \phi \rangle \mid \phi \text{ is a satisfiable Boolean formula} \}$

Boolean Formula

- Boolean formula: an expression involving **Boolean variables** and operations
 - Example:
 - $\phi = \bar{x} \wedge y \wedge z$ $x = \text{FALSE}, y = \text{TRUE}, z = \text{TRUE}$  yes-instance
 - $\phi = (\bar{x} \wedge y) \vee (x \wedge \bar{z})$  no-instance
 - (Boolean) variables: x, y, z
- The Boolean variables can take on the values **TRUE** (1) and **FALSE** (0)
- A Boolean formula is **satisfiable** if some **assignment** of *TRUEs* and *FALSEs* to the **variables** make the formula true
- $\text{SAT} = \{ \langle \phi \rangle \mid \phi \text{ is a satisfiable Boolean formula} \}$

SAT is in NP

- $SAT = \{ \langle \phi \rangle \mid \phi \text{ is a satisfiable Boolean formula} \}$
- Prove SAT is in $NP \Leftrightarrow$ Design a polynomial time verifier to decide SAT (with help from some c)

<Proof>

Let string c that encodes a truth assignment of variables in ϕ as a certificate

$V =$ “On input $\langle \phi, c \rangle$:

1. Replace the literals in ϕ by the truth assignments in c
2. Test whether the resulting ϕ is true
3. If 2 pass, *accept*; otherwise, *reject*.”

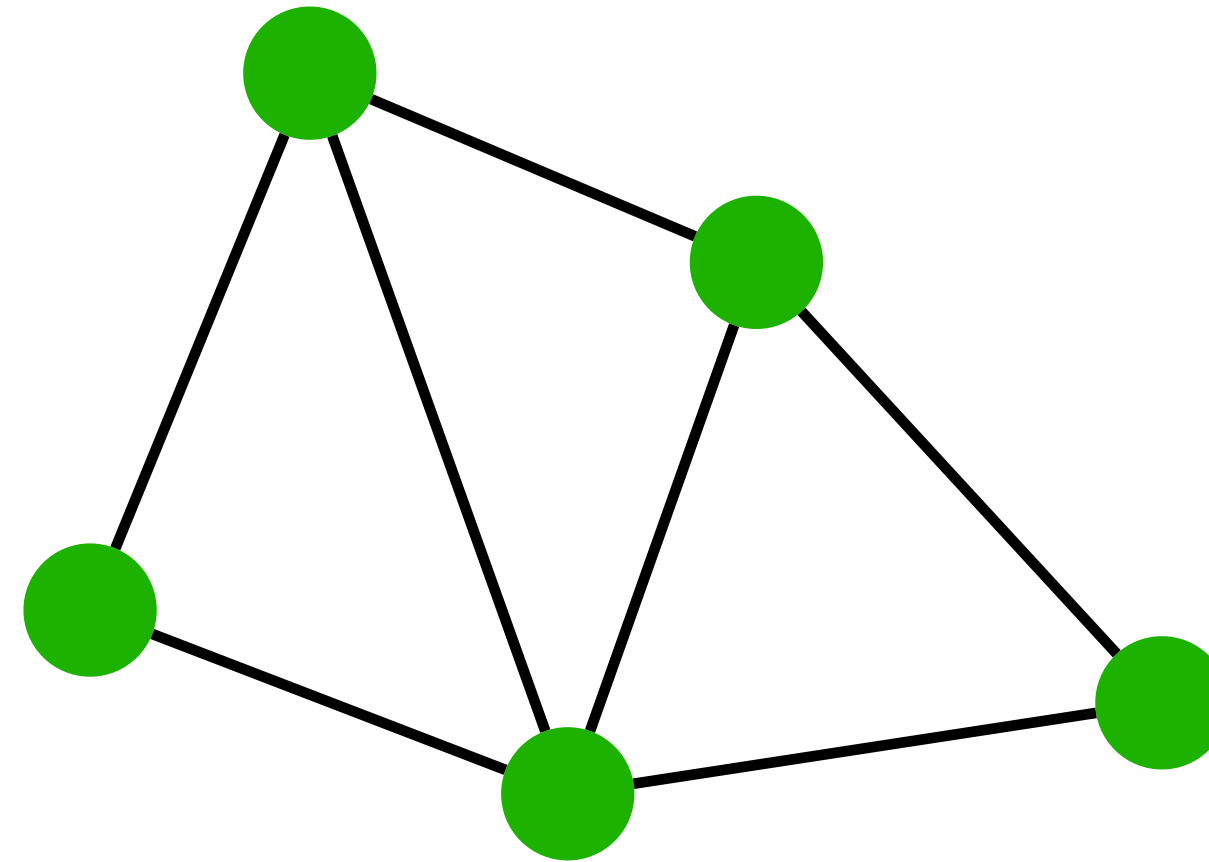
For each replacement in Step 1, it takes at most linear time of scanning through the input. In total, it scan through the input ℓ times, where ℓ is the number of literals in ϕ . Step 2 can be done in one scan through the input. Hence, V runs in polynomial time in the input length.

D-HAM-PATH



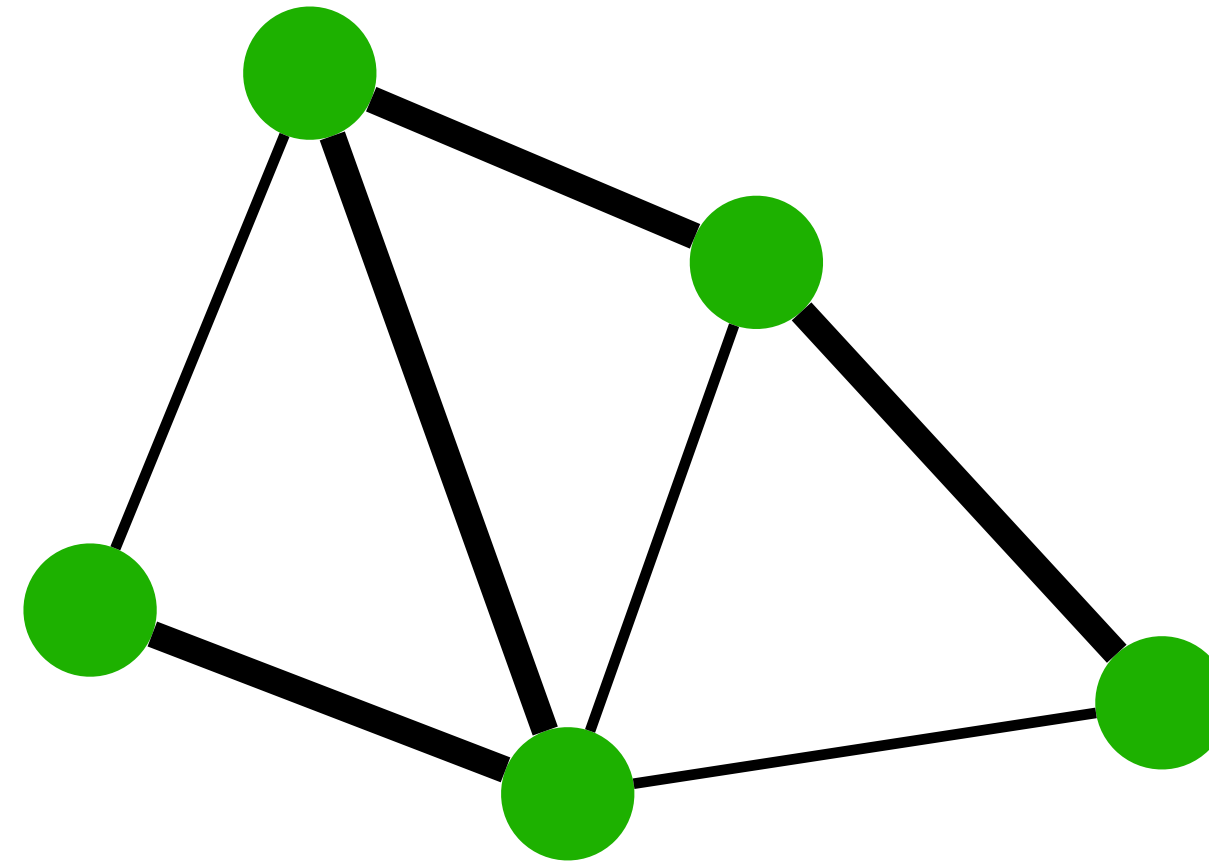
D-HAM-PATH

- A **Hamiltonian path** of a graph $G = (V, E)$ is a simple path that contains each vertex in V .



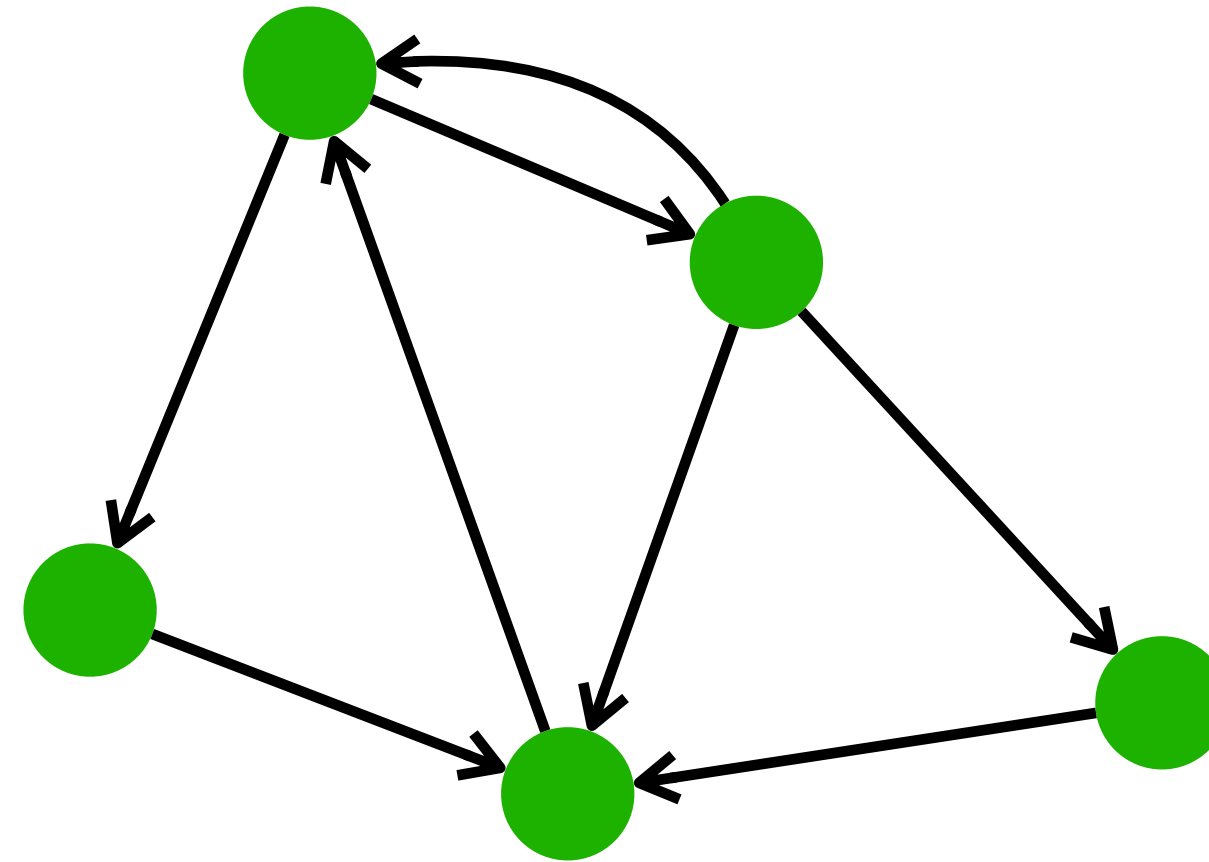
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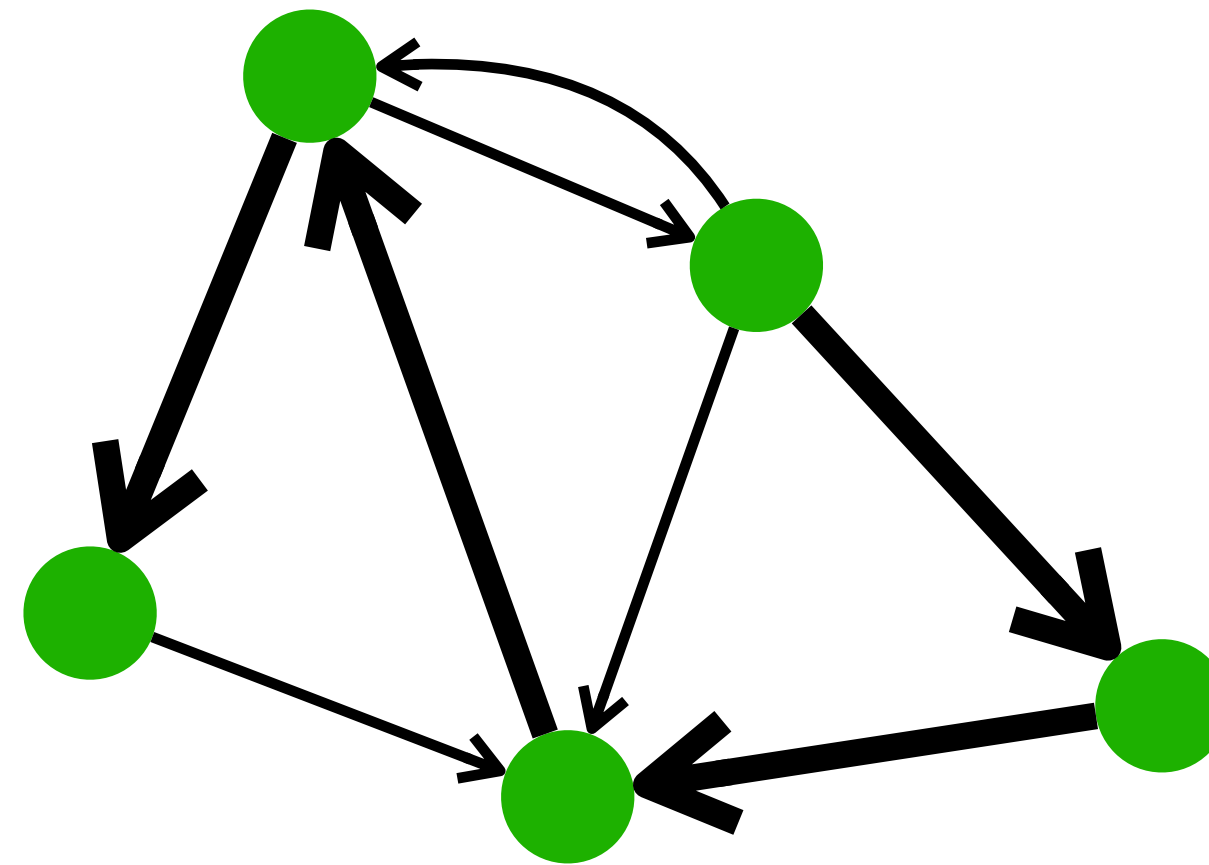
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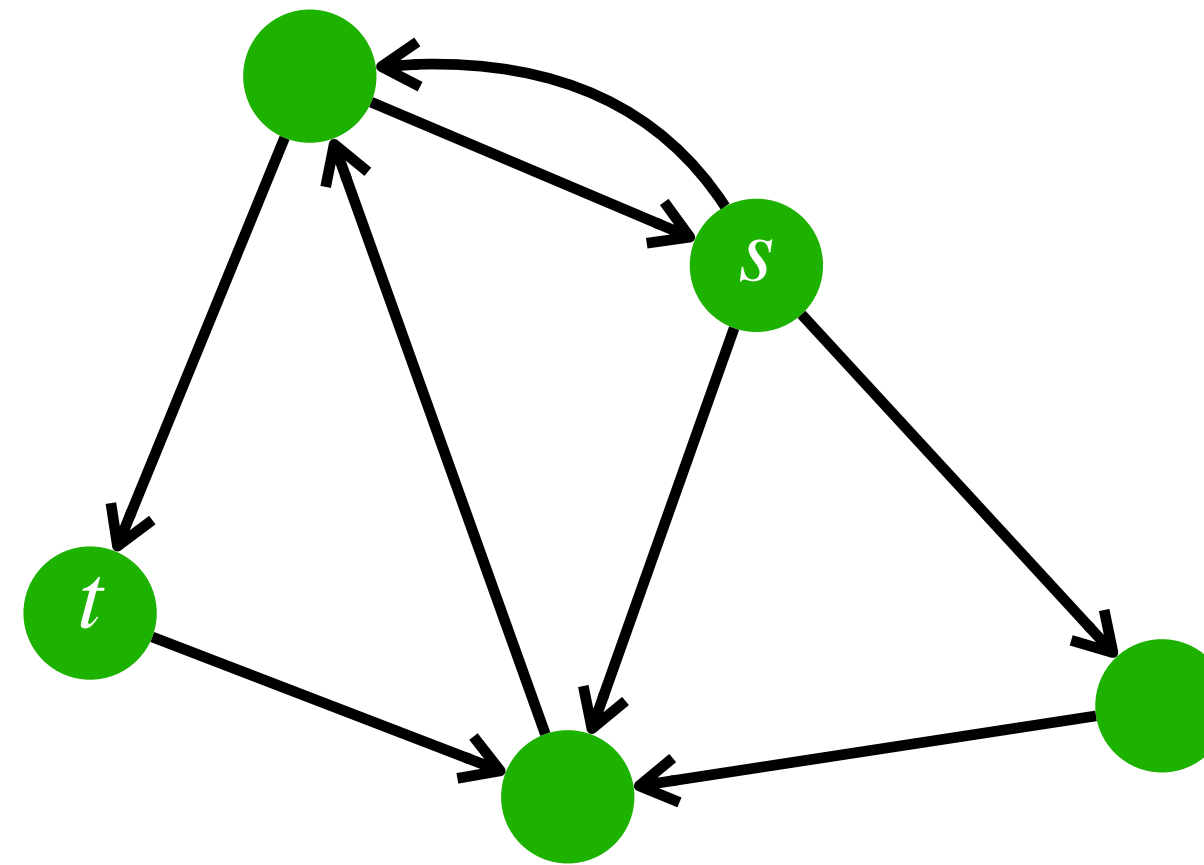
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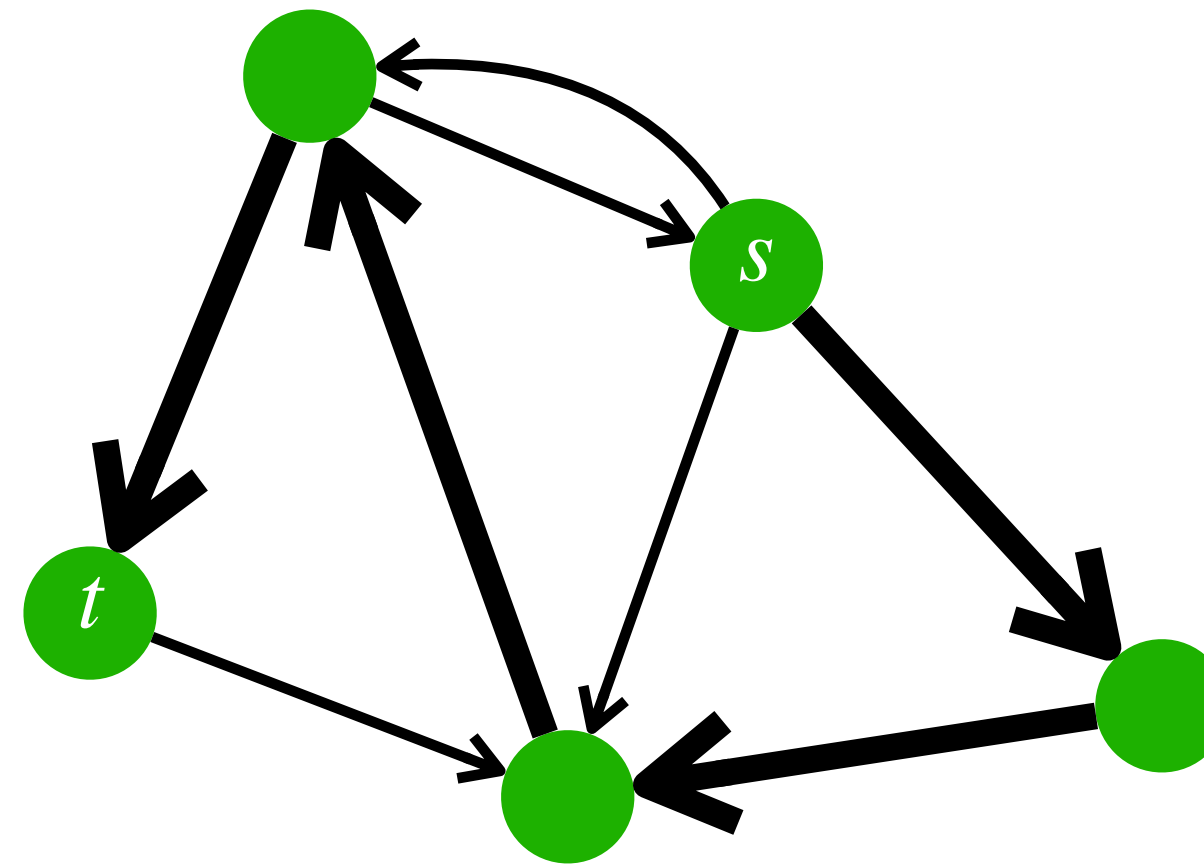
D-HAM-PATH

- A **Hamiltonian path** of a graph $G = (V, E)$ is a simple path that contains each vertex in V .
- **D-HAM-PATH** = $\{ \langle G, s, t \rangle \mid G \text{ is a directed graph with a Hamiltonian path from } s \text{ to } t \}$



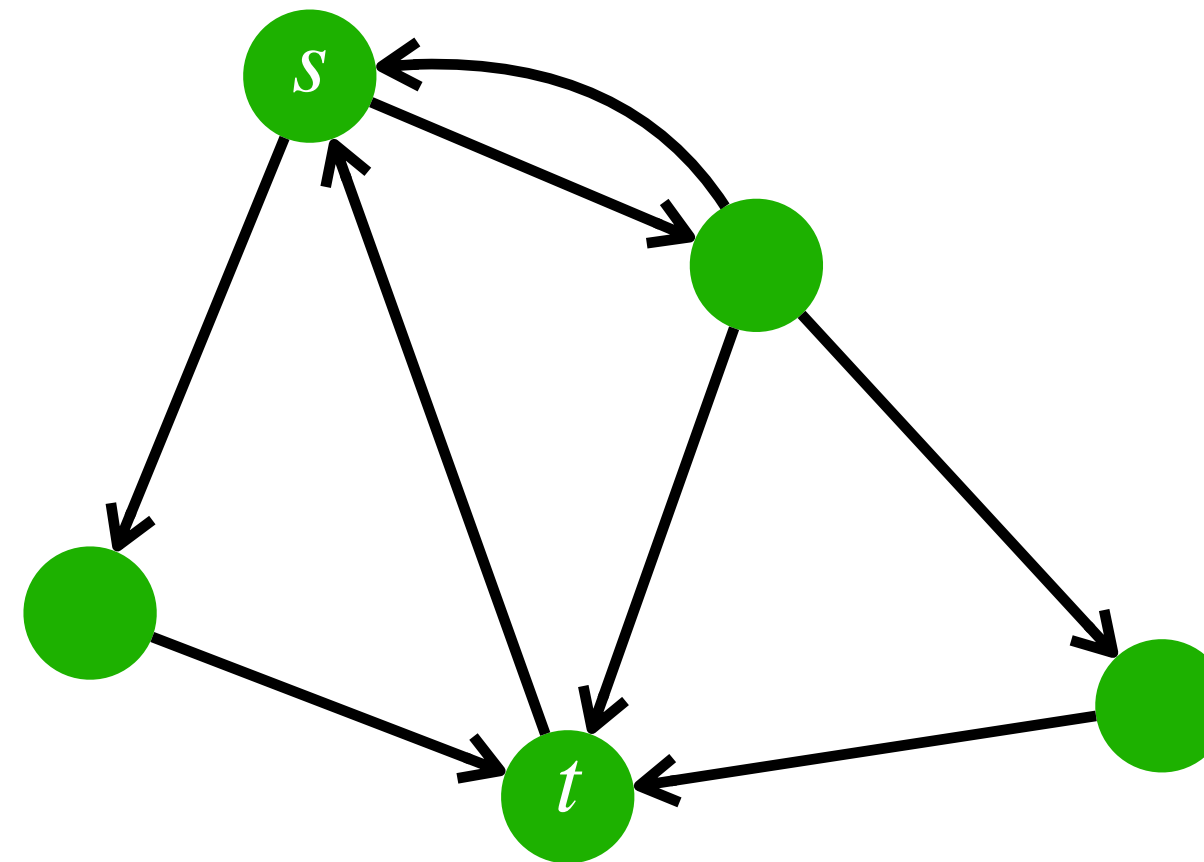
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D-HAM-PATH

- A **Hamiltonian path** of a graph $G = (V, E)$ is a simple path that contains each vertex in V .
- **D-HAM-PATH** = $\{ \langle G, s, t \rangle \mid G \text{ is a directed graph with a Hamiltonian path from } s \text{ to } t \}$



D-HAM-PATH is in NP

- **D-HAM-PATH** = $\{\langle G, s, t \rangle \mid G \text{ is a directed graph with a Hamiltonian path from } s \text{ to } t\}$
- Prove **D-HAM-PATH** is in **NP** $\Leftrightarrow$ Design a polynomial time verifier to decide **D-HAM-PATH** (with help from some c)
<Proof>

Let string c that encodes a permutation of vertices in G that forms a Hamiltonian walk starting from s and end at t as a certificate

$V =$ “On input $\langle \langle G, s, t \rangle, c \rangle$:

1. Check if c is indeed a permutation of vertices in G starting from s and end at t
2. For every consecutive pair of vertices in c , v_i and v_{i+1} , check if there is an edge from v_i to v_{i+1} in G
3. If 1 and 2 both pass, *accept*; otherwise, *reject*.”

For each element in c in Step 1, it takes at most linear time of scanning through the input. In total, it scan through the input n times, where n is the number of vertices in G . Each consecutive pair in Step 2 can be checked in one scan through the input, and there are at most $O(n)$ pairs. Hence, V runs in polynomial time in the input length.

What Happened

- To show that a problem is in **NP**, we can show that it is polynomial-time verifiable

<Proof Idea>

1. Show that for any yes instance w , there is a polynomial-size certificate c .

2. Design a verifier V on input $\langle w, c \rangle$ that *accepts* all $w \in A$ and *rejects* all $w \notin A$

3. Show that V runs in polynomial time (in the length of w)

Why P and NP?

- There are many $f(n)$ time Turing machine variations that have an equivalent $\text{poly}(f(n))$ time single-tape Turing machine
- Every $f(n)$ time non-deterministic Turing machine has an equivalent $2^{O(f(n))}$ time deterministic Turing machine
- There is at most a square or polynomial difference between the time complexity of problems measured on deterministic single-tape and many Turing machine variations
- There is at most an exponential difference between the time complexity of problems on deterministic and nondeterministic Turing machines

Reference

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- *Introduction to Algorithms* by Thomas H. Cormen, Charles E. Leiserson, Ronald L. Rivest, and Clifford Stein
- *Computational Complexity* by Christos h. Papadimitriou

