

B3CC: Concurrency

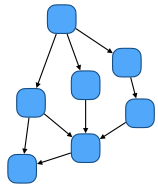
12: Data Parallelism (I)

Ivo Gabe de Wolff

- **Concurrency:** dealing with lots of things at once
- **Parallelism:** doing lots of things at once
 - Processors are no longer getting faster: limitations in power consumption, memory speed, and instruction-level parallelism
 - Adding more processor cores has been the dominant method for improving processor performance for the last decade

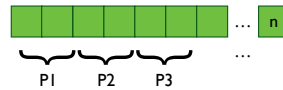
2

Recap



Task parallelism

- Explicit threads
- Synchronise via locks, messages, or STM
- Modest parallelism
- Hard to program



Data parallelism

- Operate simultaneously on bulk data
- Implicit synchronisation
- Massive parallelism
- Easy to program

Goals

- Large applications use a mix of task- and data-parallelism
 - There is a difference in how to make use of 2-4 cores vs. 32+ cores
- In the application of parallelism, we would like to achieve:
 - *Performance:* ease of use, scalability, and predictability
 - *Productivity:* expressivity, correctness, clarity, and maintainability
 - *Portability:* between different machines, compilers, or architectures

3

4

Applications

- Games
 - Probably the primary consumer market for teraflop computing applications
- Image and video editing
- Scientific computing
 - Numeric simulations, modelling, etc.
- Machine learning

5

Patterns

- Patterns, or *algorithmic skeletons*
 - A pattern is a recurring combination of task distribution and data access
 - Patterns provide a vocabulary for [parallel] algorithm design
 - These ideas are not tied to a particular hardware architecture
- This distinguishes two important aspects:
 - Semantics: what we want to achieve
 - Implementation: how to achieve this on a given architecture

6

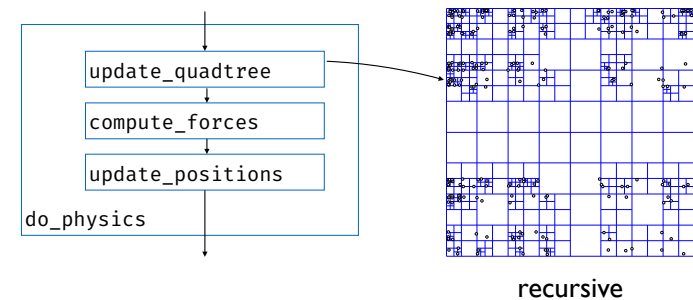
Patterns

- Patterns also exist in serial code
 - We often don't think of serial code in this way, however it helps to name these patterns in order to talk about these ideas in a parallel context
 - Compositional patterns: nesting
 - Control-flow patterns: sequence, selection, repetition, and recursion

7

Patterns: nesting

- Nesting simply refers to the ability to hierarchically compose patterns
 - Including recursive functions

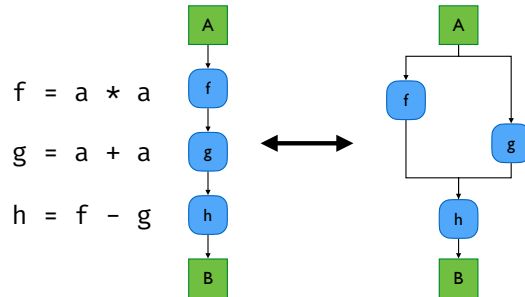


8

Patterns: sequence

- Tasks executed in a specified order

- We generally assume that the program is executed in the text order
- Modern CPUs violate this (out-of-order execution (instructions & memory))
- Programmer or language specifies if/how memory operations may be reordered (memory_order in c++)



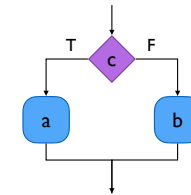
https://en.wikipedia.org/wiki/Out-of-order_execution
https://en.wikipedia.org/wiki/Memory_ordering#Runtime_memory_ordering
https://en.cppreference.com/w/cpp/atomic/memory_order

Patterns: selection

- Conditionals are pervasive in serial code

- On average one branch every five instructions
- Modern CPUs speculatively execute (far) ahead of when c is known
- TensorFlow (google deep learning framework) always evaluates both branches of conditionals

```
if (c) {
  a;
} else {
  b;
}
```



9

https://en.wikipedia.org/wiki/Speculative_execution

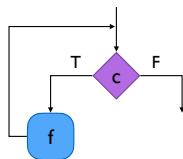
10

Patterns: iteration

- Continually execute a task while some condition is true

- Parallelisation of loops is complicated due to *loop-carried dependencies*
- There is a lot of research in this area (polyhedral models, loop nests)
- Instead, several *parallel* patterns exist for specific loop forms: map, reduce, scan, scatter, gather...

```
while (c) {
  f;
}
```

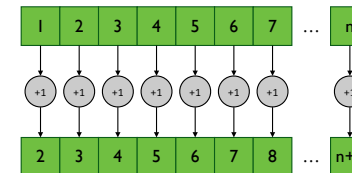


https://en.wikipedia.org/wiki/Polytope_model

Map

- The map operation applies the *same* function to each element of a set

- This is a parallelisation of a loop with a *fixed* number of iterations
- There must not be any dependencies between loop iterations: the function uses only the input element value and/or index



```
for (i = 0; i < len; ++i)
{
  x = xs[i];
  y = f(x);
  ys[i] = y;
}
```

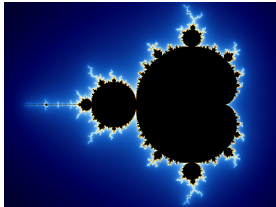
11

<https://hackage.haskell.org/package/accelerate-1.3.0.0/docs/Data-Array-Accelerate.html#g:18>

12

Map

- The map operation applies the *same* function to each element of a set
 - The function only has access to a *single value*
 - The number of iterations is dynamic (e.g. size of the array) but fixed at the start of the map: does not vary based on the loop body
 - Note that the order of operations is not specified



$$z_{n+1} = z_n^2 + c$$

13

Map

- The map operation applies the *same* function to each element of a set
 - On the GPU this corresponds to one thread per element
 - Number of loop iterations is controlled by how many threads the kernel is launched with
 - Host code:

```
map<<<4, 1024>>> ( h_xs, h_ys, 4000 );
```

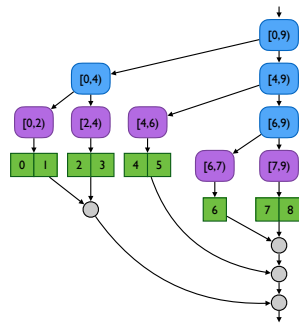
- GPU code:

```
__global__ void map( float* d_xs, float* d_ys, int len )
{
    int i = blockDim.x * blockIdx.x + threadIdx.x;
    if ( i < len ) {
        d_ys[i] = f ( d_xs[i] );
    }
}
```

14

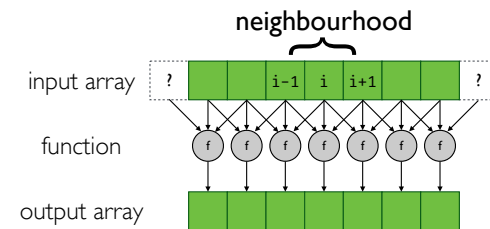
Map

- In the graphics pipeline, vertex and fragment shaders are a parallel map
 - Each shader outputs a single pixel or vertex; no other side effects
 - Shaders are also examples of *streaming algorithms*: data is used exactly once, so no caching is necessary
- On the CPU, can be implemented via
 - Static schedule (like count & list mode of IBAN)
 - fork-join
 - divide-and-conquer (like search mode of IBAN)
 - ...



Stencil

- A map with access to the neighbourhood around each element
 - The set of neighbours is fixed, and relative to the element
 - Ubiquitous in scientific, engineering, and image processing algorithms



15

<https://hackage.haskell.org/package/accelerate-1.3.0.0/docs/Data-Array-Accelerate.html#g:37>

16

Stencil

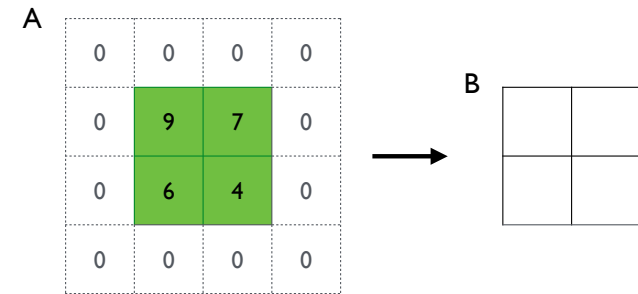
- The stencil pattern
 - The set of neighbouring elements used by the stencil function
 - The shape of the stencil pattern can be anything: sparse, non-symmetric, etc.
 - The pattern of the stencil determines how the stencil operates in an application

```
__global__ void stencil( float* xs, float* ys, int width, int height )
{
    int i = blockDim.x * blockIdx.x + threadIdx.x;
    ys[i] = f (
        xs[i-width]
        , xs[i-1], xs[i], xs[i+1]
        , xs[i+width]
    );
}
```

17

Example

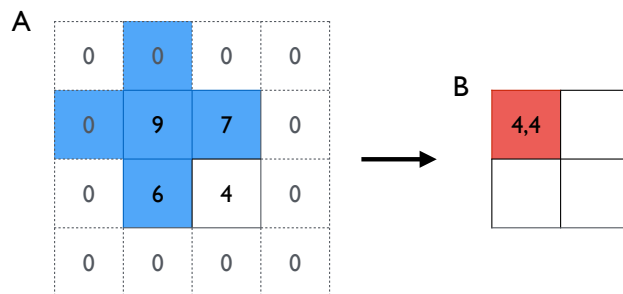
- Apply a stencil operation to the inner square
 - Treat out-of-bounds elements are zero (we'll come back to this later)



18

Example

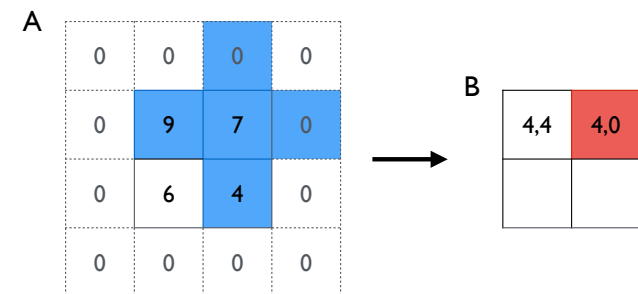
- Apply a stencil operation to the inner square
 - Treat out-of-bounds elements are zero
 - Stencil function: average of the blue squares



19

Example

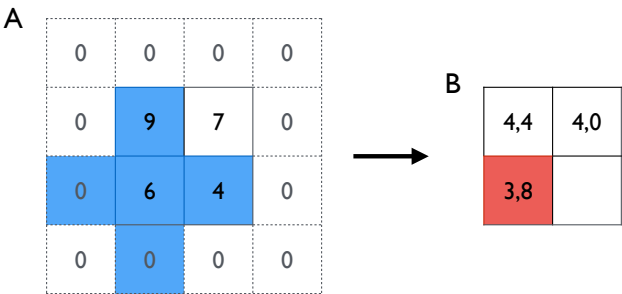
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20

Example

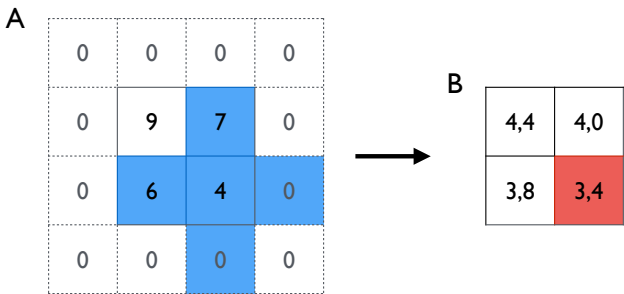
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21

Example

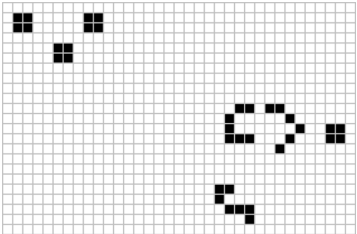
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22

Example: Conway's game of life

- Cellula automaton developed in 1970
 - Evolution of the system is determined from an initial state
 - Cells live or die based on the population of their surrounding neighbours
 - Turing complete!

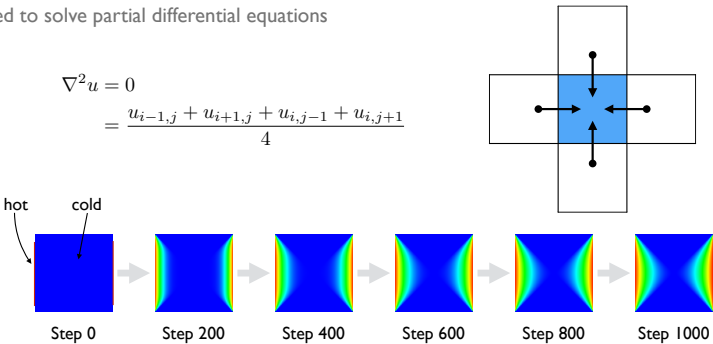


https://en.wikipedia.org/wiki/Conway%27s_Game_of_Life
<https://github.com/tmcDonell/gameoflife-accelerate>

23

Example: heat equation

- Iterative codes are ones that update their data in steps
- Most commonly found in simulations for scientific & engineering applications
 - Often used to solve partial differential equations



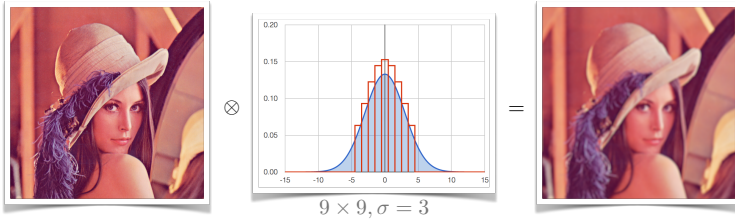
https://en.wikipedia.org/wiki/Stencil_code
<https://github.com/tmcDonell/fisher-accelerate>

24

Example: gaussian blur

- Convolution with a Gaussian function
 - Typically used to reduce image noise
 - Each pixel becomes the weighted sum of the surrounding pixels

$$(I \otimes K)(x, y) = \sum_i \sum_j I(x+i, y+j) K(i, j)$$



https://en.wikipedia.org/wiki/Gaussian_blur
<https://github.com/tmcDonell/accelerate-examples/blob/master/examples/canny/src-acc/Canny.hs#L82>

Example: gaussian blur

- Gaussian function
 - This is a *separable* convolution:
instead of a single $n \times n$ stencil,
it can be implemented as an $l \times n$ stencil after a $n \times l$ stencil
 - This is significant for large n
 - Example: 3×3 stencil

$$\begin{bmatrix} 0.077847 & 0.123317 & 0.077847 \\ 0.123317 & 0.195346 & 0.123317 \\ 0.077847 & 0.123317 & 0.077847 \end{bmatrix} = \begin{bmatrix} 0.27901 \\ 0.44198 \\ 0.27901 \end{bmatrix} \times \begin{bmatrix} 0.27901 & 0.44198 & 0.27901 \end{bmatrix}$$

25

<http://dev.theomader.com/gaussian-kernel-calculator>

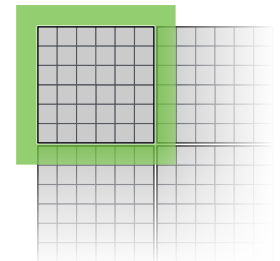
26

Stencil boundary

- What to do when the stencil pattern falls outside the bounds of the array?
 - At the edges of a simulation, we may need to impose boundary conditions
 - choose a fixed value or derivative (e.g. to impose symmetry)
 - many options are possible...
- What about between processors?

Stencil boundary

- What happens at the boundary of the computation?
 - Each larger box is owned by a thread / processor
- *Ghost cells* are one solution to the boundary and update issues of a stencil computation
 - Each thread keeps a copy of the neighbour's data to use in local computations
 - The ghost cells must be updated after each iteration of the stencil
 - The set of ghost cells is called the *halo*
 - A deeper halo can be used to reduce communication for some redundant work

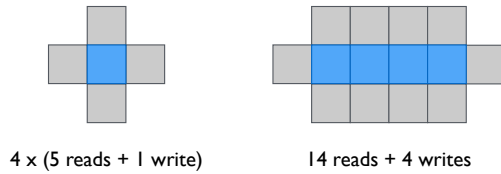


27

28

Stencil optimisations

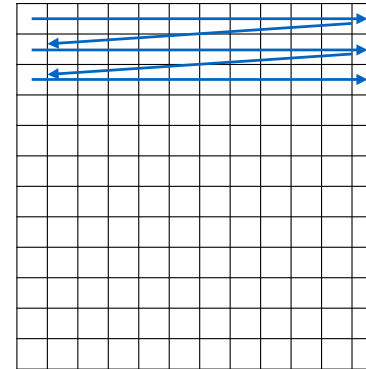
- Use a different kernel for the interior and border regions
 - In the gaussian blur example of a 512x512 pixel image, 98% of the pixels do not require in-bounds checks
- Optimise data locality & reuse through tiling
 - *Strip mining* is an optimisation that groups elements in a way that avoids redundant memory access and aligns accesses with cache lines



Stencil optimisations

Without tiling

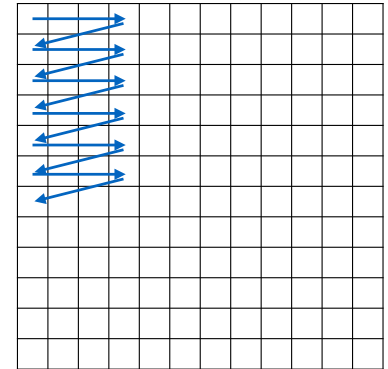
- When handling row 0, row 1 is loaded in cache.
- First values of row 1 may already be out of cache, when handling row 1



29

With tiling

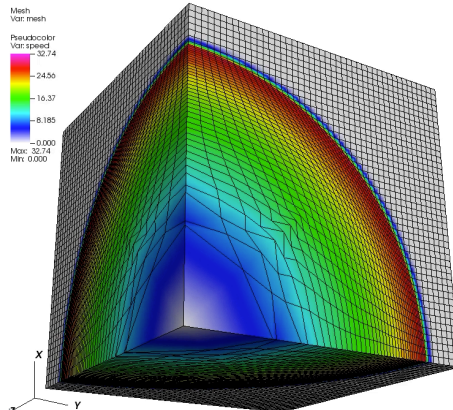
- Previously loaded row is still in cache
- Tile width is usually a power of 2, on GPUs often the warp size (32)



30

Example: LULESH

DB: lulesh_c*.silo database
Cycle: 1360 Time:0.0099864

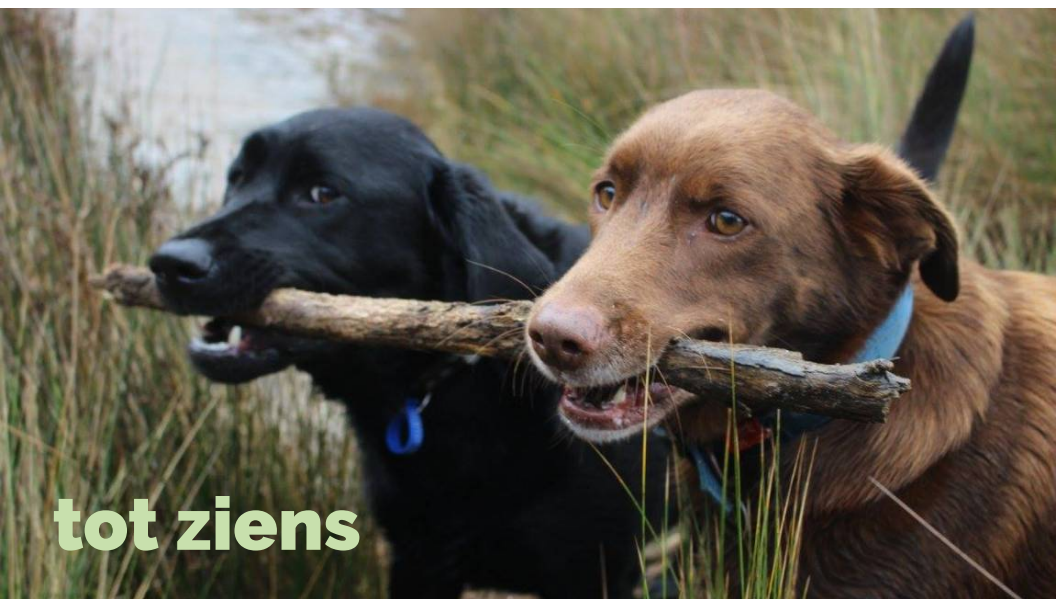


Summary

- Data-parallelism is a good fit for parallel computing
 - Conceptually simple programming model: single logical thread of control
 - Separate the pattern (what you want to do) from the implementation (how to do it: optimisations, target hardware, etc.)

31

32



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